

# Introduction to the Calculus of Variations: Lecture 9

Swarnendu Sil

Department of Mathematics  
Indian Institute of Science

Spring Semester 2021

## Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first encounter with Sobolev spaces

Existence of geodesics

Regularity questions

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem.

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**,

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**.

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here,

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course.



## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces**

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence**

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

### The End

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence** ( this will return and stay with us from chapter 4 onwards )

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence** ( this will return and stay with us from chapter 4 onwards )
- ▶ **noncompactness due to group action and a possible way to overcome it**

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence** ( this will return and stay with us from chapter 4 onwards )
- ▶ **noncompactness due to group action and a possible way to overcome it** ( this would return when we study the area functional in the last chapter)

## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence** ( this will return and stay with us from chapter 4 onwards )
- ▶ **noncompactness due to group action and a possible way to overcome it** ( this would return when we study the area functional in the last chapter)
- ▶ **regularity questions**

### Prelude to Direct Methods

Geodesics: the problem

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End



## Direct methods in a classical problem

Now we intend to give a brief illustration of direct methods in a classical problem. We intend to study a problem that we have referred to a few times already, the problem of finding **geodesics**, i.e. **curves of 'shortest' length between two given points on a manifold**.

However, we are going to solve the problem using the **direct methods**. Although the setting is decidedly simpler here, but we would already see a remarkable number of features that would remain with us in different guises and would keep us busy till the end of the course. Roughly, these are the following.

- ▶ **Sobolev spaces** ( we would see a baby version here and this would stay with us from chapter 3 onwards)
- ▶ **direct methods for existence** ( this will return and stay with us from chapter 4 onwards )
- ▶ **noncompactness due to group action and a possible way to overcome it** ( this would return when we study the area functional in the last chapter)
- ▶ **regularity questions** ( we shall take it up again the chapter 5)

## The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ .

## The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ .  
Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ .

## The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ .  
Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ .

## The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

### The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

$$c(0) = p_1 \quad \text{and} \quad c(T) = p_2.$$

## The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

$$c(0) = p_1 \quad \text{and} \quad c(T) = p_2.$$

The length of the curve is

$$L(c) := \int_0^T |\dot{c}(t)| \, dt.$$

### The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

$$c(0) = p_1 \quad \text{and} \quad c(T) = p_2.$$

The length of the curve is

$$L(c) := \int_0^T |\dot{c}(t)| \, dt.$$

Our aim is to find a curve connecting  $p_1$  and  $p_2$  which has the shortest length.



### The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

$$c(0) = p_1 \quad \text{and} \quad c(T) = p_2.$$

The length of the curve is

$$L(c) := \int_0^T |\dot{c}(t)| \, dt.$$

Our aim is to find a curve connecting  $p_1$  and  $p_2$  which has the shortest length.

So our first try for the variational problem is

### The variational problem for geodesics

Let  $M$  be an  $N$ -dimensional smooth embedded submanifold of  $\mathbb{R}^d$ . Let  $c \in C^1([0, T]; M)$  be a  $C^1$  curve on  $M$ . Let  $p_1, p_2 \in M$  be two distinct points on  $M$ . We suppose that the curve begins at  $p_1$  and ends at  $p_2$ , which translates to

$$c(0) = p_1 \quad \text{and} \quad c(T) = p_2.$$

The length of the curve is

$$L(c) := \int_0^T |\dot{c}(t)| \, dt.$$

Our aim is to find a curve connecting  $p_1$  and  $p_2$  which has the shortest length.

So our first try for the variational problem is

$$\inf \{ L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2. \} = m.$$

But clearly this can not be the variational problem.

## Geodesic: setting of the problem

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever!

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ).

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length.

## Geodesic: setting of the problem

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ .



## Geodesic: setting of the problem

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ . ( Think of  $M$  as the  $N$ -sphere  $\mathbb{S}^N$  in  $\mathbb{R}^{N+1}$ . )

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ . ( Think of  $M$  as the  $N$ -sphere  $\mathbb{S}^N$  in  $\mathbb{R}^{N+1}$ . )

Now there are two ways we can bring  $M$  into the picture.

