

MEROMORPHIC QUADRATIC DIFFERENTIALS WITH HALF-PLANE STRUCTURES

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ABSTRACT. We prove the existence of “half-plane differentials” with prescribed local data on any Riemann surface. These are meromorphic quadratic differentials with higher-order poles which have an associated singular flat metric isometric to a collection of euclidean half-planes glued by an interval-exchange map on their boundaries. The local data is associated with the poles and consists of the integer order, a non-negative real residue, and a positive real leading order term. This generalizes a result of Strebel for differentials with double-order poles, and associates metric spines with the Riemann surface.

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1. INTRODUCTION

A holomorphic quadratic differential on a Riemann surface defines a conformal metric that is flat with conical singularities, together with pair of *horizontal* and *vertical* measured foliations, and this singular-flat geometry is intimately related to quasiconformal mappings and the geometry of Teichmüller space \mathcal{T}_g in the Teichmüller metric. In this paper we consider certain *infinite area* singular flat surfaces corresponding to (non-integrable) meromorphic quadratic differentials that arise as geometric limits

Key words and phrases. Quadratic differentials, quasiconformal maps, flat surfaces.

MSC Classification: 30F30, 30F60. This work was (partly) supported by the Danish Research Foundation DNR95 (Center for Quantum Geometry of Moduli Spaces - QGM).

along Teichmüller geodesic rays.

A *half-plane surface* is a singular flat surface that is obtained by taking a finite partition of the boundaries of a collection of euclidean half-planes and gluing by an interval-exchange map (see §4 for examples.) We shall only exclude the possibility that the two infinite-length boundary intervals of the same half-plane are identified. Such a surface can be thought of as a Riemann surface with punctures p_1, p_2, \dots, p_n corresponding to the ends of the surface, equipped with a quadratic differential (restricting to dz^2 on the half-planes) that is holomorphic away from the punctures. This *half-plane differential* has a pole of order $n_j \geq 4$ at p_j (for $1 \leq j \leq n$) and one can associate with it the data of a non-negative real *residue* a_j (this is always zero when n_j is odd) and, in a given choice of local coordinates, a positive real *leading order term* c_j , which is the top coefficient in a local series expansion of the differential. In the singular flat metric, a neighborhood of p_j is isometric to a “planar end” comprising $n_j - 2$ half-planes glued cyclically along their boundaries (see Definition 2.4). The residue a_j then corresponds to the metric holonomy around the puncture and c_j gives the “scale” of this planar end relative to the others. We provide precise definitions in §3.

In this article we show that one can get *any* Riemann surface with n punctures by the above construction, and furthermore can arbitrarily prescribe the data of order, residue and leading order terms:

$$\mathcal{D} = \{(n_j, a_j, c_j) | n_j \in \mathbb{N}, n_j \geq 4, c_j \in \mathbb{R}^+, a_j \in \mathbb{R}_{\geq 0}, a_j = 0 \text{ for } n_j \text{ odd.}\}$$

associated with the set of punctures:

Theorem 1.1. *Let Σ be a Riemann surface with a set P of n marked points and with a choice of local coordinates around each. Then for any data \mathcal{D} as above there is a corresponding half-plane surface $\Sigma_{\mathcal{D}}$ and a conformal homeomorphism*

$$g : \Sigma \setminus P \rightarrow \Sigma_{\mathcal{D}}$$

that is homotopic to the identity map.

(The only exception is for the Riemann sphere with one marked point with a pole of order 4, in which case the residue must equal zero.)

Note that it is not hard to show the existence of *some* meromorphic quadratic differential which has local data given by \mathcal{D} at the poles using the Riemann-Roch theorem, but half-plane differentials are a special subclass that satisfy the *global* requirement of having a “half-plane structure” as described.

This result can be thought of as a generalization of the following theorem of Strebel ([Str84]):

Theorem (Strebel). *Let Σ be a Riemann surface of genus g , and $P = \{p_1, p_2, \dots, p_n\}$ be marked points on Σ such that $2g - 2 + n > 0$, and (a_1, a_2, \dots, a_n) a tuple of positive reals. Then there exists a meromorphic quadratic differential q on Σ with poles at \mathcal{P} of order 2 and residues a_1, \dots, a_n , such that all horizontal leaves (except the critical trajectories) are closed and foliate punctured disks around \mathcal{P} .*

The corresponding singular flat metric for such a “Strebel differential” with poles of order two comprises a collection of half-infinite cylinders glued by an interval-exchange on their boundaries, and has a metric spine (sometimes called the “ribbon graph” or “fat graph”). Strebel also showed that the quadratic differential q above - and hence

this metric spine - is unique, which yields a combinatorial description of Teichmüller space like that in [Pen87] and has had useful applications (see, for example, [HZ86], [Kon92]). However, a corresponding uniqueness statement for Theorem 1.1 is not known, and conjecturally holds for poles of order 4 (for a discussion, see §13.2).

The proof of Theorem 1.1 uses the well-known result of Jenkins and Strebel that associates a holomorphic quadratic differential to a collection of curves on a *compact* Riemann surface. The idea is to consider a compact exhaustion of $\Sigma \setminus P$ and produce a corresponding sequence of half-plane surfaces that shall have both $\Sigma \setminus P$ and $\Sigma_{\mathcal{D}}$ as its conformal limit. The main technical work is to obtain enough geometric control for this sequence, and extract these limits by building appropriate sequences of quasiconformal maps. We give a more detailed outline in §5, and carry out the proof in §6-12. In §13 we conclude with some applications and further questions. In particular, the connection of half-plane surfaces with the asymptotic behavior of grafting and Teichmüller rays appears in a subsequent paper ([Gup]).

Acknowledgements. This paper arose from work of the author as a graduate student at Yale, and he wishes to thank his thesis advisor Yair Minsky for his generous help. The author also wishes to thank Michael Wolf for numerous helpful discussions, Kingshook Biswas and Enrico Le Donne for useful conversations, and the support of the Danish National Research Foundation center of Excellence, Center for Quantum Geometry of Moduli Spaces (QGM) where this work was completed.

2. BACKGROUND

In this section we review some background on meromorphic quadratic differentials and the geometry they induce on a Riemann surface.

Most of this is standard (we refer to [Str84]), but we point the reader to our notion of a “planar end” (Definition 2.4), which provides a metric model for an end of a half-plane surface, or more generally for the quadratic differential metric around higher-order poles.

2.1. Quadratic differential space. A closed genus- g Riemann surface Σ_g admits no non-constant holomorphic functions, but carries a finite-dimensional vector space of holomorphic one-forms, or more general holomorphic differentials, which are holomorphic sections of powers of the canonical line-bundle K_{Σ} .

A *quadratic differential* q on Σ_g is a section of $K_{\Sigma} \otimes K_{\Sigma}$, a differential of type $(2, 0)$ locally of the form $q(z)dz^2$. It is said to be *holomorphic* (or *meromorphic*) when $q(z)$ is holomorphic (or meromorphic).

A *zero* or a *pole* of a holomorphic quadratic differential is a point p where in a local chart sending p to 0 we have $\phi(z) = z^n\psi(z)$ or $\phi(z) = \frac{1}{z^n}\psi(z)$ respectively, where $\psi(z) \neq 0$ and the integer $n \geq 1$ is the *order* of the zero or pole. The following is a well-known fact:

Lemma 2.1. *If there are M zeroes of orders n_1, n_2, \dots, n_M , and N poles of orders k_1, k_2, \dots, k_N , then $\sum_{i=1}^M n_i - \sum_{i=1}^N k_i = 4g - 4$.*

Let Q_{g,k_1,k_2,\dots,k_N} be the space of meromorphic quadratic differentials on Σ_g with poles of order less than or equal to k_1, k_2, \dots, k_N at a collection of N marked points, and $\hat{Q}_{g,k_1,k_2,\dots,k_N}$ be the subset of such differentials with poles of orders *exactly* k_1, k_2, \dots, k_N . The former is a finite dimensional vector space, whose dimension can be computed using the Riemann-Roch theorem.

In fact the vector space $Q(X)$ of holomorphic quadratic differentials on a Riemann surface X has complex dimension exactly $3g - 3$ (see for example [FK92]).

2.2. Quadratic differential metrics. A holomorphic quadratic differential $q \in Q(X)$ defines a conformal metric (also called the q -metric) given in local coordinates by $|q(z)||dz|^2$ which has Gaussian curvature zero wherever $q(z) \neq 0$.

At the points where $q(z) = 0$ (finitely many by Lemma 2.1) there is a conical singularity of angle $(n+2)\pi$ where n is the order of the zero, and locally the singular flat metric looks like a collection of n rectangles glued around the singularity (see §7 of [Str84]).

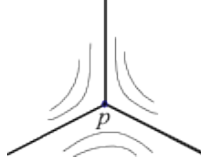


FIGURE 1. A simple zero p is a 3π cone-point.

One way to see this is to change to coordinates where $q = d\zeta^2$ by the conformal map

$$(1) \quad z \mapsto \int_p^z \sqrt{q(z)} dz$$

which gives a branched covering of the ζ -plane when p is a zero of q .

Lengths, area. The *horizontal length* in the q -metric of an arc γ is defined to be

$$|\gamma|_h = \operatorname{Re} \int_{\gamma} \sqrt{q(z)} dz$$

and the *vertical length* is the corresponding imaginary part. The total length in the q -metric is $(|\gamma|_h^2 + |\gamma|_v^2)^{1/2}$.

The L^1 -norm of a quadratic differential gives the *area* in the q -metric:

$$(2) \quad \operatorname{Area}_q(X) = \int_X |\phi(z)| dz d\bar{z}$$

2.3. Measured foliations. A holomorphic quadratic differential $q \in Q(X)$ determines a *horizontal foliation* on X which we denote by $\mathcal{F}_h(q)$, obtained by integrating the line field of vectors $\pm v$ where the quadratic differential is real and positive, that is $q(v, v) \geq 0$. Similarly, there is a *vertical foliation* $\mathcal{F}_v(q)$ consisting of integral curves of directions where q is real and negative.

These foliations can be thought of as the pullback by the map (1) of the horizontal and vertical lines in the ζ -plane. These foliations are also *measured*: the measure of an arc transverse to \mathcal{F}_h is given by its *vertical* length, and the transverse measure for \mathcal{F}_v is given by horizontal lengths. Such a measure is invariant by isotopy of the arc if it remains transverse with endpoints on leaves.

Let \mathcal{MF} be the space of singular foliations on a surface equipped with a transverse measure, upto isotopy and Whitehead equivalence.

Theorem (Hubbard-Masur [HM79]). *Fix a Riemann surface X . Then any $\mathcal{F} \in \mathcal{MF}$ is the horizontal foliation of a unique holomorphic quadratic differential on X .*

Theorem 1.1 of this paper can be thought of as a step towards a generalization to a *non-compact* version of the above result. In this paper we shall use a special case independently proved in [Jen57] and [Str66] (See [Wol95] for a proof using harmonic maps to metric graphs.)

Theorem 2.2 (Jenkins-Strebel). *Let $\gamma_1, \gamma_2, \dots, \gamma_n$ be disjoint homotopy classes of curves on a Riemann surface Σ . Then there exists a holomorphic quadratic differential q whose horizontal foliation $\mathcal{F}_h(q)$ consists of closed leaves foliating n cylinders with core curves in those homotopy classes. Moreover, one can prescribe the heights, or equivalently the circumferences, of the n metric cylinders to be any n -tuple (c_1, c_2, \dots, c_n) of positive reals.*

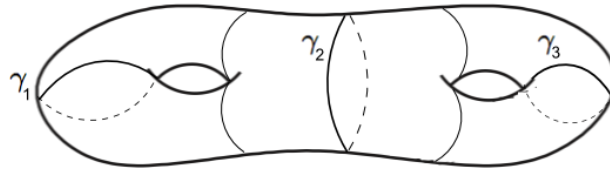


FIGURE 2. In Theorem 2.2 the surface in the q -metric is composed of metric cylinders with core curves the given homotopy classes of curves.

Critical segments. A *critical segment* is a horizontal arc between two critical points (zeroes or poles) of the quadratic differential, and a critical arc between two zeroes is called a *saddle-connection*. Their number is always finite since by the theorem of Gauss-Bonnet (see also Theorem 14.2.1 in [Str84]) there cannot be more than one saddle-connection between a pair of zeroes.

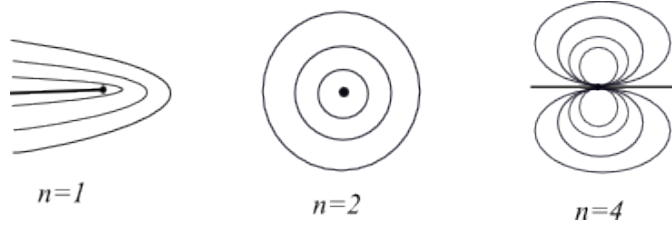


FIGURE 3. Local picture with horizontal leaves at a pole of order n .

2.4. Metric structure at poles. Most of the preceding discussion also holds when the quadratic differential q is *meromorphic*, with finitely many poles: namely, one has an associated singular flat q -metric, together with horizontal and vertical foliations.

A meromorphic quadratic differential with a finite q -area can have poles of order at most 1 (see [Str84]). At such a pole, there is a conical singularity of angle π , and the singular flat metric has a “fold” (see figure, also §7 of [Str84]).

A pole of higher order $n > 1$ is at an infinite distance in the q -metric. Any such pole p has an associated *analytic residue* which is defined to be

$$(3) \quad \text{Res}_q(p) = \int_{\gamma} \sqrt{q}$$

where γ is any simple closed curve homotopic into p (this is independent of choice of γ since q is holomorphic away from p).

For the rest of this article, we shall consider only higher order poles which have a *real* analytic residue (in [Str84] this property is referred to as q having a *vanishing logarithmic term*). This rules out any “spiralling” behaviour of the horizontal foliation at the poles. We also have an explicit description of the singular flat metric around the pole p (Theorems 2.3 and 2.6) which can be culled from [Str84] (see §7 of the book for a discussion).

Theorem 2.3. *Let p on Σ be a pole of order 2 with a positive real analytic residue C . Then there is a neighborhood U of p such that in the q -metric $U \setminus p$ is isometric to a half-infinite euclidean cylinder with circumference $2\pi C$.*

Proof. A neighbourhood U of p has a conformal chart to \mathbb{D} taking p to 0 the quadratic differential takes the form

$$-\frac{C^2}{z^2} dz^2$$

The change of coordinates (1) is given by a logarithm map $\zeta = iC \ln z$ that pulls back the euclidean ζ -plane to a half-infinite cylinder. We leave these verifications to the reader. \square

2.5. Planar ends. We now introduce the notion of a *planar end* and its *metric residue*.

In the following definition we identify the boundary of a euclidean half-plane with \mathbb{R} .

Definition 2.4 (Planar-end). Let $\{H_i\}$ for $1 \leq i \leq n$ be a cyclically ordered collection of half-planes with rectangular “notches” obtained by deleting, from each, a rectangle

of horizontal and vertical sides adjoining the boundary, with the boundary segment having end-points x_i and y_i , where $x_i < y_i$. A *planar end* is obtained by gluing the interval $[y_i, \infty)$ on ∂H_i with $(-\infty, x_{i+1}]$ on H_{i+1} by an orientation-reversing isometry. Such a surface is homeomorphic to a punctured disk.

For an example, see Figure 4.

Definition 2.5 (Metric residue). Let the half-plane differential q at a pole p_j have a planar end as above (where the number of half-planes n equals $n_j - 2$). Then the residue a_j of q at p_j is defined to be the alternating sum $\sum_{i=1}^n (-1)^{i+1} (y_i - x_i)$. Note that there is an ambiguity of sign because of the cyclic ordering in the alternating sum, and we resolve this by choosing a starting index that ensures a positive sum.

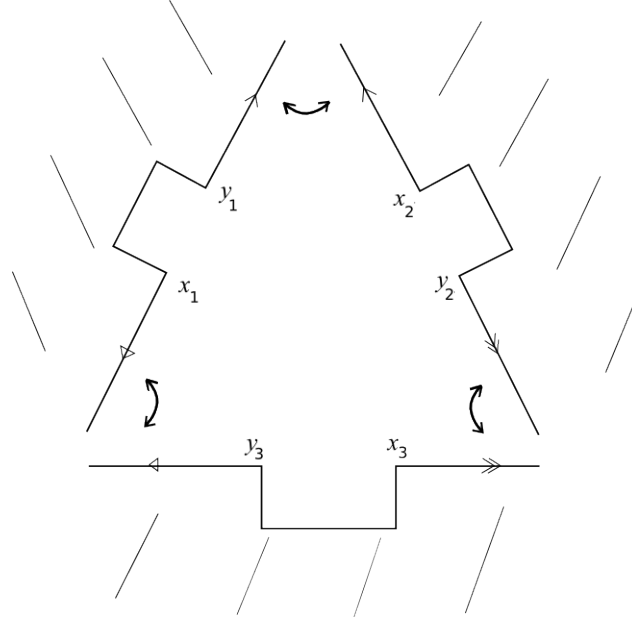


FIGURE 4. A planar-end obtained from 3 “notched” half-planes (see Definition 2.4).