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ . ( Think of  $M$  as the  $N$ -sphere  $\mathbb{S}^N$  in  $\mathbb{R}^{N+1}$ . )

Now there are two ways we can bring  $M$  into the picture. One is if  $M$  is given by some equations

$$M = \{x \in \mathbb{R}^d : G_\alpha(x) = 0 \text{ for all } \alpha \in \mathcal{I}\},$$

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ . ( Think of  $M$  as the  $N$ -sphere  $\mathbb{S}^N$  in  $\mathbb{R}^{N+1}$ . )

Now there are two ways we can bring  $M$  into the picture. One is if  $M$  is given by some equations

$$M = \{x \in \mathbb{R}^d : G_\alpha(x) = 0 \text{ for all } \alpha \in \mathcal{I}\},$$

then we can treat this as a variational problem with additional constraints

$$G_\alpha(c(t)) = 0 \quad \text{for all } \alpha \in \mathcal{I}.$$

But clearly this can not be the variational problem. It has no reference to  $M$  whatsoever! In fact, we already know the solution to the above variational problem ( though it is quite tricky proving it this way! ). The straight line in  $\mathbb{R}^d$  joining the points  $p_1$  and  $p_2$  is the unique path of shortest length. This path has no reason to lie in  $M$ . ( Think of  $M$  as the  $N$ -sphere  $\mathbb{S}^N$  in  $\mathbb{R}^{N+1}$ . )

Now there are two ways we can bring  $M$  into the picture. One is if  $M$  is given by some equations

$$M = \{x \in \mathbb{R}^d : G_\alpha(x) = 0 \text{ for all } \alpha \in \mathcal{I}\},$$

then we can treat this as a variational problem with additional constraints

$$G_\alpha(c(t)) = 0 \quad \text{for all } \alpha \in \mathcal{I}.$$

However, here we shall not take this path and instead introduce local charts in  $M$ .

## Local charts

Let  $p \in M$ .

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  
 $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that



## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  
 $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  
 $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism,

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart,

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ ,

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ , there exists a curve  $\gamma$  in  $U$



## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ , there exists a curve  $\gamma$  in  $U$  such that

$$c(t) = f(\gamma(t)) \quad \text{for every } t \in [0, T].$$

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ , there exists a curve  $\gamma$  in  $U$  such that

$$c(t) = f(\gamma(t)) \quad \text{for every } t \in [0, T].$$

$\gamma$  is also  $C^1$  if  $c$  is

## Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ , there exists a curve  $\gamma$  in  $U$  such that

$$c(t) = f(\gamma(t)) \quad \text{for every } t \in [0, T].$$

$\gamma$  is also  $C^1$  if  $c$  is and by the chain rule, we have

### Local charts

Let  $p \in M$ . A local chart around  $p$  is a map  $f : U \subset \mathbb{R}^N \rightarrow V \subset \mathbb{R}^d$  such that

- ▶  $U, V$  are open sets in the respective Euclidean spaces,
- ▶  $f(U) = M \cap V$ ,
- ▶  $p \in f(U)$  and
- ▶  $f$  is a smooth diffeomorphism onto its image.

Now since  $f$  is a diffeomorphism, for any curve  $c(t)$  which is contained inside a single chart, i.e.  $c([0, T]) \subset f(U)$ , there exists a curve  $\gamma$  in  $U$  such that

$$c(t) = f(\gamma(t)) \quad \text{for every } t \in [0, T].$$

$\gamma$  is also  $C^1$  if  $c$  is and by the chain rule, we have

$$\dot{c}(t) = Df(\gamma(t)) \dot{\gamma}(t).$$

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ).

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus



### Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^\alpha}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

### Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^\alpha}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite**

### Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^\alpha}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite symmetric**

### Length and the Metric tensor

$$c^{\dot{\alpha}}(t) = \frac{\partial f^{\alpha}}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^{\alpha}}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^{\alpha}}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite symmetric** matrix

### Length and the Metric tensor

$$c^{\dot{\alpha}}(t) = \frac{\partial f^{\alpha}}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^{\alpha}}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^{\alpha}}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite symmetric** matrix

$$g_{ij}(z) = \frac{\partial f^{\alpha}}{\partial z^i}(z) \frac{\partial f^{\alpha}}{\partial z^j}(z),$$

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^\alpha}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite symmetric** matrix

$$g_{ij}(z) = \frac{\partial f^\alpha}{\partial z^i}(z) \frac{\partial f^\alpha}{\partial z^j}(z),$$

the **metric tensor** of  $M$

## Length and the Metric tensor

$$\dot{c}^\alpha(t) = \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \quad \text{for every } 1 \leq \alpha \leq d.$$

Here we used the Einstein summation convention ( i.e. repeated index, here  $i$ , is to be summed over, here from 1 to  $N$  ). Thus

$$\begin{aligned} L(c) &= \int_0^T \left( \frac{\partial f^\alpha}{\partial z^i}(\gamma(t)) \dot{\gamma}^i(t) \frac{\partial f^\alpha}{\partial z^j}(\gamma(t)) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \\ &= \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt, \end{aligned}$$

where  $g = (g_{ij})$  is a **positive definite symmetric** matrix

$$g_{ij}(z) = \frac{\partial f^\alpha}{\partial z^i}(z) \frac{\partial f^\alpha}{\partial z^j}(z),$$

the **metric tensor** of  $M$  with respect to the chart  $f : U \rightarrow V$ .

# Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity.



# Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$

# Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas).

# Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ ,

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals.

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen.



## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not.

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ ,

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ , then one can check we have

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ , then one can check we have

$$\int_0^T \left( g_{ij}^1(\gamma_1(t)) \dot{\gamma}_1^i(t) \dot{\gamma}_1^j(t) \right)^{\frac{1}{2}} dt = \int_0^T \left( g_{ij}^2(\gamma_2(t)) \dot{\gamma}_2^i(t) \dot{\gamma}_2^j(t) \right)^{\frac{1}{2}} dt,$$

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ , then one can check we have

$$\int_0^T \left( g_{ij}^1(\gamma_1(t)) \dot{\gamma}_1^i(t) \dot{\gamma}_1^j(t) \right)^{\frac{1}{2}} dt = \int_0^T \left( g_{ij}^2(\gamma_2(t)) \dot{\gamma}_2^i(t) \dot{\gamma}_2^j(t) \right)^{\frac{1}{2}} dt,$$

where

$$f_1 \circ \gamma_1 = c = f_2 \circ \gamma_2.$$

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ , then one can check we have

$$\int_0^T \left( g_{ij}^1(\gamma_1(t)) \dot{\gamma}_1^i(t) \dot{\gamma}_1^j(t) \right)^{\frac{1}{2}} dt = \int_0^T \left( g_{ij}^2(\gamma_2(t)) \dot{\gamma}_2^i(t) \dot{\gamma}_2^j(t) \right)^{\frac{1}{2}} dt,$$

where

$$f_1 \circ \gamma_1 = c = f_2 \circ \gamma_2.$$

The diffeomorphism

$$f_2^{-1} \circ f_1 : f_1^{-1}(f_1(U_1) \cap f_2(U_2)) \rightarrow f_2^{-1}(f_1(U_1) \cap f_2(U_2))$$

## Chart overlaps, transition functions and the length of curves

We shall always work with the simplifying assumption that the curve is contained in a single chart just for clarity. In general, a manifold would be covered by a collection of charts  $\{(f_\beta, U_\beta)\}_\beta$  (called an atlas). Given a curve  $c$  on  $M$ , we can always find a partition

$$0 = t_0 < t_1 < \dots < t_r < T$$

such that  $c([t_k, t_{k+1}])$  is contained in a single chart and then we would write the length functional as sum of the integrals. It might appear that the length of a curve depends on the chart chosen. But it does not. If  $c(0, T) \subset f_1(U_1) \cap f_2(U_2)$ , then one can check we have