Theorem 2.6. Let p on Σ be a pole of order $n > 2$ with a real analytic residue C . Then there is a neighborhood U of p such that in the q -metric $U \setminus p$ is isometric to a planar-end surface with $(n - 2)$ half-planes and metric residue equal to C .

Proof. We provide only the proof for the statement regarding the metric residue, as the proof of the planar-end structure appears in [Str84] (see §10.4 of the book).

Let P be a polygon made from the boundaries of the rectangular “notches” of each half-plane of the planar end (see Definition 2.4) oriented counter-clockwise. Then P is a polygon enclosing p contained in U , and consists of alternating horizontal and vertical segments, with the horizontal edges having lengths $b_i - a_i$ for $1 \leq i \leq n$.

Analytic notions	Metric notions
L^1 -norm	Area
At least one non-simple pole	Infinite area
Zero of order n	Cone point of angle $(n + 2)\pi$
Simple (order 1) pole	Cone point of angle π
Order 2 pole	Half-infinite cylinder
Order $n > 2$ pole	Planar end
Analytic residue	Metric residue

TABLE 1. A glossary of the correspondence between analytic and metric properties of a meromorphic quadratic differential.

We first note that

$$(4) \quad \pm \int_P \sqrt{q} = \sum_{i=1}^n (-1)^{i+1} (b_i - a_i)$$

This follows from the fact that by a change of coordinates (see (1)) the integral over three successive edges (horizontal-vertical-horizontal) equals integrating the form $d\zeta$ on the complex (ζ -)plane over a horizontal edge that goes from the right to left on the upper half-plane followed by one over a vertical edge followed by one over a horizontal edge that goes from left to right in the lower half-plane. Hence the integral over the horizontal sides picks up the horizontal lengths but the sign switches over the two successive horizontal edges. Meanwhile the integral over the vertical sides contribute to the imaginary part, but they cancel out since two successive vertical segments on the upper (ζ)-half-plane are of equal length but of opposite orientation.

The left hand side of (4) is equal to the real analytic residue C (upto sign) by definition (3), and the right hand side is equal to the metric residue of the planar end as defined in Definition 2.4, and the proof is complete. \square

3. PRELIMINARIES

In this section we introduce some of the terminology and observations used in this paper.

3.1. Half-plane differentials. The following definition was already mentioned in §1:

Definition 3.1 (Half-plane surface). Let $\{H_i\}_{1 \leq i \leq N}$ be a collection of $N \geq 2$ euclidean half planes and let \mathcal{I} be a finite partition into sub-intervals of the boundaries of these half-planes. A *half-plane surface* Σ is a complete singular flat surface obtained by gluings by (oriented) isometries amongst intervals from \mathcal{I} .

Such a half-plane surface has a number of planar ends as in Definition 2.4, and is equipped with a meromorphic quadratic differential q (the *half-plane differential*) that restricts to dz^2 in the usual coordinates on each half-plane.

3.2. Residue. The residue a_j associated with a puncture (or end) of a half-plane surface has both an metric definition (Definition 2.5) and the following analytic definition (see (3)):

Definition 3.2 (Analytic residue). The residue a_j of the half-plane differential q at a pole p_j is defined to be the absolute value of the integral

$$a_j = \int_{\gamma_j} \sqrt{q}$$

where γ_j is a simple closed curve enclosing p_j and contained in a chart where one can define $\pm\sqrt{q}$. This gives a positive real number (see Theorem 2.6) and in particular, equals the metric residue of the corresponding planar end.

3.3. Planar ends and truncations. A planar end (Definition 2.4) can be thought of as a neighborhood of ∞ on \mathbb{C} in the metric induced by the restriction of a “standard” holomorphic quadratic differential ϕ :

$$(5) \quad \phi = \phi(z)dz^2 = \left(z^{n-2} + ia z^{n/2-2} \right) dz^2$$

where a is the (positive, real) residue at the pole at 0 and $n \geq 4$ is even. See *Example 2* in §4.1 for details. When n is odd, the residue is necessarily zero, and the metric is induced by the differential $\phi = \phi(z)dz^2 = z^{n-2}dz^2$.

By inversion ($w = 1/z$), this can be thought of as the metric induced by the restriction of a meromorphic quadratic differential (which we also denote by ϕ) to a neighborhood of $0 \in \mathbb{C}$:

$$(6) \quad \left(\frac{1}{w^{n+2}} + \frac{ia}{w^{n/2+2}} \right) dw^2$$

when n is even and $\left(\frac{1}{w^{n+2}} \right) dw^2$ when n is odd.

Definition 3.3 (\mathcal{P}_H). For a planar end with residue a , the *truncation at height H* denoted by \mathcal{P}_H , is when the missing “notches” are rectangles of horizontal width H and vertical heights $H/2$, except one rectangle of horizontal width $H + a$. The boundary of the planar \mathcal{P}_H is then a polygon of alternating horizontal and vertical sides, each of length H except one horizontal side of length $H + a$. (This is then compatible with the metric residue being a - see Definition 2.5.)

Remark. Any planar end has a truncation at height H , for sufficiently large H .

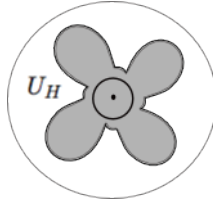


FIGURE 5. A truncation of a planar end can be conformally identified with a neighborhood U_H of $0 \in \mathbb{C}$ (shown shaded). Lemma 3.4 gives estimates on its dimensions.

By the previous discussion we can identify $\mathcal{P}_H \cup \infty$ with a neighborhood U_H of $0 \in \mathbb{C}$, via a map taking ∞ to 0, which is an isometry with respect to the singular flat metric on the planar end and the ϕ -metric on U_H , and is hence conformal. The following estimates about this simply connected domain in \mathbb{C} will be useful later:

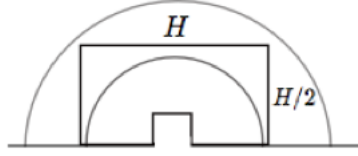
Lemma 3.4. *There exist universal constants $D_1, D_2 > 0$ such that for all sufficiently large H , we have:*

$$(7) \quad \frac{D_1}{H^{2/n}} \leq \text{dist}(0, \partial U_H) \leq \frac{D_2}{H^{2/n}}$$

where n is the number of half-planes for the planar end.

(In this paper, $\text{dist}(q, K) = \inf_{p \in K} |p - q|$ where $q \in \mathbb{C}$ and $K \subset \mathbb{C}$ is a compact set.)

Proof. Observe that given a planar end, one can circumscribe a circle of circumference $C_2 H$ and inscribe one of circumference $C_1 H$ around $\partial \mathcal{P}_H$, where $0 < C_1 < 1 < C_2$ are constants that depend only on n (for sufficiently large H , the effect of the fixed a is negligible).



Now the circumference of the boundary circle ∂B_r in the metric induced by q (see (6)) is:

$$C(r) = \int_{\partial B_r} |\sqrt{q}| = \int_{|w|=r} \left| \frac{1}{w^{n/2+1}} + \frac{ia}{2w} \right| dw \approx \int_{|w|=r} \left| \frac{1}{w^{n/2+1}} \right| dw = O\left(\frac{1}{r^{n/2}}\right)$$

for sufficiently small r .

The previous observation together with this calculation then implies that U_H is contained within two boundary circles which yield (7). (Here D_1, D_2 depend on C_1, C_2 .) \square

Corollary 3.5. *The conformal map $\phi_H : U_H \rightarrow \mathbb{D}$ that takes 0 to 0, satisfies*

$$(8) \quad \frac{1}{4D_2} \leq \frac{|\phi'_H(0)|}{H^{2/n}} \leq \frac{1}{D_1}$$

for all $H > 0$.

Proof. Note that such a conformal map is determined uniquely upto rotation (fixing 0), but this does not change the magnitude of the derivative at 0.

For any conformal map $f : \mathbb{D} \rightarrow \mathbb{C}$ the following holds for any $z \in \mathbb{D}$ (see Corollary 1.4 of [Pom]):

$$\frac{1}{4} (1 - |z|^2) |f'(z)| \leq \text{dist}(f(z), \partial f(\mathbb{D})) \leq (1 - |z|^2) |f'(z)|$$

We apply this to the conformal map $f = \phi_H^{-1} : \mathbb{D} \rightarrow U_H \subset \mathbb{C}$ and $z = 0$. We get by rearranging and using that $f(0) = 0$ that

$$(9) \quad \text{dist}(0, \partial f(\mathbb{D})) \leq |f'(0)| \leq 4 \text{dist}(0, \partial f(\mathbb{D}))$$

By the previous lemma, and the fact that $\phi'_H(0) = 1/f'(0)$, (8) now follows. \square

We also note the following monotonicity:

Lemma 3.6. *Let $\phi_H : U_H \rightarrow \mathbb{D}$ be the conformal map preserving 0. Then the derivative $|\phi'_H(0)|$ is strictly increasing with H .*

Proof. For $\hat{H} > H$ we have the strict inclusions $\mathcal{P}_H \subset \mathcal{P}_{\hat{H}}$ and $U_{\hat{H}} \subset U_H$. Hence $\phi_H \circ \phi_{\hat{H}}^{-1} : \mathbb{D} \rightarrow \mathbb{D}$ is well-defined, and the lemma follows from an application of the Schwarz lemma. \square

3.4. Leading order term.

Definition 3.7. In a choice of local coordinates z around the pole p , any meromorphic quadratic differential q has a local expression:

$$q = \left(\frac{a_n}{z^n} + \frac{a_{n-1}}{z^{n-1}} + \cdots \frac{a_1}{z} + a_0 + \cdots \right) dz^2$$

and we define the *leading order term* at the pole to be the positive real number $c_j = |a_n|$.

Remarks. 1. A pole at p of a half-plane differential q has a neighborhood U that is isometric to a planar end as in Definition 2.4. The leading order term of a half-plane differential at a pole determines, roughly speaking, the relative scale of the conformal disk U is on the Riemann surface.

2. We shall sometimes refer to the leading order term of q at p *with respect to U* , where U is simply-connected domain containing p . This means that the coordinate chart that we consider is the conformal (Riemann) map $\phi : U \rightarrow \mathbb{D}$ that takes p to 0. Note that by the above definition, the leading order term is independent of the choice of such a ϕ (rotation does not change the magnitude).

Lemma 3.8 (Pullbacks and leading order terms). *Let $f : \mathbb{D} \rightarrow \mathbb{C}$ be a univalent conformal map such that $f(0) = 0$ and let q be a meromorphic quadratic differential on \mathbb{C} having the local expression*

$$q(z)dz^2 = \left(\frac{a_n}{z^n} + \frac{a_{n-1}}{z^{n-1}} + \cdots \frac{a_1}{z} + a_0 + \cdots \right) dz^2$$

*in the usual z -coordinates. Then the pullback quadratic differential f^*q on \mathbb{D} has leading order term equal to $|f'(0)|^{2-n} a_n$ at the pole at 0.*

Proof. By the usual transformation law for change of coordinates, the local expression for the pullback differential is $q \circ f(z) f'(z)^2$. The lemma follows by a calculation involving a series expansion, using that

$$f(z) = f'(0)z + b_2 z^2 + O(z^3).$$

\square

4. EXAMPLES

4.1. Explicit hpd's in $\hat{\mathbb{C}}$. A meromorphic quadratic differential on $\hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$ can be expressed as $q(z)dz^2$ in the affine chart \mathbb{C} , where $q(z)$ is a meromorphic function. The following are examples of such functions which yield a half-plane differential (hpd).

Example 0. The quadratic differential dz^2 has a pole of order 4 at ∞ , and it induces the usual euclidean metric on the plane.

Example 1. The quadratic differential $z^n dz^2$ for $n \geq 1$ has a pole of order $n + 4$ at infinity, with analytic residue (and metric residue) equal to zero. The singular flat metric has $n + 2$ half-planes glued around the origin.

Example 2. The quadratic differential ϕ (see (5))

$$\left(z^{n-2} + ia z^{n/2-2}\right) dz^2$$

on \mathbb{C} for an even integer $n \geq 4$ and some real number $a > 0$ has $n/2 + 1$ zeroes, a pole of order $n + 2$ at infinity, and a connected critical graph with a metric residue πa (see figure, and [HM79] and [AW06] for details).

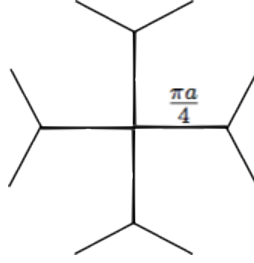


FIGURE 6. Partial picture of the critical graph when $n = 8$ in *Example 2*. The finite-length saddle connections have length $\pi a/4$.

In local w -coordinates at infinity obtained by inversion, the quadratic differential has the standard form (6) as in §3. The analytic residue can thus be computed in these coordinates as follows:

$$Res_q(0) = \int_{\gamma} \sqrt{q} = \int_{\gamma} \left(\frac{1}{w^{n/2+1}} + \frac{ia}{2w} \right) dw = \pi a$$

which is equal to the metric residue.

4.2. Other hpd's in $\hat{\mathbb{C}}$. Since there is only a unique Riemann surface conformally equivalent to \mathbb{C} , it is easy to construct half-plane differentials on the Riemann sphere:

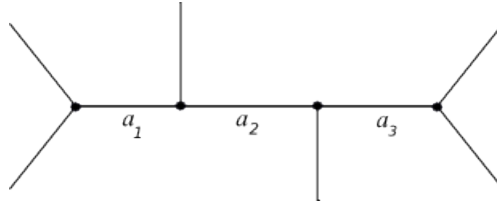


FIGURE 7. Attaching half-planes along this metric tree produces an hpd with a pole of order 8 and residue $|2a_1 - 2a_3|$.

Single-poled. Take any metric tree T with n edges of infinite length. Then there are n resulting boundary lines (think of the boundary of an ϵ -thickening of T and let $\epsilon \rightarrow 0$) and one can attach n euclidean half-planes to these boundary lines by isometries along their boundaries. The resulting Riemann surface is simply connected, and parabolic, and hence \mathbb{C} , and is equipped with an hpd with order $n + 2$ pole at infinity. The metric spine is T , and the metric residue at the pole can be read off from the lengths of edges in T (see Figure 7).

Multiple-poled. Consider \mathbb{C} obtained by gluing half-planes to a metric tree T as above. The following local modification introduces another pole: Take a subinterval of one of the edges of T and slit it open, introduce n' vertices on the resulting boundary circle, and attach n' semi-infinite edges from those vertices. Along each of the n' resulting new boundary lines, we attach half-planes as before. Topologically, one has just attached a punctured disk to \mathbb{C} after the slit, so the resulting surface (after adding the puncture) is still $\hat{\mathbb{C}}$, but this now has a half-plane differential with a new pole of order $n' + 2$. One can also vary the residues at the poles by controlling edge lengths (see Figure 8).

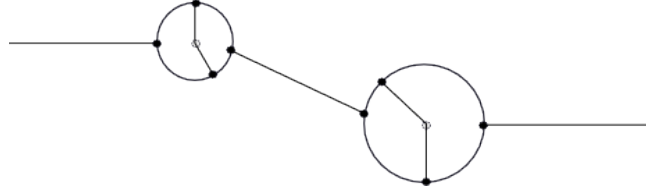


FIGURE 8. An hpd on $\hat{\mathbb{C}}$: The zeroes are the dark vertices, and the poles of order 4 are at the lighter vertices and infinity. Varying the lengths of various edges changes the residues and leading order terms.

4.3. Interval-exchange surfaces. Introduce a finite-length horizontal slit on \mathbb{C} and glue the resulting two sides of the interval by an interval exchange (see Figure 9). The resulting surface (punctured at infinity) can be of any genus, by prescribing the combinatorics of the gluing appropriately. By adding the two semi-infinite horizontal intervals on either side of the slit, one can easily see that this is a half-plane surface with two half-planes (above and below the horizontal line). The half-plane differential has a single order-4 pole at infinity.

One consequence of Theorem 1.1 is that one gets *all* once-punctured Riemann surfaces this way. The following is a simple dimension count that indicates that this is possible:

We place a vertex at infinity to get a cell decomposition of a *closed* surface of genus g . We have

$$(10) \quad v - e + f = 2 - 2g$$

where v , e and f are the number of vertices, edges and vertices of the resulting decomposition.

Note that there are two faces (the two half-planes), so $f = 2$. Moreover, in the generic case, all vertices are trivalent except one (the vertex at infinity, which has valence 2).