$$\int_0^T \left( g_{ij}^1(\gamma_1(t)) \dot{\gamma}_1^i(t) \dot{\gamma}_1^j(t) \right)^{\frac{1}{2}} dt = \int_0^T \left( g_{ij}^2(\gamma_2(t)) \dot{\gamma}_2^i(t) \dot{\gamma}_2^j(t) \right)^{\frac{1}{2}} dt,$$

where

$$f_1 \circ \gamma_1 = c = f_2 \circ \gamma_2.$$

The diffeomorphism

$$f_2^{-1} \circ f_1 : f_1^{-1}(f_1(U_1) \cap f_2(U_2)) \rightarrow f_2^{-1}(f_1(U_1) \cap f_2(U_2))$$

is called a **transition map**.

# The variational problem

Now our variational problem is

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End



# The variational problem

Now our variational problem is

$$\inf_{\gamma \in X} \left\{ \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \right\} = m.$$

Now our variational problem is

$$\inf_{\gamma \in X} \left\{ \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \right\} = m.$$

where

$$X = \{ \gamma \in C^1([0, T]; U) : \gamma(0) = f^{-1}(p_1), \gamma(T) = f^{-1}(p_2) \}.$$

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics  
Regularity questions

The End

Now our variational problem is

$$\inf_{\gamma \in X} \left\{ \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \right\} = m.$$

where

$$X = \{ \gamma \in C^1([0, T]; U) : \gamma(0) = f^{-1}(p_1), \gamma(T) = f^{-1}(p_2) \}.$$

Now we attempt to solve it via direct methods.

Now our variational problem is

$$\inf_{\gamma \in X} \left\{ \int_0^T \left( g_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t) \right)^{\frac{1}{2}} dt \right\} = m.$$

where

$$X = \{ \gamma \in C^1([0, T]; U) : \gamma(0) = f^{-1}(p_1), \gamma(T) = f^{-1}(p_2) \}.$$

Now we attempt to solve it via direct methods.

But it is a quite difficult one and we need to slowly move towards it.

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{ L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2. \} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima,



To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence,

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{ L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2. \} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

we deduce

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

we deduce

$$\|\dot{c}_\nu\|_{L^1([0, T])} := \int_0^T |\dot{c}_\nu(t)| dt \leq m + 1.$$

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

we deduce

$$\|\dot{c}_\nu\|_{L^1([0, T])} := \int_0^T |\dot{c}_\nu(t)| dt \leq m + 1.$$

Now we see one of the first difficulties.

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

we deduce

$$\|\dot{c}_\nu\|_{L^1([0, T])} := \int_0^T |\dot{c}_\nu(t)| dt \leq m + 1.$$

Now we see one of the first difficulties. We obtained an **uniform bound for the  $L^1$  norm of the derivatives**

To understand at least some of the difficulties of the problem, we first try to solve the simpler problem

$$\inf \{L(c) : c \in C^1([0, T]; \mathbb{R}^d), c(0) = p_1, c(T) = p_2.\} = m.$$

This is just the first problem we wrote down today.

Now, as we did in the case of finding a minima, if  $\{c_\nu\}$  is a minimizing sequence, i.e.

$$L(c_\nu) = \int_0^T |\dot{c}_\nu(t)| dt \rightarrow m,$$

we deduce

$$\|\dot{c}_\nu\|_{L^1([0, T])} := \int_0^T |\dot{c}_\nu(t)| dt \leq m + 1.$$

Now we see one of the first difficulties. We obtained an **uniform bound for the  $L^1$  norm of the derivatives** and **not the  $C^0$  norm of the derivatives**.

# Difficulties

So we realize that

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End



## Difficulties

So we realize that  $C^1$  is a terrible class from the point of view of direct methods.

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

## Difficulties

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for.

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more.

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

and

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

and

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right| \leq \int_s^t |\dot{c}_\nu(t)| dt.$$



So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

and

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right| \leq \int_s^t |\dot{c}_\nu(t)| dt.$$

So at least the  $C^0$  norm of the minimizing sequences are uniformly bounded.