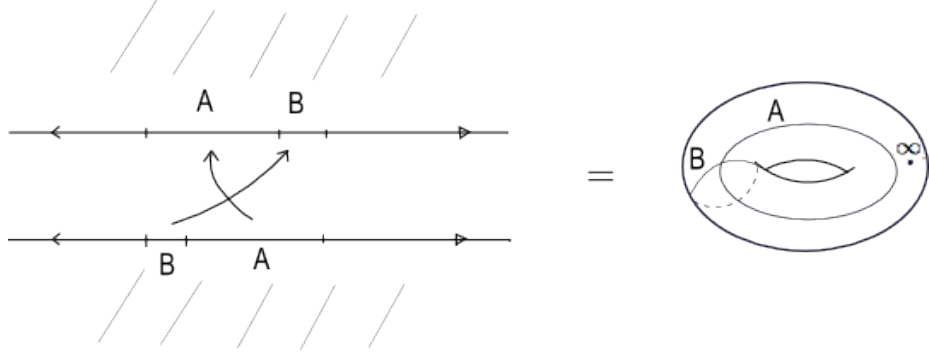


FIGURE 9. The half-plane surface obtained by the interval exchange shown on the left gives a punctured torus. This is not the generic case, as the resulting hpd has a zero of order two.

Hence

$$2e = 3(v - 1) + 2$$

Using these facts in (10) we get

$$e = 6g - 1$$

To count the resulting number of parameters, note that there are two edges corresponding to the two semi-infinite edges, and the conformal structure of the half-plane surface does not change if one scales all finite lengths by a positive real. Hence the total dimension of the set of parameters is $(6g - 4)$, which is the dimension of the moduli space $\mathcal{M}_{g,1}$.

4.4. Single-poled hpd's on surfaces. Take a single-poled hpd on $\hat{\mathbb{C}}$ and introduce a slit on one of the edges of the metric spine, and glue the resulting two sides by an interval exchange. By suitable choice of combinatorics of gluing, this gives higher genus half-plane surfaces. (See Figure 9)

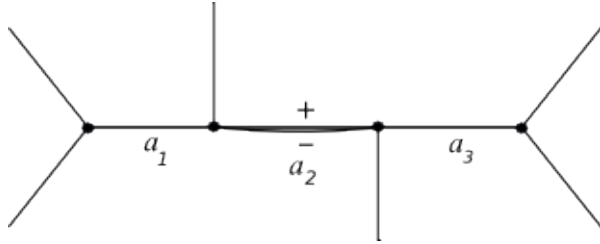


FIGURE 10. Slitting the metric spine of an hpd on $\hat{\mathbb{C}}$ along an edge and then gluing the resulting sides by an interval exchange produces a single-poled hpd on higher genus surfaces.

4.5. A low complexity example: The following lemma deals with the exceptional case in Theorem 1.1.

Lemma 4.1. *Any meromorphic quadratic differential on $\hat{\mathbb{C}}$ with a single pole p of order 4 has residue 0 at p .*

Proof. Let q be such a meromorphic quadratic differential, so it is

$$q = \left(\frac{c_4}{z^4} + \frac{c_3}{z^3} + \cdots\right)dz^2$$

in the usual coordinates in an affine chart. However in $\hat{\mathbb{C}}$ we also have the quadratic differential

$$\psi = \frac{c_4}{z^4}dz^2$$

The quadratic differential $q - \psi$ then has a single pole of order less than or equal to 3. There is no such non-zero quadratic differential on $\hat{\mathbb{C}}$, and hence $q = \psi$, and has residue 0. \square

5. OUTLINE OF THE PROOF

We illustrate the proof of Theorem 1.1 in the case of a single puncture. This easily generalizes to the case of multiple poles - in §12 we shall provide a summary.

Throughout, we shall fix a Riemann surface Σ of genus g , with a marked point p with a disk neighborhood U , and an integer $n \geq 4$ and $a, c \in \mathbb{R}^+$. Our goal is to show there exists a conformal homeomorphism

$$g : \Sigma \setminus p \rightarrow \Sigma_{n,a}$$

where $\Sigma_{n,a}$ is a half-plane surface such that the half-plane differential has one pole of order n and residue a . Furthermore, via the uniformizing chart

$$\phi : U \rightarrow \mathbb{D}$$

taking p to 0 the pullback quadratic differential on \mathbb{D} has a pole at 0 with leading order term c .

Briefly, the argument consists of producing a sequence of half-plane surfaces (*Steps 1 and 2*) that converge to a surface conformally equivalent to $\Sigma \setminus p$ (*Step 3*) and metrically a half-plane surface (*Steps 4 and 5*). The bulk of the proof lies in proving the latter convergence, after first showing that one has sufficient geometric control on the surfaces along the sequence.

Step 1. (*Quadrupling*) We define a suitable compact exhaustion $\{\Sigma_i\}$ of $\Sigma \setminus p$, and by a two-step conformal doubling procedure along boundary arcs we define a corresponding sequence of compact Riemann surfaces $\hat{\Sigma}_i$. An application of the Jenkins-Strebel theorem then produces certain holomorphic quadratic differentials on these surfaces which on passing back to Σ_i again by the involutions gives singular flat structures with “polygonal” boundary.

Step 2. (*Prescribing boundary lengths*) We complete each of these singular flat surfaces with polygonal boundary to a half-plane surface Σ'_i by gluing in an appropriate planar end. We first show that by choosing the arcs in the first doubling step appropriately, one can ensure that the sequence of planar ends one needs are truncations at height $H_i \rightarrow \infty$ of a fixed planar end \mathcal{P} . Here H_i is a sequence of real numbers diverging at a prescribed rate. This is the geometric control crucial for the convergence in *Step 4*.

Step 3. (*Conformal limit*) Applying a quasiconformal extension result we show that these half-plane surfaces Σ'_i have $\Sigma \setminus p$ as a conformal limit.

Step 4. (*The quadratic differentials converge*) We now show that the half-plane differentials corresponding to Σ'_i satisfy a convergence criterion (see Appendix A) and hence after passing to a subsequence they converge to a meromorphic quadratic differential with the right order and residue.

Step 5. (*A limiting half-plane surface*) We show that the limiting quadratic differential in *Step 4* is in fact a half-plane differential, that is, the sequence of half-plane surfaces limits to a half-plane surface $\Sigma_{n,a}$. By *Step 3*, this surface is conformally $\Sigma \setminus p$, as required.

Step 6. (*The leading order coefficient*) With a final analytical lemma we show that an additional control on the sequence $H_i \rightarrow \infty$ in *Step 2* ensures that the limiting half-plane differential has leading order term c on U , as required.

6. STEP 1: A QUADRUPLING PROCEDURE

The compact exhaustion. Consider the neighborhood U of $p \in \Sigma$ with the conformal chart $\phi : U \rightarrow \mathbb{D}$ such that $\phi(p) = 0$. Let $B(r) \subset \mathbb{D}$ denote the open disk of radius r centered at 0, and let $U(r) \subset U$ denote the inverse image $\phi^{-1}(B(r))$.

Define Σ_i to be Riemann surface $\Sigma \setminus U(2^{-i})$. For convenience we shall denote $U(2^{-i})$ by U_i . Note that this is a compact Riemann surface with boundary $C_i = \partial \Sigma_i = \partial U(2^{-i})$.

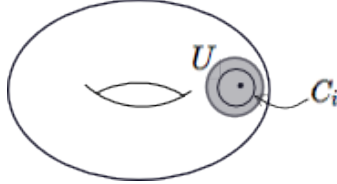


FIGURE 11. C_i is the inverse image of a circle of radius 2^{-i} under the conformal chart $\phi : U \rightarrow \mathbb{D}$.

The subsurfaces $\{\Sigma_i\}_{i=1}^\infty$ form a compact exhaustion. In particular, we note the following:

- (1) $\Sigma_i \subset \Sigma_{i+1}$ for each $i \geq 1$.
- (2) $\bigcup_{i=1}^\infty \Sigma_i = \Sigma \setminus p$.
- (3) $U_i = \Sigma \setminus \Sigma_i$ is a topological disk containing p , and
- (4) $\Sigma_i \setminus \Sigma_1$ is a topological annulus of modulus $A \cdot i$ for some constant $A > 0$.

Conformal doubling. For each subsurface in the compact exhaustion constructed in the previous section, we shall now define a two-step doubling across a collection of n arcs to get a sequence of compact surfaces $\widehat{\Sigma}_i$.

For each $i \geq 1$ consider the homeomorphism $\phi_i : \overline{U_i} \rightarrow \overline{B(2^{-i})}$ that is the restriction of the conformal chart ϕ . Choose a collection of n arcs on the boundary $\partial \overline{B(2^{-i})}$ and

pull it back via h_i^{-1} to a collection of arcs a_1, a_2, \dots, a_n on $C_i = \partial\Sigma_i$. Note that the complement of these arcs on C_i is another collection of n arcs which we denote by b_1, b_2, \dots, b_n . In *Step 2* (following section) we shall specify more about the choice of these arcs.

Consider now two copies of the surface Σ_i with the collections of a and b arcs on its boundary. Passing to the unit disc \mathbb{D} via the conformal chart h , glue the b arcs together via the anti-conformal map $z \mapsto 2^{-2i}/\bar{z}$ (this preserves the circle of radius 2^{-i}). We get a doubled surface Σ_i^d with a conformal structure, which has n slits corresponding to the a arcs on the boundary of each half (which remain unglued in our doubling).

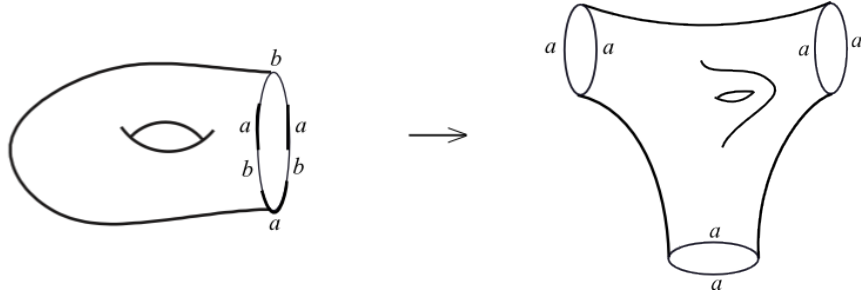


FIGURE 12. We first double Σ_i (shown on the left) along the b -arcs on the boundary to get Σ_i^d (shown on the right).

Next, we take two copies of this resulting surface Σ_i^d and glue them along these slits to get a *closed* Riemann surface $\widehat{\Sigma}_i$. This time the conformal gluing is via a suitable restriction of the hyperelliptic involution of a genus n surface branched over n equatorial slits on $\widehat{\mathbb{C}}$ (the restriction is to a collar neighborhood on one side of the equator).

Note that the glued pairs of a -slits form a collection of n nontrivial homotopy classes of curves $[\gamma_1], [\gamma_2], \dots, [\gamma_n]$ on the surface $\widehat{\Sigma}_i$.

We also have a pair of anticonformal involutions j_i^1 and j_i^2 , where $j_i^1 : \Sigma_i^d \rightarrow \Sigma_i^d$ is the deck translation of the branched double covering $\pi_i^d : \Sigma_i^d \rightarrow \Sigma_i$, and $j_i^2 : \widehat{\Sigma}_i \rightarrow \widehat{\Sigma}_i$ that similarly commutes with the branched double covering $\pi_i^2 : \widehat{\Sigma}_i \rightarrow \Sigma_i^d$.

Rectangular surfaces. By the theorem of Jenkins-Strebel, on each surface $\widehat{\Sigma}_i$ we have a holomorphic quadratic differential \hat{q}_i which induces a singular-flat metric comprising n euclidean cylinders of circumference $(2H_i, 2H_i, \dots, 2H_i + 2a)$ with core curves $[\gamma_1], [\gamma_2], \dots, [\gamma_n]$, where

$$(11) \quad H_i = (H_0 \cdot 2^i)^{n/2}$$

for a choice of a $H_0 > 0$ that shall be eventually made in Proposition 11.2.

(The reason for choosing H_i to be of the above form shall be clarified by Lemma 7.4).

We now show that this passes down to a singular flat metric on Σ_i with a “rectangular” structure when we quotient back by the anticonformal involutions j_i^1 and j_i^2 .

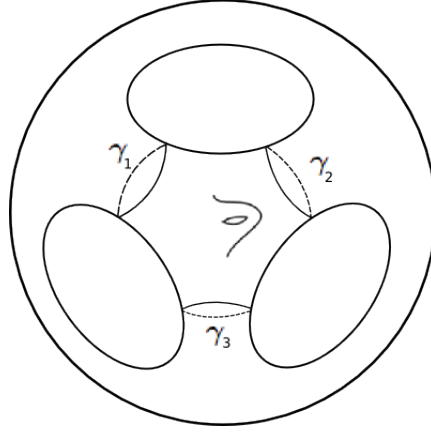


FIGURE 13. In the second step one glues two copies of Σ_d^i (see Figure 12) to get the closed, “quadrupled” surface $\widehat{\Sigma}_i$. (Not all the handles are shown in the figure.)

Lemma 6.1. *Let X be a Riemann surface with a holomorphic quadratic differential q , and let $j : X \rightarrow X$ be an anti-conformal involution that is pointwise identity on a connected analytic arc γ . Then γ is either completely horizontal or completely vertical in the quadratic differential metric.*

Proof. Let $p \in \gamma$, and let $v \in T_p X$ be the tangent vector to γ at p . Since γ is fixed pointwise by j , the induced map $j_* : T_p X \rightarrow T_p X$ satisfies $j_*(v) = v$.

Since j is anticonformal, we have that the pullback quadratic differential j^*q satisfies:

$$(12) \quad j^*q(v, v) = \overline{q(v, v)}$$

where $\bar{\alpha}$ denotes the complex-conjugate of a complex number α .

On the other hand, by definition of the pullback we have:

$$(13) \quad j^*q(v, v) = q(j_*v, j_*v) = q(v, v)$$

where we used the fact that j_* fixes v .

By (12) and (13) we have that $\overline{q(v, v)} = q(v, v)$ and hence $q(v, v) \in \mathbb{R}$.

Consider the local coordinate around any point $p \in \gamma$ in which the quadratic differential q is dz^2 . By the previous observation and the fact that γ is analytic, γ is locally either a horizontal or vertical segment around the image of p . Since γ is connected, this is true of the entire arc. \square

We apply this lemma to the involutions j_i^1 and j_i^2 . First, the anticonformal involution $j_i^2 : \widehat{\Sigma}_i \rightarrow \widehat{\Sigma}_i$ fixes the n a -slits and hence they are either completely horizontal or vertical. Since they are homotopic to the core curves of the cylinders in the \hat{q}_i -metric, they must in fact be completely horizontal. Next, the anticonformal involution $j_i^1 : \Sigma_i^d \rightarrow \Sigma_i^d$ fixes the b -arcs on Σ_i^d . Since these arcs embed in $\widehat{\Sigma}_i$ as transverse arcs across the cylinders in the \hat{q}_i -metric, they must be completely vertical.

Hence the holomorphic quadratic differential \hat{q}_i passes down to a holomorphic quadratic differential q_i on the bordered surface Σ_i . The n a -arcs on $\partial\Sigma_i$ become horizontal segments, and the remaining n b -arcs on $\partial\Sigma_i$ are vertical segments. These form a polygonal boundary. The n euclidean cylinders on $\widehat{\Sigma}_i$ descend to a cyclically-ordered collection of n euclidean rectangles on Σ_i glued along the critical graph \mathcal{G}_i . In the q_i -metric on Σ_i , the horizontal width of these rectangles are $(H_i, H_i \dots H_i + a)$ in a cyclic order (see Figure 14).

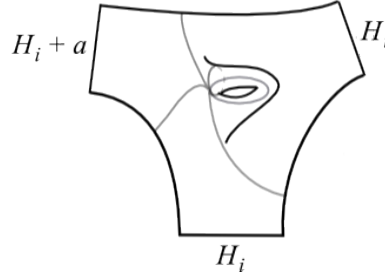


FIGURE 14. The rectangular surface at the end of *Step 1*.

7. STEP 2: PRESCRIBING LENGTHS

In *Step 1*, the Jenkins-Strebel theorem allows us to prescribe the circumferences of the resulting metric cylinders on the “quadrupled” surface $\widehat{\Sigma}_i$, but not their lengths. On quotienting back by the two involutions, this results in control on the lengths of the “horizontal” sides of the polygonal boundary of the resulting “rectangular” surface (see figure above). We show here, using a continuity method, that choosing the arcs carefully in the conformal doubling step ensures that the extremal lengths of the curves obtained from the doubled arcs on $\widehat{\Sigma}_i$ are appropriate values (Lemma 7.2) such that the vertical edge-lengths are also prescribed (Lemma 7.3).

We shall use the following:

Lemma 7.1 (A topological lemma). *Let $\phi : \mathbb{R}_{>0}^n \rightarrow \mathbb{R}_{>0}^n$ be a proper, continuous map mapping*

$$(x_1, x_2, \dots, x_n) \mapsto (y_1, y_2, \dots, y_n)$$

Suppose there exists functions η_1, η_2 such that:

(1) $x_i > A \implies y_i > \eta_1(A)$, and

(2) $x_i < \epsilon \implies y_i < \eta_2(\epsilon)$,

for each $1 \leq i \leq n$, where $\eta_1(A) \rightarrow \infty$ as $A \rightarrow \infty$, and $\eta_2(\epsilon) \rightarrow 0$ as $\epsilon \rightarrow 0$.

Then ϕ is surjective.

(Note: here $\mathbb{R}_{>0} = \mathbb{R}^+$ denotes the positive real numbers.)

Sketch of a proof. The proof is a standard topological degree argument. Note that (1) and (2) are equivalent to the requirement that ϕ , in addition to being proper, has a coordinate-wise control: for a sequence of points $(x_1^j, x_2^j, \dots, x_n^j)$ and ϕ -images $(y_1^j, y_2^j, \dots, y_n^j)$ (where $j \in \mathbb{N}$) we have that fixing $1 \leq i \leq n$, $x_i^j \rightarrow \infty \implies y_i^j \rightarrow \infty$ and $x_i^j \rightarrow 0 \implies y_i^j \rightarrow 0$ *uniformly* (independent of the rest of the coordinates). This implies that ϕ has degree 1 at infinity, and hence ϕ is surjective. \square

Arcs and extremal lengths. Consider a Riemann surface Σ with one boundary component which we identify with S^1 , and with n sub-intervals I_1, I_2, \dots, I_n of equal length. Each I_i is further divided into two sub-arcs $\{a_i, b_i\}$ in clockwise order (see figure). As in the construction in *Step 1*, consider the two step doubling that leads to a closed Riemann surface: first double along the b arcs on $\partial\Sigma$ to get a Riemann surface Σ_d with slits corresponding to the a -arcs, and next, glue two copies of Σ_d along these slits to get a closed surface $\hat{\Sigma}$.

We shall work with the doubled surface Σ_d , and homotopy classes of curves γ_i that enclose each of the slits a_i , for $1 \leq i \leq n$. Let their extremal lengths be $\lambda_1, \lambda_2, \dots, \lambda_n$ - note that these values are exactly double of the extremal lengths of the corresponding closed curves one gets on $\hat{\Sigma}$. We shall first show that by prescribing the 2-arc decomposition of each interval I_i appropriately, we can obtain any n -tuple of extremal lengths.

Consider the subinterval $I_i = a_i \cup b_i$. We denote the (angular) length of a subarc τ on $\partial\Sigma \equiv S^1$ by $l(\tau)$. Note that $l(I_i) = \frac{2\pi}{n}$ for each i . For convenience, we shall fix a conformal metric ρ on Σ that gives a length 2π to the boundary circle $\partial\Sigma$, and the above lengths of arcs shall be those induced by this metric. Denote the ratio of lengths $r_i = \frac{l(a_i)}{l(b_i)}$. Also, notice that each a_i arc has two adjacent arcs b_{i-1} and b_i on either side (where $i - 1$ is taken to be n if $i = 1$).

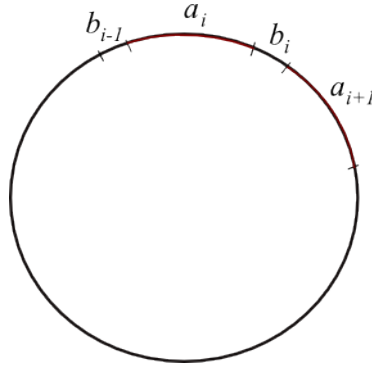


FIGURE 15. The a - and b -arcs on the boundary component of $\partial\Sigma$. The closed curve γ_i goes around the a_i slit on the surface doubled across the b -arcs, and has extremal length λ_i .

Lemma 7.2. *The map $\phi : \mathbb{R}_{\geq 0}^n \rightarrow \mathbb{R}_{\geq 0}^n$ that assigns to a tuple (r_1, r_2, \dots, r_n) of ratios of interval lengths, the corresponding extremal lengths $(\lambda_1, \lambda_2, \dots, \lambda_n)$ is surjective.*

Proof. The map ϕ is continuous since the moduli of the doubled surfaces depend continuously on the lengths of the slits (even if some slits degenerate to punctures). The lemma shall follow once we show that the following properties hold.

Notation. In what follows we shall consider an arbitrary $(r_i)_{1 \leq i \leq n}$ in $\mathbb{R}_{\geq 0}^n$ and its ϕ -image $(\lambda_i)_{1 \leq i \leq n}$. In (2) and (3) below, we consider a sequence $\{(r_i)^j\}$ of such n -tuples and their ϕ -images $\{(\lambda_i)^j\}$, where the index j runs from $1 \leq j < \infty$ and shall be appended to any of the geometric quantities varying with j .

- (1) $\lambda_i = 0 \iff r_i = 0$.
 (2) $r_i^j \rightarrow \infty \implies \lambda_i^j \rightarrow \infty$. The divergence is uniform, that is $r_i > c \implies \lambda_i > \eta_1(c)$.
 (3) $r_i < c \implies \lambda_i < \eta_2(c)$.
 (Here $\eta_1, \eta_2 : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ are increasing functions.)

Note that (1) and (2) imply that the map ϕ is proper, and from the uniform estimates in (2) and (3), the surjectivity of ϕ follows from Lemma 7.1.

Property (1): The backward implication holds since $r_i = 0 \iff l(a_i) = 0$ and hence the corresponding a -slit has degenerated to a puncture on Σ_d , and the extremal length λ_i of a loop enclosing a puncture is 0. For the other implication, observe if $l(a_i) \neq 0$ then for our choice of conformal metric ρ we shall have $l_\rho(a_i) > \eta > 0$, and a lower bound of 2η of the length of the curve around the a_i -slit. The analytic definition of extremal length:

$$\lambda_i = \sup_{\rho} \frac{l_{\rho}(a_i)^2}{A(\rho)}$$

then shows that there is a positive lower bound on the extremal length λ_i .

Property (2): Note that by definition, $r_i^j \rightarrow \infty \implies l(b_i^j) \rightarrow 0$. By the geometric definition of extremal length,

$$(14) \quad \lambda_i^j = \inf_{\text{mod}(\mathcal{A})} \frac{1}{\text{mod}(\mathcal{A})}$$

where $\mathcal{A} \subset \Sigma_d$ is an embedded annulus with core-curve enclosing the a_i^j -slit.

It is well-known that there is a bound B on the largest modulus annulus $\hat{\mathcal{A}}$ that can be embedded in \mathbb{C} such that the bounded complementary component contains the interval $[0, l(a_i^j)]$ and the other component contains the point $l(a_i^j) + l(b_i^j) \in \mathbb{R}$. Moreover, $B \rightarrow 0$ as $l(b_i) \rightarrow 0$. In our case, the a_i^j -slit on Σ_d is such an interval in an appropriate conformal chart, and the endpoint of the adjacent b -slit is the other real point. However since the annulus \mathcal{A} is now constrained to be embedded in the surface Σ_d , the modulus of \mathcal{A} is less than that of $\hat{\mathcal{A}}$ (in the planar case). One can also see this by considering the annular cover associated with the closed curve where all the slits lie. From the above discussion, this proves that $\lambda_i^j \rightarrow \infty$ by (14).

Property (2) continued: The uniform divergence follows by quantifying the estimates in the argument above: the bound B of the largest modulus of an annulus in \mathbb{C} separating the interval $[0, a]$ from $a + b \in \mathbb{R}$ is in fact a strictly increasing function of b/a . That is, $B = \eta(b/a)$ where $\eta : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ is a continuous function such that $\eta(0) = 0$. The above argument then shows that

$$r_i > c \implies \frac{l(b_i)}{l(a_i)} < 1/c \implies B < \eta(1/c) \implies \lambda_i > \eta(1/c)^{-1}$$

where we have used (14) for the last inequality. Hence the uniform estimate holds with the function $\eta_1(x) := \eta(1/x)^{-1}$.

Property (3): This follows from closely examining the argument of the backward implication in *Property (1)*: if $r_i < c$ then by definition $l(a_i) < \frac{2\pi c}{n(1+c)}$ and hence for sufficiently small c one can embed an annulus of inner radius $\frac{2\pi c}{n(1+c)}$ and outer radius

R (that depends only on ρ and Σ) on the doubled surface Σ_d . The modulus of this annulus is $M(c)$ which tends to ∞ as $c \rightarrow 0$. By the geometric definition of extremal length (14), λ_i is less than $1/M(c)$. \square

Remark. A similar setup involving slits along subintervals of the real line in $\hat{\mathbb{C}}$ was considered in [Pen88].

Cylinder lengths. As in §6, an application of the Jenkins-Strebel theorem to the homotopy classes of curves (corresponding to the doubled a -slits) on the “quadrupled” surface $\hat{\Sigma}$ produces a quadratic differential metric with a decomposition into n metric cylinders C_1, C_2, \dots, C_n with these as the core curves. By choosing the a -arcs on $\partial\Sigma$ appropriately, by Lemma 7.2 these curves can have assume any n -tuple of extremal lengths. We now show that by prescribing these extremal lengths correctly, one can assume any n -tuple of cylinder lengths $\{l_i\}_{1 \leq i \leq n}$. Note that the Jenkins-Strebel theorem already allows one to prescribe arbitrary circumferences.

Lemma 7.3. *Suppose one fixes each cylinder circumference to be H . Then the map $\psi : \mathbb{R}_{>0}^n \rightarrow \mathbb{R}_{>0}^n$ that assigns to a tuple $(\lambda_1, \lambda_2, \dots, \lambda_n)$ of extremal lengths of the core curves, the reciprocals of the cylinder lengths $(1/l_1, 1/l_2, \dots, 1/l_n)$, is surjective.*

Proof. The surjectivity of ψ shall follow from Lemma 7.1 once we establish the following properties:

- (1) $\lambda_i > C \implies 1/l_i > \eta_1(C)$.
- (2) For sufficiently small c , $\lambda_i < c \implies 1/l_i < \eta_2(c)$.

for some increasing functions $\eta_1, \eta_2 : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$.

Property (1): By (14) we have:

$$\lambda_i \geq C \implies \text{mod}(\mathcal{A}) \leq 1/C$$

where \mathcal{A} is any embedded annulus in Σ_d with core curve γ_i . This implies that $l_i \leq H/C$ since otherwise one can embed a flat cylinder of modulus greater than $1/C$ with core curve γ_i . Hence $\eta_1(x) = x/H$ works.

Property (2): We shall prove the converse statement: If $l_i < B$, then $\lambda_i > C > 0$ for some C that depends on B . For this, we shall construct a curve β_i that intersects γ_i at most twice, such that the extremal length

$$(15) \quad \text{Ext}(\beta_i) < D$$

for some D (depending on B). The lower bound C for $\lambda_i = \text{Ext}(\gamma_i)$ now follows from the well-known inequality (see [Min93]):

$$\text{Ext}(\gamma_i) \text{Ext}(\beta_i) \geq i(\gamma_i, \beta_i)^2$$

To show the bound (15) we shall use the geometric definition of extremal length (14): namely, we shall construct an annulus of definite modulus with core curve β_i .

The construction of β_i is geometric, and falls in two cases. Consider the cylinder C_i corresponding to γ_i on the quadrupled surface Σ_d , of circumference H , and length $l_i < B$ (by our current assumption). Recall C_i has a bilateral symmetry that comes

from the doubling. Each of its two boundary components is adjacent to the other cylinders C_2, \dots, C_n , and at least one of them, say C_k , shares a boundary segment with C_i of definite length, that is:

$$l(\partial C_k \cap \partial C_i) > \frac{H}{n}$$

Let the length of the cylinder C_k be l_k . The two cases are:

(I) $l_k \leq B$: In this case we construct the curve β_i intersecting γ_i once, as shown in Figure 16.

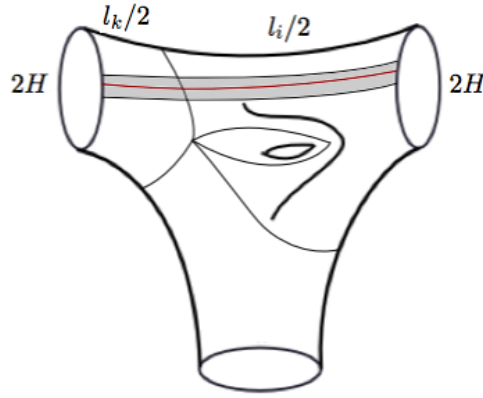


FIGURE 16. In Case I β_i consists of an arc across C_i and an arc across C_k . This figure shows half of the surface. By the two-fold symmetry from the “doubling”, these arcs join up to form a closed curve.

(II) $l_k > B$: In this case we construct β_i intersecting γ_i twice, as shown in Figure 17.

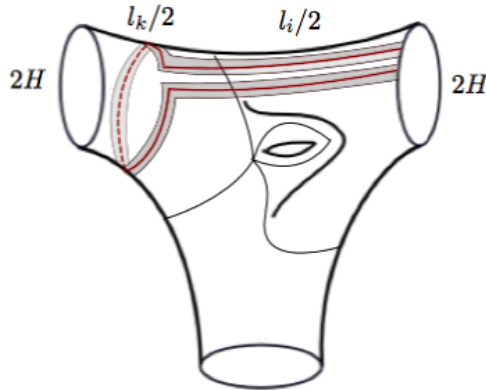


FIGURE 17. In Case II β_i comprises two arcs across C_i , separated by a definite distance, that extend a bit into C_k , together with a loops around C_k connecting the two pairs of endpoints.

In both cases, the curves are of bounded length and admit an embedded “collar” neighborhood of definite width (these dimensions depend only on B and H) and hence satisfy (15) for some D , by the geometric definition of extremal length. The function η_2 is implicit from the construction. \square

Remark. The above argument also works if the cylinder circumferences are fixed n -tuple (c_1, c_2, \dots, c_n) , by replacing H by the maximum or minimum value of the c_i -s, in the proof, as appropriate.

Half-plane surfaces Σ'_i . By Lemmas 7.3 and 7.2 one can now choose the a - and b -arcs on $\partial\Sigma_i$ such that the cylinder lengths of the Jenkins-Strebel differential on the quadrupled surface $\widehat{\Sigma}_i$ are all $2H_i$. (Recall $H_i = (H_0 \cdot 2^i)^{n/2}$ as in (11). See also the remark following Lemma 7.3.)

Hence on each singular flat surface (Σ_i, q_i) , one now has n euclidean rectangles R_1, \dots, R_n glued along the metric spine \mathcal{G}_i in that cyclic order, such that the resulting polygonal boundary has all the side-lengths H_i , except one horizontal side of length $H_i + a$ (see Figure 18 - here a is the desired residue at the pole).

We construct a half-plane surface Σ'_i by gluing in a planar end \mathcal{P}_{H_i} (see also Definition 3.3) which has a polygonal boundary isometric to $\partial\Sigma_i$. From our choice of lengths of the polygonal boundary, the metric residue of Σ'_i is equal to a . For each i these planar ends are truncations at height $H_i \rightarrow \infty$ of a fixed planar end \mathcal{P} of residue a .

Choice of H_i . Recall from §3.2 that there is a conformal map from $\mathcal{P}_{H_i} \subset \Sigma'_i$ to a neighborhood U_{H_i} of $0 \in \mathbb{C}$ that is an isometry in the ϕ -metric as in (6).

We now observe that by Lemma 3.4 the choice of H_i in (11) yields the following:

Lemma 7.4. $D'_1 2^{-i} \leq \text{dist}(0, \partial U_{H_i}) \leq D'_2 2^{-i}$, where $D'_1, D'_2 > 0$ are constants independent of i (they depend only on the choice of H_0).

Remark. This choice implies the modulus of the annulus $U \setminus U_i$ in the compact exhaustion is comparable (upto a bounded multiplicative factor) to that of the annulus $\mathcal{P}_{H_0} \setminus \mathcal{P}_{H_i}$ on the half-plane surface Σ'_i . This is the geometric control crucial for extracting a convergent subsequence in Step 4.

8. STEP 3: A CONFORMAL LIMIT

Here we show that the sequence $\{\Sigma'_i\}_{i \geq 1}$ of half-plane surfaces constructed in the previous section has $\Sigma \setminus p$ as a conformal limit:

Lemma 8.1 (Conformal limit). *For all sufficiently large i there exist $(1+\epsilon_i)$ -quasiconformal homeomorphisms*

$$(16) \quad f_i : \Sigma'_i \rightarrow \Sigma \setminus p$$

where $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$.

The intuition behind the proof is that since Σ'_i is obtained by excising-and-regluing disks from Σ that get smaller as $i \rightarrow \infty$, for large enough i the conformal structure is not too different, and one can construct an almost-conformal map as above.