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

and

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right| \leq \int_s^t |\dot{c}_\nu(t)| dt.$$

So at least the  $C^0$  norm of the minimizing sequences are uniformly bounded. However, this is not good enough for extracting a convergent sequence.

So we realize that  $C^1$  is a terrible class from the point of view of direct methods. From integral functionals, uniform bounds for some integral norms of the derivatives are the best we can hope for. So, minimizing sequences would never be uniformly bounded in the  $C^1$  norm!

However, we push ahead a bit more. Using the fundamental theorem of calculus, we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \leq |p_1| + \|\dot{c}_\nu\|_{L^1([0, T])} \leq |p_1| + m + 1,$$

and

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right| \leq \int_s^t |\dot{c}_\nu(t)| dt.$$

So at least the  $C^0$  norm of the minimizing sequences are uniformly bounded. However, this is not good enough for extracting a convergent sequence. ( Thus showing  $C^0$  is an equally bad space as  $C^1$  ).

But we were very close.

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

But we were very close. By virtue of the Ascoli-Arzelà theorem,

But we were very close. By virtue of the Ascoli-Arzela theorem, all we needed for compactness is **equicontinuity**,

Prelude to Direct  
Methods

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics  
Regularity questions

The End

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$



But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

From the second inequality, this would be the case if we can conclude

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

From the second inequality, this would be the case if we can conclude

$$\int_s^t |\dot{c}_\nu(t)| \, dt \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

From the second inequality, this would be the case if we can conclude

$$\int_s^t |\dot{c}_\nu(t)| \, dt \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

This property is called **equiintegrability**.

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

From the second inequality, this would be the case if we can conclude

$$\int_s^t |\dot{c}_\nu(t)| \, dt \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

This property is called **equiintegrability**. Unfortunately, a sequence which is uniformly bounded in  $L^1$  need not be equiintegrable,

But we were very close. By virtue of the Ascoli-Arzelà theorem, all we needed for compactness is **equicontinuity**, i.e.

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

From the second inequality, this would be the case if we can conclude

$$\int_s^t |\dot{c}_\nu(t)| dt \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

This property is called **equiintegrability**. Unfortunately, a **sequence which is uniformly bounded in  $L^1$  need not be equiintegrable**, showing  $L^1$  is not a particularly nice space either.

# An easier problem

Let us now make our life a bit easier and try to solve the variational problem

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$



## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$

Arguing as before,

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$

Arguing as before, for a minimizing sequence  $\{c_\nu\}$ ,

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$

Arguing as before, for a minimizing sequence  $\{c_\nu\}$ , we now have

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$

Arguing as before, for a minimizing sequence  $\{c_\nu\}$ , we now have

$$E(c_\nu) = \|\dot{c}_\nu\|_{L^2([0, T])}^2 \leq m + 1.$$

## An easier problem

Let us now make our life a bit easier and try to solve the variational problem

$$\inf_{c \in X} \left\{ E(c) = \int_0^T |\dot{c}(t)|^2 dt \right\} = m,$$

where

$$X = \{c \in C^1([0, T]; \mathbb{R}^d) : c(0) = p_1, c(T) = p_2\}.$$

Arguing as before, for a minimizing sequence  $\{c_\nu\}$ , we now have

$$E(c_\nu) = \|\dot{c}_\nu\|_{L^2([0, T])}^2 \leq m + 1.$$

But this time we have a control of the  $L^2$  norm of the derivatives instead of the  $L^1$  norm.

Using the fundamental theorem of calculus once again,

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

Using the fundamental theorem of calculus once again, this time we obtain

Using the fundamental theorem of calculus once again, this time we obtain

$$|c_\nu(t)| \leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right|$$



Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{H\"older}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \end{aligned}$$

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ .

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right|$$

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$|c_\nu(t) - c_\nu(s)| = \left| \int_s^t \dot{c}_\nu(t) dt \right| \stackrel{\text{Hölder}}{\leq} \sqrt{(t-s)} \left( \int_s^t |\dot{c}_\nu(t)|^2 dt \right)^{\frac{1}{2}}$$

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$\begin{aligned} |c_\nu(t) - c_\nu(s)| &= \left| \int_s^t \dot{c}_\nu(t) dt \right| \stackrel{\text{Hölder}}{\leq} \sqrt{(t-s)} \left( \int_s^t |\dot{c}_\nu(t)|^2 dt \right)^{\frac{1}{2}} \\ &\leq \sqrt{(t-s)} \|\dot{c}_\nu\|_{L^2([0, T])} \end{aligned}$$

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$\begin{aligned} |c_\nu(t) - c_\nu(s)| &= \left| \int_s^t \dot{c}_\nu(t) dt \right| \stackrel{\text{Hölder}}{\leq} \sqrt{(t-s)} \left( \int_s^t |\dot{c}_\nu(t)|^2 dt \right)^{\frac{1}{2}} \\ &\leq \sqrt{(t-s)} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq \sqrt{(t-s)} \sqrt{m+1}. \end{aligned}$$



Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$\begin{aligned} |c_\nu(t) - c_\nu(s)| &= \left| \int_s^t \dot{c}_\nu(t) dt \right| \stackrel{\text{Hölder}}{\leq} \sqrt{(t-s)} \left( \int_s^t |\dot{c}_\nu(t)|^2 dt \right)^{\frac{1}{2}} \\ &\leq \sqrt{(t-s)} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq \sqrt{(t-s)} \sqrt{m+1}. \end{aligned}$$

Thus,

Using the fundamental theorem of calculus once again, this time we obtain

$$\begin{aligned} |c_\nu(t)| &\leq |c_\nu(0)| + \left| \int_0^t \dot{c}_\nu(t) dt \right| \\ &\stackrel{\text{Hölder}}{\leq} |p_1| + \sqrt{t} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq |p_1| + \sqrt{t} \sqrt{m+1}. \end{aligned}$$

Thus  $\{c_\nu\}$  is uniformly bounded in  $C^0$ . Now we have,

$$\begin{aligned} |c_\nu(t) - c_\nu(s)| &= \left| \int_s^t \dot{c}_\nu(t) dt \right| \stackrel{\text{Hölder}}{\leq} \sqrt{(t-s)} \left( \int_s^t |\dot{c}_\nu(t)|^2 dt \right)^{\frac{1}{2}} \\ &\leq \sqrt{(t-s)} \|\dot{c}_\nu\|_{L^2([0, T])} \\ &\leq \sqrt{(t-s)} \sqrt{m+1}. \end{aligned}$$

Thus,

$$|c_\nu(t) - c_\nu(s)| \rightarrow 0 \quad \text{uniformly in } \nu \quad \text{as } t - s \rightarrow 0.$$

Hence by Ascoli-Arzela theorem,

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

Hence by Ascoli-Arzelà theorem, we deduce that

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled,

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ .



Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ ,

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space,

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \tag{1}$$

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \tag{1}$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ .

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \quad (1)$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ . Is there a relation between  $v$  and  $c$ ?



Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \quad (1)$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ . Is there a relation between  $v$  and  $c$ ? In particular, is  $v = \dot{c}$ ?

## Compactness in $C^0$

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \tag{1}$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ . Is there a relation between  $v$  and  $c$ ? In particular, is  $v = \dot{c}$ ?

Note that (1) implies for any  $\psi \in C_c^\infty([0, T]; \mathbb{R}^d)$ ,

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \quad (1)$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ . Is there a relation between  $v$  and  $c$ ? In particular, is  $v = \dot{c}$ ?

Note that (1) implies for any  $\psi \in C_c^\infty([0, T]; \mathbb{R}^d)$ , we have

Hence by Ascoli-Arzelà theorem, we deduce that up to the extraction of a subsequence which is not relabelled, we obtain

$$c_\nu \rightarrow c \quad \text{in } C^0,$$

for some  $c \in C^0([0, T]; \mathbb{R}^d)$ . Unfortunately, this tells us nothing about the derivatives of  $c$ .

$c$  might not even be differentiable, let alone being  $C^1$ .