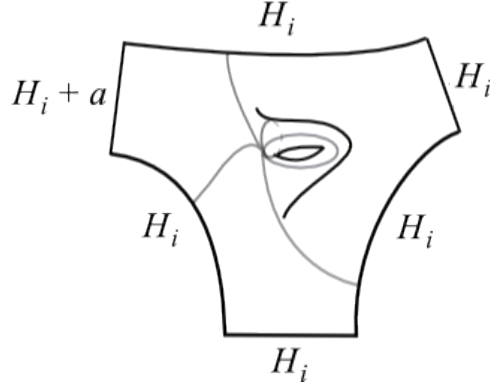


FIGURE 18. *Step 2* ensures that one gets a “rectangular” surface Σ_i with horizontal and vertical edges as shown, that can be extended to a half-plane surface Σ'_i by gluing in a planar end.

Quasiconformal extensions. The following lemma is a slight strengthening of the quasiconformal extension lemma proved in [Gup12].

Throughout, \mathbb{D} shall denote a unit disk of radius 1 and $B(r)$ shall denote an open ball of radius r , centered at $0 \in \mathbb{C}$.

Lemma 8.2. *For any $\epsilon > 0$ sufficiently small, and $0 \leq r \leq \epsilon$, a map*

$$f : \mathbb{D} \setminus B(r) \rightarrow \mathbb{D}$$

that

(1) *preserves the boundary and is a homeomorphism onto its image,*

(2) *is $(1 + \epsilon)$ -quasiconformal on $\mathbb{D} \setminus B(r)$*

extends to a $(1 + C\epsilon)$ -quasisymmetric map on the boundary, where $C > 0$ is a universal constant.

Sketch of the proof. In [Gup12] (see Appendix A of that paper) we proved this when the map f was a quasiconformal homeomorphism of the *entire* disk, though it had the control on distortion only on the annulus $A = \mathbb{D} \setminus B(r)$ as in (2) above. However, all that was required was the following estimate on the image of the ball $B(r)$:

$$\text{diam}(f(B(r))) < C_1 \epsilon$$

for some universal constant $C_1 > 0$.

Here, this can be replaced by the following fact:

$$(17) \quad d = \text{diam}(\mathbb{D} \setminus f(A)) < C_1 \epsilon$$

which follows from the modulus-estimates

$$(18) \quad \frac{1}{1 + \epsilon} \leq \frac{\text{mod}(f(A))}{\text{mod}(A)}$$

$$(19) \quad \text{mod}(A) = \frac{1}{2\pi} \ln \frac{1}{r} \leq \frac{1}{2\pi} \ln \frac{1}{\epsilon}$$

$$(20) \quad \text{mod}(f(A)) < \frac{1}{2\pi} \ln \frac{16}{d}$$

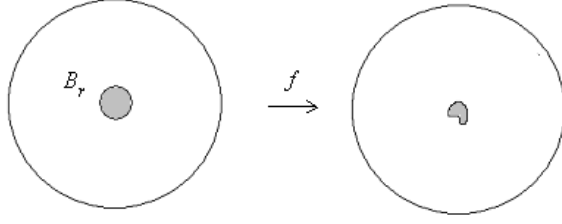


FIGURE 19. The map f in Lemma 8.2 is almost-conformal off a small sub-disk.

where (18) follows from the hypothesis (2) above, (19) follows from the fact that A is a circular annulus and $r \leq \epsilon$, and (20) is well-known (see III.A of [Ahl06a]).

The rest of the proof is exactly the same as in [Gup12]:

Let Γ be family of curves between two arcs on the boundary of \mathbb{D} , that avoids the set $\mathbb{D} \setminus f(A)$ which by (17) is of diameter $O(\epsilon)$. Then by a length-area inequality, we have the following estimate on the extremal lengths:

$$(21) \quad 1 \leq \frac{\lambda_{f(A)}(\Gamma)}{\lambda_{\mathbb{D}}(\Gamma)} \leq 1 + C_2 \epsilon$$

where $C_2 > 0$ depends only on C_1 .

Since this holds for any pair of arcs on the boundary $\partial\mathbb{D}$, it translates to a condition on the cross-ratios of four boundary points, and is enough to prove the extension of f to the boundary is $(1 + C\epsilon)$ -quasisymmetric, as claimed (see [AB56], and [Gup12] for details). \square

Corollary 8.3. *Let $r > 0$ be sufficiently small. Suppose $g : \mathbb{D} \setminus B(r) \rightarrow \mathbb{D}$ is a conformal embedding that extends to a homeomorphism of $\partial\mathbb{D}$ to $\partial\mathbb{D}$. Then there exists a $(1 + \epsilon)$ -quasiconformal map $f : \mathbb{D} \rightarrow \mathbb{D}$ such that the extension of f to $\partial\mathbb{D}$ agrees with that of g , and*

$$(22) \quad \epsilon < 2C'r$$

for some universal constant $C' > 0$.

Proof. Since g is conformal, it is also $(1 + r)$ -quasiconformal. By the previous lemma, g extends to a $(1 + Cr)$ -quasisymmetric map of the boundary, which by the Ahlfors-Beurling extension (see [AB56]) extends to an $(1 + C'r)$ -quasiconformal map of the entire disk, which is our required map f . \square

Corollary 8.4. *Let $\epsilon > 0$ be sufficiently small, and U_0, U and U' be conformal disks such that $U_0 \subset U$ and the annulus $A = U \setminus U_0$ has modulus larger than $\frac{1}{2\pi} \ln \frac{1}{\epsilon}$. Then for any conformal embedding $g : A \rightarrow U'$ that takes ∂U to $\partial U'$ there is a $(1 + C'\epsilon)$ -quasiconformal map $f : U \rightarrow U'$ such that f and g are identical on ∂U .*

Proof. By uniformizing, one can assume that $U = U' = \mathbb{D}$ and $U_0 \subset B(r)$ where $r \leq \epsilon$ by the condition on modulus. Hence this reduces to the previous corollary. \square

Proof of Lemma 8.1.

Proof. Consider the rectangular subsurface $\Sigma_i \subset \Sigma'_i$ and the conformal embedding

$$g_i : \Sigma_i \rightarrow \Sigma \setminus p$$

which exists as the subsurface Σ_i is also part of a compact exhaustion of $\Sigma \setminus p$ (see §6).

By construction of Σ'_i , the complement $\Sigma'_i \setminus \Sigma_i$ is a planar end that is conformally a punctured disk, and by property (3) of the compact exhaustion (see the first section of §6), so is the complement of $g_i(\Sigma_i)$ in $\Sigma \setminus p$.

The conformal embedding g_i restricts to a conformal map on the annulus $\Sigma_i \setminus \Sigma_1$. By property (4) of the compact exhaustion (see §6) this annulus has a modulus $M = A \cdot i$, and hence $M \rightarrow \infty$ as $i \rightarrow \infty$.

By an application of the quasiconformal extension in Corollary 8.4, one can get, for sufficiently large i , a $(1 + \epsilon_i)$ -quasiconformal map g'_i from the punctured disk $\Sigma'_i \setminus \Sigma_1$ to $U \setminus p$, that has the same boundary values as g_i on $\partial\Sigma_1$. Here $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$. In fact, by (22) and the fact that $M = A \cdot i$, we can derive the better estimate

$$(23) \quad \epsilon_i < B2^{-i}$$

where $B > 1$ is a universal constant. This will be useful in the next section.

Together with the conformal map g_i on Σ_1 , this defines the $(1 + \epsilon_i)$ -quasiconformal homeomorphism $f_i : \Sigma'_i \rightarrow \Sigma \setminus p$ for all sufficiently large i , as required in (16). \square

9. STEP 4: A LIMITING QUADRATIC DIFFERENTIAL

In this section and the next we show that after passing to a subsequence the sequence of half-plane surfaces Σ'_i converges to a half-plane surface $\Sigma_{n,a}$ - by *Step 3* this would be conformally equivalent to $\Sigma \setminus p$, as required. In this section we complete a preliminary step, namely we show that after passing to a subsequence the corresponding half-plane differentials converge in $\hat{\mathcal{Q}}_m$, the subset of the bundle of meromorphic quadratic differentials that have a single pole of order exactly n (see Appendix A for a discussion).

Recall (from §6) the half-plane surfaces Σ'_i are constructed by excising a disk and gluing in a planar end (a planar domain with a fixed quadratic differential). The idea is that though the glued-in disk gets smaller on the conformal surface, one can still extract some global control on the corresponding half-plane differentials (it is useful to remember that two holomorphic quadratic differentials on a closed surface are identical if they agree on any open set.) In particular, since the planar ends glued in are truncated at heights increasing at a prescribed rate that matches the rate of shrinking of the excised disks (see the final part of §7), the restriction of the resulting half-plane differential on a *fixed* conformal disk U converge. We make this precise in the rest of this section.

Let q'_i be the half-plane differential corresponding to the half-plane structure on Σ'_i and let $U_i = f_i^{-1}(U)$ where f_i is the $(1 + \epsilon_i)$ -quasiconformal map in Lemma 8.1. Let

$\phi_i : U_i \rightarrow \mathbb{D}$ be the conformal chart mapping $p_i = f_i^{-1}(p)$ to 0.

By the gluing-in construction (see §6 and the final part of §7), there is an open set $V_i \subset U_i \subset \Sigma'_i$ containing p_i which, in the metric induced by q'_i , is isometric to a planar end \mathcal{P}_{H_i} . Moreover, if $\phi : (U, p) \rightarrow (\mathbb{D}, 0)$ is the conformal coordinate map, then $V_i = f_i^{-1}(V)$ where $V = \phi^{-1}(B(2^{-i}))$.

Let us recall that the planar end of Σ'_i is isometric (and hence conformally equivalent) to a neighborhood of $0 \in \mathbb{C}$ equipped with the following meromorphic quadratic differential (see §3.3):

$$(24) \quad \left(\frac{1}{z^{n+2}} + \frac{ia}{z^{n/2+2}} \right) dz^2$$

Hence the quadratic differential q'_i on U_i (a subset of the planar end) is the pullback by some conformal map, of the above fixed meromorphic quadratic differential on \mathbb{C} . The fact that $V_i \subset U_i$ is isometric to the truncation at height H_i of a planar end moreover implies that this conformal map takes V_i to the neighborhood U_{H_i} of $0 \in \mathbb{C}$.

We shall use the following criterion of convergence of meromorphic quadratic differentials (see the Appendix for a discussion of the proof, and *Criterion 4'* there):

Lemma 9.1. *Let (Σ_i, U_i, p_i) be a sequence of marked, pointed Riemann surfaces converging to (Σ, U, p) in the sense that there exists a $(1 + \epsilon_i)$ -quasiconformal map $f_i : \Sigma_i \rightarrow \Sigma$ that takes (U_i, p_i) to (U, p) , such that $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$. Assume that Σ_i is equipped with a quadratic differential q_i whose restriction to U_i is the pullback by a univalent conformal map g_i of a fixed meromorphic quadratic differential on \mathbb{C} . If g_i form a normal family, then after passing to a subsequence, $q_i \rightarrow q \in \widehat{\mathcal{Q}}_m(\Sigma)$.*

This normality condition is satisfied if for each i , g_i maps the subdomain $V_i \subset U_i$ to $U_{H_i} \subset \mathbb{C}$, where via the conformal identification $\phi_i : (U_i, p_i) \rightarrow (\mathbb{D}, 0)$, we have:

$$(25) \quad d2^{-i} < \text{dist}(0, \partial U_{H_i}) < D2^{-i}$$

and

$$(26) \quad d2^{-i} < \text{dist}(0, \partial \phi_i(V_i)) < D2^{-i}$$

for constants $d, D > 0$.

Note that (25) holds by Lemma 7.4. Hence to show that in our case the maps $f_i : \Sigma'_i \rightarrow \Sigma \setminus p$ satisfy above the conditions of the above lemma (in the notation already introduced) we only need to prove the bounds (26). Recall here that V_i is the image of a round disk via a quasiconformal map $(f_i^{-1} \circ \phi^{-1})$ of small dilatation. We start with the following more general analytical lemma:

Lemma 9.2. *Let $\epsilon > 0$ be sufficiently small, and r satisfy*

$$(27) \quad r \geq \frac{\epsilon}{C}$$

for some constant $C > 1$. Let $f : \mathbb{D} \rightarrow \mathbb{D}$ be a $(1 + \epsilon)$ -quasiconformal map such that $f(0) = 0$. Let $V = f(B_r)$ be the image of the subdisk of radius r centered at 0. Then we have

$$(28) \quad \frac{r}{D} \leq \text{dist}(0, \partial V) \leq 32r$$

for some universal constant $D > 0$.

Proof. A K -quasiconformal self-map of the disk is Hölder-continuous, with coefficient 16 and exponent $1/K$ (see [Ahl06b]). So for any $z \in \partial B_r$ we have:

$$(29) \quad |f(z)| \leq 16r^{1/1+\epsilon} < 16r^{1-\epsilon} = 16r^{-\epsilon} \cdot r \leq 16(C)^\epsilon \epsilon^{-\epsilon} \cdot r < 32r$$

for sufficiently small ϵ (since $C^\epsilon \rightarrow 1$ as $\epsilon \rightarrow 0$ and $\epsilon^{-\epsilon} < e^{-e} < 1.45$).

This gives the inequality on the right, in (28).

For the left inequality of (28) let $z \in \partial B_r$, that is, $|z| = r$. Then the Hölder continuity of $f^{-1} : \mathbb{D} \rightarrow \mathbb{D}$ yields:

$$r = |z| \leq 16 |f(z) - f(0)|^{1/(1+\epsilon)} = 16 |f(z)|^{1/(1+\epsilon)}$$

and hence we have:

$$|f(z)| \geq \left(\frac{r}{16}\right)^{(1+\epsilon)} \geq r \cdot \frac{\epsilon^\epsilon}{C^\epsilon 16^{1+\epsilon}}$$

where we have used (27) for the last inequality.

It is easy to verify that for sufficiently small ϵ , we have:

$$\frac{\epsilon^\epsilon}{C^\epsilon 16^{1+\epsilon}} \geq \frac{1/2}{2 \cdot 16^{3/2}}$$

and hence we can take $D = 256$ in (28). \square

Remarks. 1. The condition (27) is necessary, as in general quasiconformal maps are Hölder continuous with exponent less than 1 and no better, and (28) then fails for small r .

2. The left inequality can be thought of a quasiconformal version of the Koebe one-quarter theorem, and it would be interesting to give a better estimate of the constant D .

Proposition 9.3 (Step 4). *There is a subsequence of $\{q'_i\}_{i \geq 1}$ that converges to a meromorphic quadratic differential q on Σ with a pole of order n and residue a at p .*

Proof. We recapitulate some of the previous discussion in this section:

In the construction of the half-plane surface Σ'_i , one excises a subdisk $V_i \subset U$ and glues it back by a different quasisymmetric map w of a circle (the boundary extension of the conformal map uniformizing $\Sigma \setminus U$ to the rectangular surface Σ_i) to form a new conformal surface. The conformal structure on the resulting disk $U_i = (U \setminus V_i) \cup_w V_i$ now admits a uniformizing map $\phi_i : (U_i, p_i) \rightarrow (\mathbb{D}, 0)$, and in the quadratic differential metric the disk $\phi_i(U_i)$ is isometric to a subset of a planar end of residue a . It follows that the quadratic differential on $\phi_i(U_i)$ is a pullback of the fixed differential (24) on \mathbb{C} (with a pole at 0) via a univalent conformal map. By construction, U_{H_i} corresponds to the subdomain $\phi_i(V_i)$ via this map.

We shall verify the convergence criterion of Lemma 9.1. Recall that $\phi : (U, p) \rightarrow (\mathbb{D}, 0)$ was the uniformizing map for the (fixed) pointed disk (U, p) on Σ , and $f_i : (\Sigma_i, U_i) \rightarrow (\Sigma, U)$ was a $(1 + \epsilon_i)$ -quasiconformal map (Lemma 8.1). Hence the map $f = \phi_i \circ f_i^{-1} \circ \phi^{-1} : \mathbb{D} \rightarrow \mathbb{D}$ is a $(1 + \epsilon_i)$ -quasiconformal map, and since the disk excised at the beginning of the construction was $\phi^{-1}(B(2^{-i}))$, the image of the disk $B(2^{-i})$ under f is $\phi_i(V_i)$.

From (23) in the proof of Lemma 8.1, we have that:

$$(30) \quad \epsilon_i < B2^{-i}$$

for some constant $B > 1$, and hence the condition (27) of Lemma 9.2 is satisfied (here $r = r_i = 2^{-i}$ and $\epsilon = \epsilon_i$). Applying Lemma 9.2 to the map f , we then get the distance bounds (26). The bounds (25) also hold by Lemma 7.4, as noted previously.

Applying Lemma 9.1 to the sequence of half-plane surfaces Σ_i with their corresponding half-plane differentials q'_i , we have that there is a limiting meromorphic quadratic differential $q \in \widehat{\mathcal{Q}}_m(\Sigma)$. \square

10. STEP 5: A LIMITING HALF-PLANE SURFACE

The set $\mathcal{Q}_{\mathcal{D}'}$ of half-plane differentials associated with the local data

$$\mathcal{D}' = \{(n_j, a_j) | n_j \in \mathbb{N}, n_j \geq 4, a_j \in \mathbb{R}_{\geq 0}, \text{ where } a_j = 0 \text{ for } n_j \text{ odd.}\}$$

of order of poles and residues at the marked points, is a subset of $\widehat{\mathcal{Q}}_m$. In this section we shall prove that this subset is closed. To simplify the discussion, we shall continue to consider the case of a *single* pole of order n and residue a . The proof of the general case follows by an easy extension of the arguments.

Theorem 10.1. *Let Σ_i be a sequence of half-plane surfaces in $\mathcal{Q}_{\mathcal{D}'}$ such that the corresponding half-plane differentials $q_i \rightarrow q \in \widehat{\mathcal{Q}}_m$. Then q is a half-plane differential in $\mathcal{Q}_{\mathcal{D}'}$.*

This together with Proposition 9.3 shall complete the proof of the following:

Proposition 10.2. *The convergent subsequence of $\{q'_i\}_{i \geq 1}$ converges to a half-plane differential q on Σ with a pole of order n and residue a at p .*

Proof of Theorem 10.1. Consider a family of half-plane differentials $q_i \in \mathcal{Q}_{\mathcal{D}'}$ that converge in $\widehat{\mathcal{Q}}_m$. The goal is to show that after passing to a subsequence the corresponding sequence of half-plane surfaces converges geometrically to a half-plane surface. This shall be done in this section by considering the *metric spines* (see Definition 10.4) of the sequence and constructing the limiting half-plane surface from the limiting metric spine (Definition 10.15). The geometric convergence is not quite a metric or biLipschitz one, as edges of the spines might collapse. A crucial observation is that by the assumption of convergence in $\widehat{\mathcal{Q}}_m$, in the sequence of metric spines, their embeddings in the surface do not get worse (Lemma 10.12), cycles do not collapse (Lemma 10.14), and hence the limiting metric spine yields the same marked topological surface. The proof is completed by showing this limiting half-plane surface is indeed a *conformal* limit of the sequence (Lemma 10.16) by building quasiconformal maps whose dilatation tends to 1.

Spines.

Definition 10.3. A *topological spine* on a surface S with a set of punctures P is an embedded graph that $S \setminus P$ deformation-retracts onto. Moreover, we assume each vertex other than the punctures has valence at least three, so there are no unnecessary vertices.

Definition 10.4. Associated to the half-plane differential q on Σ is its *metric spine* $\mathcal{G}(q)$, which is the metric graph on the half-plane surface obtained from the boundaries of the half-planes after identifications. This is a topological spine as in the previous definition - the retraction can be defined by collapsing along the vertical rays on each half-plane.

The metric spines $\mathcal{G}_i = \mathcal{G}(q_i)$ are topologically equivalent since they are all spines of $\Sigma \setminus P$. After passing to a subsequence, one can assume that they are isomorphic. Let \mathcal{G}_{top} denote this fixed finite graph, such that each \mathcal{G}_i is just an assignment of lengths to its set of edges \mathcal{E} . By passing to further subsequence we can assume that the edge-lengths $l_i(e)$ for $e \in \mathcal{E}$ converge to a collection of non-negative reals $\{l(e)\}_{e \in \mathcal{E}}$.

Definition 10.5. The *collapsing locus* \mathcal{C} of the sequence is the set of edges of \mathcal{G}_{top} whose edge-lengths tend to zero, and the *diverging locus* \mathcal{D} of the sequence is the set of edges whose lengths tend to infinity.

The goal of the next sections is to show that in fact, after passing to a subsequence, the *embeddings* of these spines can also be assumed to be the same upto isotopy, that is, the metric spines are identical as *marked* graphs on the surface. From this it will follow that the collapsing locus \mathcal{C} has no cycles and \mathcal{D} is empty (Lemma 10.14).

Bounded twisting and no collapsing cycles.

Definition 10.6 (Twist). Let S be a surface and $A \subset S$ an annulus with core a non-trivial simple closed curve γ . For an embedded arc τ between the boundary components of A , the *twist* of τ around γ relative to A is an integer denoting the number of times τ goes around γ in A , upto isotopy fixing the endpoints $\tau \cap \partial A$. (We ignore signs by taking an absolute value.)

Remark. The above twist can be thought of as the distance in the curve complex of the annulus A (see also §3 in [Min96]).

The following notion is to ensure that *all* non-trivial twists about the core curve are captured in the annulus in the above definition:

Definition 10.7 (Maximal annulus). Given a non-trivial simple closed curve c on a surface, its associated *maximal annulus* $A(c)$ is an embedded open annulus with core curve c such that the complement of its closure is either empty, or has components which are either disks or once-punctured disks.

Remark. An example is the maximal embedded annulus realizing the extremal length for γ - the complement of its interior is a graph on the surface. In our case, we shall embed the annulus away from disks around the punctures, which gives the once-punctured disks in its complement.

Lemma 10.8. Let $D_c : S \rightarrow S$ denote the Dehn twist around a simple closed curve c , and M be a positive integer. Then for any maximal annulus $A(c)$ and any simple closed curve γ that intersects c , the twist of some component arc of $D_c^n(\gamma) \cap A(c)$ about c is greater than M for all n sufficiently large.

Proof. It suffices to show that the “twists” of the arcs $D_c^n(\gamma) \cap A(c)$ about c are supported in the interior of $A(c)$, that is, cannot be isotoped away from the annulus. This holds because $A(c)$ is maximal, that is, the complement of its interior comprises closed disks connected by arcs. The image curve $D_c^n(\gamma)$ being embedded cannot run along these arcs more than once, and any twisting in the interior of the disks can be isotoped to be trivial. \square

The following finiteness result is well-known. In the statement “sufficiently large” can be taken to be a finite set of curves consisting of a complete marking (a maximal set of pants curves together with curves intersecting each), or alternatively, the Humphries generators for the mapping class group of S .

Lemma 10.9. *Let \mathcal{C} be a sufficiently large collection of simple closed curves on a surface S . For each $N > 0$, the set :*

$$\mathcal{S} = \{\gamma \text{ is a simple closed curve} \mid \text{Each component of } \gamma \cap A(c) \text{ has twist less than } N \text{ around } c, \text{ for each } c \in \mathcal{C}\}$$

is a finite set.

Proof. There are finitely many curves $\gamma_1, \gamma_2, \dots, \gamma_k$ on S upto the action of the mapping class group $MCG(S)$, which is virtually generated by Dehn twists around \mathcal{C} . By Lemma 10.8 powers of a Dehn twist around $c \in \mathcal{C}$ increases the twist of some component of $\gamma_j \cap A(c)$ around c , and hence by the condition that twists are bounded there are only finitely many mapping classes g_1, \dots, g_N such that $g_i \cdot \gamma_j \in \mathcal{S}$ (where $1 \leq i \leq N$, and $1 \leq j \leq k$). Hence \mathcal{S} is finite. \square

As a consequence we have the finiteness of spines with a similar “bounded twisting” condition:

Lemma 10.10. *Let \mathcal{C} be a sufficiently large collection of simple closed curves on a surface S . For each $N > 0$, the set :*

$$\mathcal{M} = \{m \text{ is a topological spine for } S \setminus P \mid \text{Each component of } e \cap A(c) \text{ has twist less than } N \text{ around } c, \text{ for each edge } e \in m \text{ and } c \in \mathcal{C}\}$$

is a finite set.

Proof. It suffices to show that each cycle in a spine in \mathcal{M} corresponds to finitely many possible homotopy classes of curves on the surface. Since there are uniformly bounded number of edges in the spine (depending only on the topology of the surface), and each edge of the cycle has bounded twisting around each $c \in \mathcal{C}$, so does the embedded cycle on the surface, and the finiteness follows from the previous lemma. \square

Consider now the sequence of half-plane surfaces Σ_i and the metric spines \mathcal{G}_i .

Lemma 10.11. *There exists a choice of disk neighborhoods $U_i \subset \Sigma_i$ around the pole of q_i , for each $i \geq 1$, such that for the sequence of singular flat surfaces $S_i = \Sigma_i \setminus U_i$ we have:*

(1) *The sequence of areas $\text{Area}(S_i) = \int_{S_i} |q_i|$ is uniformly bounded from above.*

(2) *For any simple closed curve γ on S , the length in the q_i -metric of any curve in S_i homotopic to γ is uniformly bounded from below.*

Proof. Since the meromorphic quadratic differentials q_i are converging in $\widehat{\mathcal{Q}}_m$, the underlying conformal structures converge. Choose a disk U around the pole in Σ , and for a choice of $\epsilon > 0$, fix a sequence of $(1 + \epsilon)$ -quasiconformal maps $f_i : \Sigma_i \rightarrow \Sigma$ preserving the puncture. Set $U_i = f_i^{-1}(U)$. By the convergence of q_i , the area or L^1 -norm of q_i on S_i converges to $\text{Area}(\Sigma \setminus U)$, and hence we have statement (1) above. Also, by the convergence, the singular flat q_i -metrics lie in a compact set, and hence so do the lengths of the geodesic representatives of a fixed simple closed curve γ on Σ_i . (By properties of non-negative curvature, such a geodesic representative is unique except the case when they sweep out a flat annulus, in which case the lengths are all the same.) This implies that the length of any curve in S_i homotopic to γ is uniformly bounded from below, which is statement (2). \square

Lemma 10.12. *For any simple closed curve γ , consider a maximal embedded annulus $A_i(\gamma)$ on S_i . Then for any edge e of the spine \mathcal{G}_i , each component of $e \cap A_i(\gamma)$ has*

uniformly bounded length as $i \rightarrow \infty$. Moreover, $A_i(\gamma)$ is a maximal annulus on Σ_i and $e \cap A_i(\gamma)$ has uniformly bounded twist about γ .

Proof. The horizontal edge e from the spine twists across the annular region $A_i(\gamma)$. Assume a large number of twists. For each point in $e \cap A_i(\gamma)$ sufficiently in the middle, there is a vertical segment into an adjacent half-plane, which because of the twisting, has length at least the circumference of $A_i(\gamma)$ before it can escape the annulus (see Figure 20).

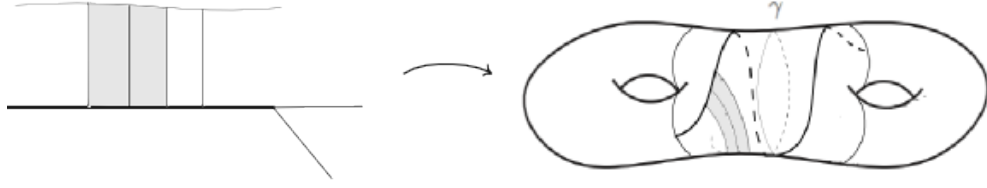


FIGURE 20. A collar about the metric spine eating into an adjacent half-plane (shown on the left) embeds in $A_i(\gamma)$ contributing to area.

This circumference is bounded below by (2) of Lemma 10.11, and hence this sweeps out a definite metric collar in $A_i(\gamma)$ around the spine, which contributes area proportional to the length of $e \cap A_i(\gamma)$. On the other hand, by (1) of Lemma 10.11 the areas of $A_i(\gamma)$ (which are less than $\text{Area}(S_i)$) remain uniformly bounded, and hence so do the lengths of $e \cap A_i(\gamma)$. Again by the uniform lower bound on the circumferences of $A_i(\gamma)$, this implies that the twisting of e around γ cannot tend to infinity (each twist will add to a length of at least half the circumference). Since the complement of a S_i is a punctured disk U_i , the annulus $A_i(\gamma)$ that is maximal on S_i , is also maximal on Σ_i . \square

The following is now immediate from Lemma 10.10:

Corollary 10.13. *After passing to a further subsequence, we can assume that the metric graphs \mathcal{G}_i are isomorphic as marked spines on the surface. In particular, a cycle in the graph corresponds to the same homotopy class of a closed curve throughout the sequence.*

Lemma 10.14 (No collapsing cycles). *\mathcal{C} is a forest, that is, it contains no cycle, and \mathcal{D} is empty.*

Proof. The meromorphic quadratic differentials q_i lie in a compact set K of $\widehat{\mathcal{Q}}_m$ since they form a convergent sequence. By Corollary 10.13, after passing to a subsequence a cycle in the metric graph \mathcal{G}_i corresponds to a (fixed) non-trivial curve in Σ whose lengths in the singular flat q_i -metric must have a uniform lower bound by the compactness of K . By the uniform (upper) length bound of Lemma 10.12 there cannot be an edge whose lengths tend to infinity. \square

Recall from the discussion preceding Definition 10.5 that the finite edge-lengths of the metric spines converge after passing to a subsequence. Let \mathcal{G} be metric graph obtained by assigning this length $l(e)$ to every edge $e \in \mathcal{G}_{top}$, where it is understood that any component tree of the collapsing locus \mathcal{C} is identified with a single vertex.

The previous lemma ensures that \mathcal{G} has the same topological type, that is, remains homotopy equivalent to \mathcal{G}_{top} .

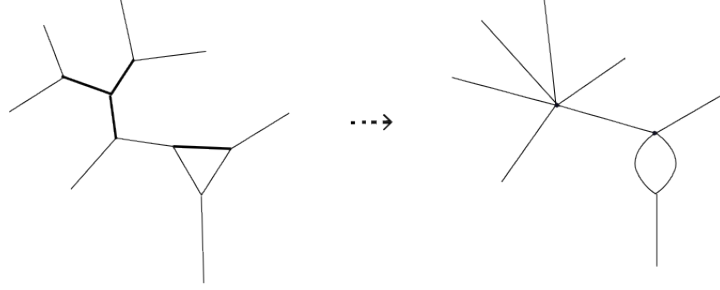


FIGURE 21. The edges in \mathcal{C} (shown in bold on the left) collapse along the sequence of graphs \mathcal{G}_i .

Definition 10.15 (Limiting half-plane surface). The half-plane surface $\Sigma_{\mathcal{G}}$ is defined to be the one obtained by gluing in n half-planes along the metric graph \mathcal{G} in the combinatorial order identical to the gluing of the half-planes along the metric spine of each (Σ, q_i) . (Here we assume we have passed to a subsequence where the metric spines are identical as marked graphs.)

Proving $\Sigma_{\mathcal{G}}$ is the conformal limit.

Lemma 10.16. *For all sufficiently large i there exist $(1 + \epsilon_i)$ -quasiconformal maps*

$$\bar{h}_i : \Sigma'_i \rightarrow \Sigma_{\mathcal{G}}$$

where $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$.

We start by observing that a map that collapses a short segment of the boundary of a half-plane \mathbb{H} can be extended to a map of the half-plane that is almost-isometric away from a suitable neighborhood:

Lemma 10.17. *For any $\epsilon > 0$ there exists a $\delta > 0$ such that a map $h : \partial\mathbb{H} \rightarrow \partial\mathbb{H}$ that collapses an interval I of length ϵ and isometric on its complement, extends to a homeomorphism $\bar{h} : \mathbb{H} \rightarrow \mathbb{H}$ that is an isometry away from an δ -neighborhood of I . Moreover, one can choose δ such that $\delta \rightarrow 0$ as $\epsilon \rightarrow 0$.*

Proof. One can in fact choose $\delta = \epsilon$, and the extension to be height-preserving, as follows. Let $\mathbb{H} = \{(x, y) \mid y > 0\}$ and $I = [-\epsilon/2, \epsilon/2] \times \{0\}$. Choose a “bump” function $\phi(x, y)$ supported on the rectangle $R = [-\epsilon, \epsilon] \times [0, \epsilon]$ that is positive in its interior and interpolates between 0 on I and 1 on the complement of R . This function $\phi(x, y)$ is the “dilatation factor” of a horizontal stretch map

$$h(x, y) = (\phi(x, y)x, y)$$

that is the required extension. □

Proof of Lemma 10.16. For any $\epsilon > 0$, we shall construct a $(1 + \epsilon)$ -quasiconformal map from Σ'_i to $\Sigma_{\mathcal{G}}$ for all sufficiently large i . The construction is in two steps: in the first step we map to an intermediate half-plane surface $\Sigma_{\mathcal{G}'_i}$.

Step I. Let \mathcal{E} be the set of edges in \mathcal{G}_{top} . The cardinality $|\mathcal{E}|$ is finite, a number depending only on the genus of Σ . Recall also (see Definition 10.5) that $\mathcal{C} \subset \mathcal{E}$ is the sub-graph consisting of edges whose lengths along the sequence \mathcal{G}_i tend to zero.