However, since  $\{\dot{c}_\nu\}$  is uniformly bounded in  $L^2$ , which unlike  $L^1$ , is a reflexive space, we deduce, by Banach-Alaoglu theorem

$$\dot{c}_\nu \rightharpoonup v \quad \text{in } L^2, \quad (1)$$

for some  $v \in L^2([0, T]; \mathbb{R}^d)$ . Is there a relation between  $v$  and  $c$ ? In particular, is  $v = \dot{c}$ ?

Note that (1) implies for any  $\psi \in C_c^\infty([0, T]; \mathbb{R}^d)$ , we have

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle \rightarrow \int_0^T \langle v, \psi \rangle. \quad (2)$$

But integrating by parts, we obtain

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ ,

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to



But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3),

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle c, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle c, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

$v$  certainly looks way too much like  $\dot{c}$ !!

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle c, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

$v$  certainly looks way too much like  $\dot{c}$ !! Indeed, if we knew  $c$  is  $C^1$ ,

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle c, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

$v$  certainly looks way too much like  $\dot{c}$ ! Indeed, if we knew  $c$  is  $C^1$ , the above formula would indeed tell us  $v = \dot{c}$

But integrating by parts, we obtain

$$\int_0^T \langle \dot{c}_\nu, \psi \rangle = - \int_0^T \langle c_\nu, \dot{\psi} \rangle. \quad (3)$$

By convergence of  $c_\nu$  to  $c$  in  $C^0$ , the RHS above converges to

$$- \int_0^T \langle c_\nu, \dot{\psi} \rangle \rightarrow - \int_0^T \langle c, \dot{\psi} \rangle.$$

So, using this and (1) and (2) and (3), we deduce

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle c, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

$v$  certainly looks way too much like  $\dot{c}$ ! Indeed, if we knew  $c$  is  $C^1$ , the above formula would indeed tell us  $v = \dot{c}$  using integration by parts and the fundamental lemma of calculus of variations.



## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ .

**Geodesics: the problem**

Absolute continuity: first  
encounter with Sobolev  
spaces

Existence of geodesics

Regularity questions

The End

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable.

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ ,

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves,

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that



## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !**

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !!** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

### Definition (weak derivatives)

Let  $u \in L^1([0, T]; \mathbb{R}^d)$ .

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

### Definition (weak derivatives)

Let  $u \in L^1([0, T]; \mathbb{R}^d)$ . We say  $u$  has a **weak derivative**

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !!** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

### Definition (weak derivatives)

Let  $u \in L^1([0, T]; \mathbb{R}^d)$ . We say  $u$  has a **weak derivative** if there exists a function  $v \in L^1([0, T]; \mathbb{R}^d)$

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !!** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

### Definition (weak derivatives)

Let  $u \in L^1([0, T]; \mathbb{R}^d)$ . We say  $u$  has a **weak derivative** if there exists a function  $v \in L^1([0, T]; \mathbb{R}^d)$  such that

## Idea of weak derivatives

Unfortunately, we have no way of knowing at this point that  $c$  is  $C^1$ . As we said, for all we know,  $c$  need not even be differentiable. However, since  $v \in L^2$ , the above formula suggests that probably instead of  $C^1$  curves, we should look for 'curves' with  $L^2$  'derivatives'.

But how can a function which might not be differentiable have a 'derivative'??

The last bit of inspired idea that we need is that **we need to outrageously bold and simply call  $v$  as a 'derivative' of  $c$ !!** This seemingly insane idea is the beginning of modern theory of PDEs and Calculus of Variations.

### Definition (weak derivatives)

Let  $u \in L^1([0, T]; \mathbb{R}^d)$ . We say  $u$  has a **weak derivative** if there exists a function  $v \in L^1([0, T]; \mathbb{R}^d)$  such that

$$\int_0^T \langle v, \psi \rangle = - \int_0^T \langle u, \dot{\psi} \rangle \quad \text{for any } \psi \in C_c^\infty([0, T]; \mathbb{R}^d).$$

**Thank you**  
*Questions?*