The lengths of edges of $\mathcal{E} \setminus \mathcal{C}$ in \mathcal{G}_i however converge to *positive* lengths of the corresponding edges in \mathcal{G} . Hence for all $e \in \mathcal{E} \setminus \mathcal{C}$ we have:

$$(31) \quad r_i = \frac{l_i(e)}{l(e)} \rightarrow 1$$

as $i \rightarrow \infty$.

Consider the metric graph \mathcal{G}'_i obtained by assigning the following lengths to the edges of \mathcal{G}_{top} : $l(e)$ to all edges in $\mathcal{E} \setminus \mathcal{C}$ and $l_i(e)$ to all edges in \mathcal{C} . We can construct a K_i^1 -biLipschitz map

$$(32) \quad h_i^1 : \mathcal{G}_i \rightarrow \mathcal{G}'_i$$

that preserves vertices, is a linear stretch map on all the finite-length edges in $\mathcal{E} \setminus \mathcal{C}$, and is an isometry on every other edge. By (31), the stretch-factors, and therefore the biLipschitz constants $K_i^1 \rightarrow 1$ as $i \rightarrow \infty$.

Note that any K -biLipschitz map

$$b : \mathbb{R} \rightarrow \mathbb{R}$$

can be extended to a K -biLipschitz map $\bar{b} : \mathbb{H} \rightarrow \mathbb{H}$ of the upper half-plane (here $\mathbb{R} = \partial\mathbb{H}$ by mapping

$$(x, y) \mapsto (b(x), y).$$

Applying this to the map (32) above, we get for all sufficiently large i , a $(1 + \epsilon)$ -biLipschitz extension

$$(33) \quad \bar{h}_i^1 : \Sigma_i \rightarrow \Sigma_{\mathcal{G}'_i}$$

where $\Sigma_{\mathcal{G}'_i}$ is the half-plane surface obtained by gluing half-planes along \mathcal{G}'_i .

Step II. Note that the graph \mathcal{G} is obtained by collapsing all the edges of \mathcal{C} in \mathcal{G}'_i . Let E be the set of finite-length edges of $\mathcal{E} \setminus \mathcal{C}$ and consider the minimum length

$$c = \min_{e \in E} l(e)$$

if $E \neq \emptyset$ is non-empty, and set $c = 2$ if $E = \emptyset$.

If \mathcal{C}_i denotes the metric subgraph corresponding to \mathcal{C} in \mathcal{G}_i , recall we have

$$(34) \quad \text{diam}(\mathcal{C}_i) \rightarrow 0$$

as $i \rightarrow \infty$.

Since \mathcal{C}_i is a forest by Lemma 10.14, for sufficiently large i we have:

- (1) For each half plane \mathbb{H} of the half-plane surface $\Sigma_{\mathcal{G}'_i}$ the intersection $\partial\mathbb{H} \cap \mathcal{C}_i$ is a union of segments each of length less than ϵ and separated by a distance at least c .
- (2) The $c/2$ -neighborhood $N_{c/2}$ of \mathcal{C}_i is topologically a union of disks, one for each component tree.

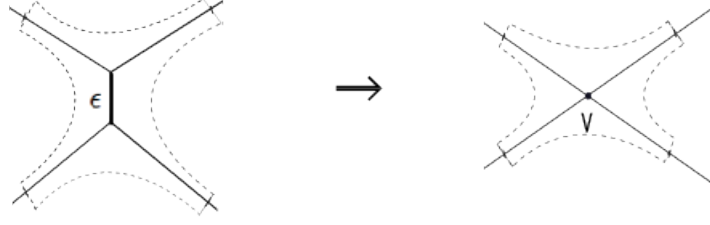


FIGURE 22. In *Step II* the map between half-plane surfaces that is an isometry away from a neighborhood of \mathcal{C} is finally adjusted to an almost-conformal map.

Moreover, for sufficiently large i , ϵ is small enough such that the corresponding $\delta < c/2$ where δ is as in Lemma 10.17. By an application of that Lemma on each half-plane, one can build a homeomorphism

$$(35) \quad \overline{h'_i} : \Sigma_{\mathcal{G}'_i} \rightarrow \Sigma_{\mathcal{G}}$$

that is an isometry (and hence conformal) away from a δ -neighborhood N_δ of \mathcal{C}_i .

By observation (2) above each component of $N_{c/2} \setminus N_\delta$ is topologically an annulus, and has modulus that tends to infinity as $\delta \rightarrow 0$. Hence for sufficiently large i , one can apply the quasiconformal extension of Corollary 8.4 to adjust the map $\overline{h'_i}$ in the component disks of N_δ to obtain a $(1 + C'\epsilon)$ -quasiconformal map homeomorphism

$$(36) \quad \overline{h_i^2} : \Sigma_{\mathcal{G}'_i} \rightarrow \Sigma_{\mathcal{G}}$$

Recall the map (33) from *Step I*. The composition

$$(37) \quad \overline{h_i} = \overline{h_i^2} \circ \overline{h_i^1} : \Sigma_i \rightarrow \Sigma_{\mathcal{G}}$$

is then $(1 + C''\epsilon)$ -quasiconformal, for some universal constant $C'' > 0$, as required. \square

11. STEP 6: PRESCRIBING THE LEADING ORDER TERM

From Lemmas 8.1 and 10.16 we now have:

Proposition 11.1. *The quasiconformal maps $g_i \circ f_i^{-1} : \Sigma \setminus p \rightarrow \Sigma_{\mathcal{G}}$ have quasiconformal dilatation that tends to 1 as $i \rightarrow \infty$, and hence limits to a conformal homeomorphism*

$$g : \Sigma \setminus p \rightarrow \Sigma_{\mathcal{G}}$$

in the sense of uniform convergence on compact sets, after passing to a subsequence. Here, $\Sigma_{\mathcal{G}} = \Sigma_{n,a}$, that is, it is a half-plane surface with a pole of order n and residue a . Moreover, g is homotopic to the identity map.

Proof. The quasiconformal maps extend to a map between the closed surfaces, mapping p to ∞ . The uniform convergence is a standard application of the compactness of a family of quasiconformal maps with fixed domain and target, and bounded dilatation. Since the quasiconformal dilatations of f_i and g_i tend to 1 as $i \rightarrow \infty$, that the limiting homeomorphism is 1-quasiconformal, and hence conformal.

By construction (see Proposition 9.3), the limiting half-plane differential has a pole of order n and residue a . Inspecting the construction of the quasiconformal homeomorphisms f_i and g_i , we observe that both are homotopic to the identity (f_i is a quasiconformal map on a disk together with the identity map on its complement, and g_i restricts to a homotopy equivalence of the metric spines). Hence so is each homeomorphism $g_i \circ f_i^{-1}$, and the limit g . \square

To complete the proof of Theorem 1.1 (in the case of a single marked point p) it only remains to show that the half-plane differential has a leading order term c with respect to the fixed choice of coordinate neighborhood U around p . By Lemma 3.8 it will be enough to show that the above conformal map g has derivative of suitable magnitude with respect to this conformal neighborhood. This is where a suitable choice of the constant H_0 in (11) will be made.

As before let $\phi : U \rightarrow \mathbb{D}$ be a conformal homeomorphism such that $\phi(p) = 0$. Let $g(U)$ be a subset of a planar end is identified with a complement of a compact set in \mathbb{C} . As in §3.3, by an inversion map, one has a conformal homeomorphism $\psi : g(U) \rightarrow V$ that takes ∞ to 0, where V is a simply connected domain in \mathbb{C} containing 0. In the rest of this section we shall show:

Proposition 11.2. *There is a choice of H_0 in (11) for which the conformal map $G = \psi \circ g \circ \phi^{-1} : \mathbb{D} \rightarrow \mathbb{C}$ that takes 0 to 0, has derivative $|G'(0)| = c^{-\frac{1}{n-2}}$. For this H_0 , we have that the leading term of the half-plane differential for Σ_G is c with respect to the coordinate chart U .*

The proof of this needs the following analytical lemma:

Lemma 11.3. *Let $f_i : \mathbb{D} \rightarrow \mathbb{C}$ be a sequence of quasiconformal embeddings such that:*
(1) $f_i(0) = 0$ for all i ,
(2) f_i is $(1 + \epsilon_i)$ -quasiconformal, where $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$, and
(3) for some sequence $r_i \rightarrow 0$ we have that $f(B_{r_i}) = V_i$, where V_i is an open simply connected domain containing $0 \in \mathbb{C}$ having a uniformizing map $\phi_i : (V_i, 0) \rightarrow (\mathbb{D}, 0)$, such that:

$$(38) \quad |r_i \phi_i'(0)| \rightarrow \alpha$$

as $i \rightarrow \infty$.

Then after passing to a subsequence, f_i converges uniformly to f , a univalent conformal map such that $|f'(0)| = 1/\alpha$.

Proof. It is a standard fact that a sequence of K -quasiconformal self maps of $\hat{\mathbb{C}}$ normalized by the additional requirement that it fixes two points 0 and ∞ forms a sequentially compact family with respect to uniform convergence. This is satisfied by the family $\{f_i\}$ for each $K > 1$ and hence there is a limiting conformal map f as required, which is either univalent or constant. It only remains to show that $|f'(0)| = 1/\alpha$ - this will also rule out the latter possibility.

Consider the conformal dilatation $\psi_i : \mathbb{D} \rightarrow B_{r_i}$ where $\psi_i(z) = r_i z$. Note that $\psi_i'(0) = r_i$. Then the composition $F_i = \phi_i \circ f_i \circ \psi_i : \mathbb{D} \rightarrow \mathbb{D}$ is $(1 + \epsilon_i)$ -quasiconformal, where $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$ by property (2) above. The compactness result mentioned above (see also Theorem 1 of [Ahl06a]) implies that there is a subsequence that converges uniformly to a conformal map F . Moreover, since each map along the sequence

preserves the point $0 \in \mathbb{D}$, so does the limit and by the Schwarz lemma, F is a rotation and in particular

$$(39) \quad |F'(0)| = 1.$$

If each f_i were differentiable at 0, and the sequence of derivatives converged to the derivative of the limit, we would have by using the chain rule:

$$|F'(0)| = \lim_{i \rightarrow \infty} |(\phi_i \circ f_i \circ \psi_i)'(0)| = \lim_{i \rightarrow \infty} |\phi_i'(0)| \cdot |f_i'(0)| \cdot r_i = \alpha |f'(0)|$$

where the last equality is from (38). By (39) the argument would be complete, namely $|f'(0)| = 1/\alpha$ as desired. However, f_i are merely quasiconformal, and may not be differentiable at 0. However they have derivatives which are defined almost-everywhere and are locally integrable, and that converge in norm to the derivative of the limit. So we run the above argument with the *averages* (L^1 -norms) of the total derivatives in a sequence of shrinking disks around 0:

Let B_δ be a disk around 0 of radius $\delta > 0$ (sufficiently small). For a conformal or quasiconformal map F defined on \mathbb{D} we have a nonnegative real number

$$D_{avg}^\delta F = \frac{1}{Area(B_\delta)} \int_{B_\delta} |DF_i(z)| dz d\bar{z}.$$

In what follows we shall pass to a converging subsequence wherever needed. The sequence of quasiconformal maps $F_i : \mathbb{D} \rightarrow \mathbb{D}$ converges uniformly to a rotation, and hence

$$(40) \quad D_{avg}^\delta F_i \rightarrow 1$$

as $i \rightarrow \infty$.

Also, the sequence of quasiconformal maps $f_i : \mathbb{D} \rightarrow \mathbb{C}$ converges uniformly to a conformal map f , and this implies that

$$(41) \quad D_{avg}^\delta f_i \rightarrow |f'(0)|$$

as $i \rightarrow \infty$ and $\delta \rightarrow 0$.

Further, for the univalent conformal map $\phi_i : V_i \rightarrow \mathbb{D}$, one has that

$$(42) \quad \phi_i'(z) = \phi_i'(0) + Az + O(z^2)$$

where $|A|$ is bounded above by a universal constant (a standard fact in univalent mappings).

Since quasiconformal maps are differentiable almost everywhere, we have by the chain rule that

$$(43) \quad |DF_i(z)| = |D\phi_i(z)Df_i(z)D\psi_i(z)| = r_i |Df_i(z)| |\phi_i'(z)|$$

for $z \in B'_\delta$, a full-measure subset of B_δ .

By (38) for any $\epsilon > 0$ there is i sufficiently large such that $\alpha - \epsilon < r_i |\phi_i'(0)| < \alpha + \epsilon$ and $Ar_i < \epsilon$ where A is the constant in (42). Using (43) we then have:

$$\int_{B'_\delta} |DF_i(z)| dz d\bar{z} = \int_{B'_\delta} |Df_i(z)| r_i |\phi_i'(z)| dz d\bar{z} \leq \int_{B'_\delta} |Df_i(z)| (\alpha + 2\epsilon) dz d\bar{z}$$

where we have used (42) and the above observations for the last inequality.

We have a similar bound from below. By taking $i \rightarrow \infty$ we get that

$$\left| \alpha D_{avg}^\delta f_i - D_{avg}^\delta F_i \right| \rightarrow 0$$

and hence by (40) we have:

$$D_{avg}^\delta f_i \rightarrow 1/\alpha$$

which by (41) is equal to $|f'(0)|$ as $\delta \rightarrow 0$. This completes the proof. \square

In our case, we shall apply Lemma 11.3 to the sequence of quasiconformal maps $g_i \circ f_i^{-1} : \Sigma \rightarrow \Sigma_G$ (see Propn. 11.1) after restricting to the open set U that we conformally identify with \mathbb{D} (see the discussion preceding Propn. 11.2). Recall that by construction the above quasiconformal map takes the open set $V_i \subset U$ to a planar end \mathcal{P}_{H_i} that can be identified with an open neighborhood U_{H_i} of $0 \in \mathbb{C}$ (See also Lemma 3.4).

To use Lemma 11.3, we need to verify the condition (3). Recall from §3.3 that U_{H_i} is the image of the planar end truncated at height H_i . Consider a sequence of uniformizing conformal maps $\phi_i : U_{H_i} \rightarrow \mathbb{D}$ for $i \geq 1$, and recall that $r_i = 2^{-i}$ by construction (§6). In this setup, we have:

Corollary 11.4. *After passing to a subsequence, $r_i |\phi_i'(0)|$ has a limit L as $i \rightarrow \infty$. Moreover, $L \rightarrow \infty$ as $H_0 \rightarrow \infty$, and $L \rightarrow 0$ as $H_0 \rightarrow 0$, where $H_0 > 0$ was the constant chosen arbitrarily in (11), and L varies continuously with H_0 .*

Proof. By construction (see the first part of §6) we have $r_i = 2^{-i}$ and $H_i^{2/n} = H_0 \cdot 2^i$ (see also (11)). Corollary 3.5 now shows that the sequence $\{r_i |\phi_i'(0)|\}_{i \geq 1}$ lies in the interval $[H_0/4D_2, H_0/D_1]$, and hence after passing to a subsequence converges to L in that interval. As one varies H_0 , all domains (and hence the conformal maps ϕ_i and its derivatives) vary continuously (see also Lemma 3.6) and the same subsequence converges to a value that varies continuously (and lies in an appropriately shifted interval). \square

Proof of Proposition 11.2. By the previous corollary, there exists a choice of H_0 in (11) for which

$$r_i |\phi_i'(0)| \rightarrow c^{\frac{1}{n-2}}$$

Applying Lemma 11.3 to the sequence of quasiconformal maps

$$\psi \circ g_i \circ f_i^{-1} \circ \phi^{-1} : \mathbb{D} \rightarrow \mathbb{C}$$

it follows that $G = \psi \circ g \circ \phi^{-1}$ has derivative $c^{-\frac{1}{n-2}}$ at 0.

Now, the half-plane differential on the disk \mathbb{D} uniformizing U is the pullback of the standard meromorphic differential on \mathbb{C} (see (6)) by this map G . Since the leading order term at the pole for this standard differential is 1, by Lemma 3.8, the leading order term is of the half-plane differential is $|G'(0)|^{2-n} = c$, as required. \square

12. SUMMARY OF THE PROOF

Collecting the results of the previous sections, we have:

Proof of Theorem 1.1. Propositions 11.1 and 11.2 complete the proof of Theorem 1.1 in the case of a single marked point. This easily generalizes to the case of multiple poles, as we briefly summarize:

For a set $P = \{p_1, \dots, p_n\}$ on Σ consider fixed coordinate charts U_1, \dots, U_n around each. As in §6, we consider a compact exhaustion of the surface by excising subdisks of radii r_i tending to zero, from each (more specifically, we choose $r_i = 2^{-i}$). For each compact subsurface Σ_i we choose a number of arcs on each boundary component depending on the desired orders of poles and by the quadrupling construction we construct a compact Riemann surface with a collection of distinct homotopy classes of curves (the assumption that $\Sigma \neq \widehat{\mathbb{C}}$ if $n = 1$ ensures that the homotopy classes are distinct). We prescribe a Jenkins-Strebel differential with closed trajectories in these homotopy classes and given cylinder circumferences on this surface. Moreover, by Lemma 7.2 one can choose the arcs so that the extremal lengths of these curves are precisely what is needed for the cylinder lengths to be

$$H_i^j = \left(H_0^j \cdot 2^i \right)^{n_j/2}$$

for the j -th marked point ($1 \leq j \leq n$), where n_j is the desired order of the pole at that marked point. (See 11) in §6.) By quotienting back, one gets a “rectangular” metric on Σ_i with polygonal boundaries of prescribed dimensions, that can be completed to a half-plane surface Σ'_i by gluing in n planar ends. As in Lemma 7.4, the above prescribed dimensions of the polygonal boundary ensures that the planar end glued in is conformally a disk of radius $O(r_i)$ around $0 \in \mathbb{C}$.

The fact that the conformal structures on $\Sigma \setminus P$ and Σ'_i differ only a union of disks of small radii (r_i) allows us to build an almost conformal homeomorphism between them (§8) that tends to a conformal homeomorphism as $i \rightarrow \infty$. The geometric control on the dimensions of polygonal boundaries of the rectangular surfaces Σ_i also shows that the corresponding half-plane differentials converge to a meromorphic quadratic differential on Σ with poles at P (as in §9), and as in §10 this limiting differential is in fact half-plane. Finally, as in §11 one can show that an appropriate choice of “scaling” factors (the constants H_0^j above) while constructing the sequence of rectangular surfaces, ensures that the leading order terms at each pole of the resulting half-plane differential are the desired real numbers. \square

13. APPLICATIONS AND QUESTIONS

13.1. An asymptoticity result. We had previously shown (see [Gup12] for a precise statement):

Theorem ([Gup12]). *A grafting ray in a generic direction in Teichmüller space is strongly asymptotic to some Teichmüller ray.*

The main result of [Gup] is a generalization of the above asymptoticity result to *all* directions. The idea of the proof is to consider the conformal limit of the grafting ray, and find a conformally equivalent singular flat surface that shall be the conformal

limit of the corresponding Teichmüller ray. The strong asymptoticity is shown by adjusting this conformal map to almost-conformal maps between surfaces along the rays.

The result of this paper is used to find the conformally equivalent singular flat surface mentioned above: namely, Theorem 1.1 can be generalized easily to include poles of order 2, which correspond to half-infinite cylinders in the quadratic differential metric. This is used to obtain a (generalized) half-plane surface Y_∞ and a conformal map

$$g : X_\infty \rightarrow Y_\infty$$

for each component X_∞ of the conformal limit of the grafting ray.

Prescribing the leading order term, or equivalently the derivative of the above conformal map g , helps to construct the controlled quasiconformal gluings of truncations of these infinite-area surfaces.

13.2. The question of uniqueness. The construction of single-poled half-plane differentials on surfaces (see §4.4) proceeds by introducing a slit in the metric spine of a single-poled hpd $\hat{\mathbb{C}}$ as above, and gluing by an interval-exchange. (This does not affect the residue and leading order coefficient at the pole.)

Since there are non-unique choices of single-poled hpds (of order greater than 4) on $\hat{\mathbb{C}}$ which have the same residue and leading order coefficient (see §4.2), one can see that uniqueness does not hold in general, in Theorem 1.1.

However, we conjecture:

Conjecture 1. *When all the orders of the poles are 4, the half-plane differential with prescribed residues and leading order terms that exists by Theorem 1.1, is unique.*

and more generally one can ask:

Question 13.1. *Does uniqueness of the half-plane differential hold if one prescribes further local data, in addition to the order of pole, residue and leading order term?*

13.3. Limits of Teichmüller rays. One obtains half-plane surfaces as geometric limits of Teichmüller rays (details in the forthcoming papers, including [Gup]). Roughly speaking, along a Teichmüller geodesic there is a stretching of the quadratic-differential metric in the “horizontal” direction (after rescaling we can assume that distances in the vertical direction remains unchanged). This increases the area of the surface monotonically, and stretches a neighborhood of the critical graph of vertical saddle-connections, to a half-plane surface.

Generically (for directions determined by *arational* laminations) one obtains a collection of $2g-2$ half-plane differentials $(\mathbb{C}, z dz^2)$, and more interesting limits are obtained for directions determined by *non-filling* laminations.

One of the questions to be addressed in forthcoming work is:

Question 13.2. *Given a collection of half-plane surfaces with pairings of poles with matching order and residues, is it possible to construct a Teichmüller ray with that (disconnected) half-plane surface as a limit?*

APPENDIX A. CRITERIA FOR CONVERGENCE

Let Σ be a Riemann surface with marked points p_1, p_2, \dots, p_n , and k_1, k_2, \dots, k_n a tuple of integers such that $k_j \geq 4$. Let $\widehat{\mathcal{Q}}_m(\Sigma)$ be the meromorphic quadratic differentials on Σ with a pole of order k_j at p_j , for each $1 \leq j \leq n$.

We prove here some criteria for convergence of meromorphic quadratic differentials. As throughout this paper, for ease of notation we shall write these criteria only for the case of a single marked point p of order k , but the results hold for any number of them. We list them in order of sophistication - the later criteria will depend on the previous ones. The final one was used in the proof of Theorem 1.1 (see §9).

For the following lemma, one might find it useful to keep in mind this toy example:

Example. Let $f_i : \mathbb{C} \rightarrow \mathbb{C}$ be a sequence of meromorphic functions such that in an open set U that is the complement of the closed ball $\overline{B_{R_0}(0)}$, we have that $f_i(z) = \frac{\phi_i(z)}{z^n}$ for some fixed $n \geq 1$, where $\{\phi_i(z)\}_{i \geq 1}$ are holomorphic functions on U that form a normal family. Then for any $R > R_0$ the values that f_i take on the circle $\partial B_R(0)$ are uniformly bounded (independent of i). By the maximal principle, the f_i s are uniformly bounded on $B_R(0)$, and hence after passing to a subsequence, they converge uniformly on compact sets to a meromorphic function f .

Lemma A.1 (Criterion 1). *Let $\{q_i\}_{1 \leq i < \infty}$ be a sequence of meromorphic quadratic differentials in $\mathcal{Q}_m(\Sigma)$ having the local expressions*

$$q_i(z) = \frac{\phi_i(z)}{z^k} dz^2$$

in a fixed coordinate neighborhood (U, z) around the pole p . If the holomorphic functions $\{\phi_i\}_{1 \leq i < \infty}$ form a normal family and converge to a holomorphic function non-vanishing at 0 then $q_i \rightarrow q \in \widehat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.

Proof. Let $V \subset U$ be the radius-1/2 disk containing p , via the conformal chart ϕ that takes U to the unit disk. The restriction of each q_i to the compact subsurface $\Sigma' = \Sigma \setminus V$ is holomorphic in its interior. Our goal is to show that they are locally uniformly bounded, and it is enough to show that their L^1 -norms (or equivalently, the q_i -areas of Σ') have a uniform bound.

Fix an arbitrary conformal metric on Σ' and $\delta > 0$ and let D_δ is a radius- δ disk on Σ' . Then we have:

Claim. $\|q_i\|_{L^1(\Sigma')} \leq C \|q_i\|_{L^1(D_\delta)}$, where C is a constant depending on Σ' and δ .

Proof. The proof of this is identical to that of Lemma 12.1 of [Dum07]. By rescaling, it suffices to prove that for *unit-norm* quadratic differentials, $\|q_i\|_{L^1(D_\delta)} \geq 1/C$ for some constant C . We proceed by contradiction: if not, we obtain a sequence of unit-norm quadratic differentials on Σ' such that the q_i -area of D_δ goes to zero. By compactness of unit-norm quadratic differentials, there is a convergent subsequence, and the limiting quadratic differential has unit norm. However it vanishes on D_δ , and

hence, by holomorphicity, is identically zero on the surface, which is a contradiction.

By the above claim it is enough to show that the q_i -area of *some* radius- δ disk is uniformly bounded (independent of i). We choose the metric, and δ , such that the annular region $U \setminus V$ contains such a δ -disk W . The sequence $\{q_i\}_{i \geq 1}$ then restricts to a uniformly bounded family on W by assumption, and this completes the proof. The final assumption of non-vanishing at 0 ensures that the limiting meromorphic quadratic differential has a poles of the same order k at p , so the limit lies in the space $\hat{\mathcal{Q}}_m$. \square

In what follows, we shall fix a sequence $\{q_i\}_{1 \leq i < \infty}$ be a sequence of meromorphic quadratic differentials in $\hat{\mathcal{Q}}_m(\Sigma)$ as in Criterion 1 above, together with a coordinate neighborhood U around the pole p . In what follows, we shall implicitly identify U with the disk \mathbb{D} in z -coordinates.

Lemma A.2 (Criterion 2). *Let there exist a fixed meromorphic quadratic differential q_0 in \mathbb{C} with a pole of order k , and a sequence of univalent conformal maps $f_i : (U, z) \rightarrow (\mathbb{C}, 0)$ where $i \geq 1$ such that the restriction of q_i to U is the pullback of q_0 via f_i . Moreover, assume that there is a uniform bound on the derivatives:*

$$(44) \quad c < |f'_i(0)| < C$$

for all i , for some fixed reals c, C .

Then $q_i \rightarrow q \in \hat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.

Proof. One applies Criterion 1: it is a standard fact that the derivative bound (44) implies that the family of univalent maps is normal, and so are the local expressions of the pullback differentials. Moreover, by Lemma 3.8 and the lower bound on the derivatives above, the leading order term (coefficient of $1/z^n$) does not vanish in the limit, and hence the limiting differential q has the pole of correct order. \square

As in §3.3 a planar end \mathcal{P}_H can be thought of as the restriction of a “standard” holomorphic quadratic differential on \mathbb{C} to a neighborhood of ∞ , or by inversion, the restriction of a meromorphic quadratic differential on \mathbb{C} (see (6)), to a neighborhood U_H of the pole at 0. Note that the neighborhoods U_H shrink down to 0, at a controlled rate (Lemma 3.4).

In what follows, we shall consider, as earlier in the paper, a sequence $H_i \rightarrow \infty$ such that

$$(45) \quad \text{dist}(0, \partial U_{H_i}) = O(r_i)$$

where $r_i = 2^{-i}$ (see Lemma 7.4).

Lemma A.3 (Criterion 3). *Let there be the same setup as in Criterion 2, except that instead of a derivative bound (44) we have that f_i maps the disk $B_{r_i} = \{z \in U \mid |z| \leq r_i\}$ to U_{H_i} for the sequence $H_i \rightarrow \infty$. Then $q_i \rightarrow q \in \hat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.*

Proof. One only needs to prove the derivative bound (44) and apply Criterion 2. Recall the following growth theorem concerning a univalent conformal map $f : \mathbb{D} \rightarrow \mathbb{C}$ such that $f(0) = 0$ (see, for example, Theorem 1.3 of [Pom]):

$$|f'(0)| \frac{|z|}{(1 + |z|)^2} \leq |f(z)| \leq |f'(0)| \frac{|z|}{(1 - |z|)^2}$$

Applying this to $f = f_i$, and $|z| = r_i$, we obtain from (45) that $|f(z)| = O(r_i)$ and the required bounds on $|f'_i(0)|$ follow. \square

Lemma A.4 (Criterion 4). *Let there be the same setup as in Criterion 3, except that instead of f_i mapping B_{r_i} to U_{H_i} , it maps some simply connected set V_i containing 0 to U_{H_i} , where*

$$(46) \quad dr_i \leq \text{dist}(0, \partial V_i) \leq Dr_i$$

for each $i \geq 1$ and some fixed reals d, D . (Here $\text{dist}(0, \partial U_{H_i}) = r_i$ as before.)

Then $q_i \rightarrow q \in \hat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.

Proof. As in the proof of the previous criterion, it shall suffice to show uniform derivative bounds of f_i at 0.

For any conformal map $f : \mathbb{D} \rightarrow \mathbb{C}$ the following holds for any $z \in \mathbb{D}$ (see Corollary 1.4 of [Pom]):

$$\frac{1}{4} (1 - |z|^2) |f'(z)| \leq \text{dist}(f(z), \partial f(\mathbb{D})) \leq (1 - |z|^2) |f'(z)|$$

Consider the conformal map $f = \phi_i : \mathbb{D} \rightarrow V_i \subset \mathbb{C}$ that fixes 0.

In particular, for $z = 0$ we get by rearranging the above inequalities and using that $\phi_i(0) = 0$ that

$$(47) \quad \text{dist}(0, \partial f(\mathbb{D})) \leq |\phi'_i(0)| \leq 4 \text{dist}(0, \partial f(\mathbb{D}))$$

Since $\phi_i(\mathbb{D}) = V_i$ and (46) holds this gives

$$(48) \quad dr_i \leq |\phi'_i(0)| \leq 4Dr_i.$$

Now, consider the univalent conformal map $g = f_i \circ \phi_i : \mathbb{D} \rightarrow U_{H_i} \subset \mathbb{C}$. Using the assumption that $\text{dist}(0, \partial U_{H_i}) = r_i$ and the distortion estimate (47) we have by the same argument:

$$(49) \quad |g'(0)| = O(r_i)$$

But by the chain rule $g'(0) = f'_i(0) \cdot \phi'_i(0)$ so by (48) and (49) we see that $|f'_i(0)|$ have uniform bounds (independent of i), and one can apply Criterion 2. \square

Varying Σ . The previous criteria were for a fixed surface Σ . We now record a criterion, for meromorphic quadratic differentials on a sequence of surfaces converging in \mathcal{T}_g , to converge in the subset $\hat{\mathcal{Q}}_m$ of the total bundle \mathcal{Q}_m over \mathcal{T}_g consisting of meromorphic quadratic differentials of a pole of order *exactly* k .

Namely, consider a sequence of meromorphic quadratic differentials $\{q_i\}_{i \geq 1}$ on underlying surfaces $\{\Sigma_i\}_{i \geq 1}$ in \mathcal{T}_g that converge to Σ , that is, there exist $(1 + \epsilon_i)$ -quasiconformal maps $h_i : \Sigma_i \rightarrow \Sigma$ where $\epsilon_i \rightarrow 0$ as $i \rightarrow \infty$. Suppose also that there exist a neighborhood U_i of the pole of q_i such that $h_i(U_i) = U$ for the fixed disk U on Σ .

Lemma A.5 (Criterion 1'). *Assume that in the sequence just described, the restriction of q_i on U_i is, in local coordinates via a conformal identification $c_i : (U_i, p) \rightarrow (\mathbb{D}, 0)$, given by:*

$$q_i(z) = \frac{\phi_i(z)}{z^k} dz^2$$

where $\phi_i(z)$ are univalent holomorphic functions that form a normal family that converges to a holomorphic function non-vanishing at 0.

Then $q_i \rightarrow q \in \hat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.

Proof. Via the $(1 + \epsilon_i)$ -quasiconformal homeomorphisms $c_i \circ h_i^{-1}$, the functions ϕ_i can be pulled back to a family of locally integrable complex-valued functions on U . By the assumption that the $\{\phi_i\}$ are a normal family, by arguing as in the proof of Criterion 1, one shows that the pullback quadratic differentials (which are measurable, but no longer holomorphic, sections of $K_{\mathbb{C}}^{\otimes 2}$ for the Riemann surface Σ) have bounded L^2 norms on every (fixed) compact set away from p , and hence converge after passing to a subsequence. Since $\epsilon_i \rightarrow 0$, away from p the limiting quadratic differential is weakly holomorphic, and hence by Weyl's Lemma, holomorphic. By the condition that the limit of ϕ_i is non-vanishing at 0, the quadratic differential has a pole of order k at p . \square

The above lemma implies that appropriate versions of Criteria 2, 3 and 4 also hold for the case when the underlying Riemann surfaces vary and form a converging sequence. In particular, we have:

Lemma A.6 (Criterion 4'). *Assume that in the sequence just described, the restriction of q_i on U_i is the pullback by a univalent conformal map $f_i : U_i \rightarrow \mathbb{C}$ of a fixed meromorphic quadratic differential q_0 on \mathbb{C} . Moreover, f_i maps the subdomain $V_i \subset U_i$ to $U_{H_i} \subset \mathbb{C}$, where*

$$\text{dist}(0, \partial U_{H_i}) = r_i$$

and V_i satisfies the uniform distance bounds

$$dr_i \leq \text{dist}(0, \partial V_i) \leq Dr_i$$

as in (46). (Here $d, D > 0$ are some constants independent of i .)

Then $q_i \rightarrow q \in \hat{\mathcal{Q}}_m(\Sigma)$ after passing to a subsequence.

The above lemma is summarized as Lemma 9.1 in §9, and used in the proof of Proposition 9.3.

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