# Introduction to the Calculus of Variations: Lecture 6 

## Classical Methods

Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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Spring Semester 2021

## Outline

## Classical Methods

Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples

Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

## Recap I

We calculated the second variation of a functional.
Theorem (Second Variation)

$$
\begin{aligned}
& \text { Let } f=f(t, u, \xi) \in C^{3}\left([a, b] \times \mathbb{R}^{N} \times \mathbb{R}^{N}\right), \alpha, \beta \in \mathbb{R}^{N}, \\
& X=\left\{u \in C^{1}\left([a, b] ; \mathbb{R}^{N}\right): u(a)=\alpha, u(b)=\beta\right\} .
\end{aligned}
$$

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

> Second Variation

> Examples

$$
\text { (P) } \quad \inf _{u \in X}\left\{I(u)=\int_{a}^{b} f(t, u(t), \dot{u}(t)) \mathrm{d} t\right\}=m
$$

For any minimizer $\bar{u} \in X \cap C^{2}$ for $(P)$, the integral

$$
\int_{a}^{b}\left[\left\langle f_{u u}(t, \bar{u}, \dot{\bar{u}}) \psi, \psi\right\rangle+2\left\langle f_{u \xi}(t, \bar{u}, \dot{\bar{u}}) \psi, \dot{\psi}\right\rangle+\left\langle f_{\xi \xi}(t, \bar{u}, \dot{\bar{u}}) \dot{\psi}, \dot{\psi}\right\rangle\right] \mathrm{d} t
$$

is nonnegative for any $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$.

## Recap II

We have also rewritten the integral as

## Classical Methods

Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

$\int_{a}^{b}\left[\left\langle\left[f_{u u}(t, \bar{u}, \dot{\bar{u}})-\frac{d}{d t} f_{u \xi}(t, \bar{u}, \dot{\bar{u}})\right] \psi, \psi\right\rangle+\left\langle f_{\xi \xi}(t, \bar{u}, \dot{\bar{u}}) \dot{\psi}, \dot{\psi}\right\rangle\right] \mathrm{d} t$
Now we want to show that for this expression to be nonnegative for every $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$, $f_{\xi \xi}$ must be nonnegative definite everywhere.

## Dominant term in the second variation I

Introduction to the Calculus of Variations

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Classical Methods
Classical Problem
Euler-Lagrange Equations Hamiltonian formulation First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

## Dominant term in the second variation I

Introduction to the Calculus of Variations

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Lemma

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

## Dominant term in the second variation I

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Lemma
If the following inequality

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

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## Lemma

If the following inequality

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\begin{array}{r}
\int_{a}^{b}\left[\left\langle\left[f_{u u}(t, \bar{u}, \dot{\bar{u}})-\frac{d}{d t} f_{u \xi}(t, \bar{u}, \dot{\bar{u}})\right] \psi, \psi\right\rangle+\left\langle f_{\xi \xi}(t, \bar{u}, \dot{\bar{u}}) \dot{\psi}, \dot{\psi}\right\rangle\right] \\
\geq 0,
\end{array}
$$

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals

Second Variation
Examples
The End

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals $\mathrm{d} t$

Second Variation
Examples
The End
holds for every $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$,

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals $\mathrm{d} t$

Second Variation
Examples
The End
holds for every $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$, then the matrix $f_{\xi \xi}(t, \bar{u}, \dot{\bar{u}})$

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holds for every $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$, then the matrix $f_{\xi \xi}(t, \bar{u}, \dot{\bar{u}})$ is nonnegative definite

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals

Second Variation
Examples
The End

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Proof. If $f_{\xi \xi}<0$ for some $t_{0} \in(a, b)$,

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals


Second Variation
Examples
The End

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals

## $\mathrm{d} t$

Second Variation
Examples
The End

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Proof. If $f_{\xi \xi}<0$ for some $t_{0} \in(a, b)$, this means there exist a $\zeta \in \mathbb{R}^{N}$ and $\beta>0$

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals


Second Variation
Examples
The End

## Dominant term in the second variation I

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\left\langle f_{\xi \xi}\left(t_{0}, \bar{u}\left(t_{0}\right), \dot{\bar{u}}\left(t_{0}\right)\right) \zeta, \zeta\right\rangle<-\beta .
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By continuity of $f_{\xi \xi}$,

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals

## $\mathrm{d} t$

Second Variation
Examples
The End

## Dominant term in the second variation I

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By continuity of $f_{\xi \xi}$, we can assume there exists $\alpha>0$

## Dominant term in the second variation I

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By continuity of $f_{\xi \xi}$, we can assume there exists $\alpha>0$ such that $a<t_{0}-\alpha<t_{0}+\alpha<b$ and we have

## Dominant term in the second variation I

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By continuity of $f_{\xi \xi}$, we can assume there exists $\alpha>0$ such that $a<t_{0}-\alpha<t_{0}+\alpha<b$ and we have

$$
\left\langle f_{\xi \xi}(t, \bar{u}(t), \dot{\bar{u}}(t)) \zeta, \zeta\right\rangle<-\beta \quad \text { for all } t \in\left[t_{0}-\alpha, t_{0}+\alpha\right] .
$$

## Dominant term in the second variation II

Choose

Classical Methods
Classical Problem
Euler-Lagrange Equations Hamiltonian formulation First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

## Dominant term in the second variation II

Choose

$$
\psi(t)= \begin{cases}\alpha \sin ^{2}\left[\frac{\pi\left(t-t_{0}\right)}{\alpha}\right] \zeta & \text { if } t \in\left[t_{0}-\alpha, t_{0}+\alpha\right] \\ 0 & \text { otherwise }\end{cases}
$$

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Clearly $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations

## Second Variation

Examples

## Dominant term in the second variation II

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples

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$$

Clearly $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$ and plugging it, we obtain
$\pi^{2} \int_{t_{0}-\alpha}^{t_{0}+\alpha} \sin ^{2}\left[\frac{2 \pi\left(t-t_{0}\right)}{\alpha}\right]\left\langle f_{\xi \xi}(t, \bar{u}(t), \dot{\bar{u}}(t)) \zeta, \zeta\right\rangle \mathrm{d} t$

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Clearly $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$ and plugging it, we obtain

$$
\begin{aligned}
& \pi^{2} \int_{t_{0}-\alpha}^{t_{0}+\alpha} \sin ^{2}\left[\frac{2 \pi\left(t-t_{0}\right)}{\alpha}\right]\left\langle f_{\xi \xi}(t, \bar{u}(t), \dot{\bar{u}}(t)) \zeta, \zeta\right\rangle \mathrm{d} t \\
& \quad+\alpha^{2} \int_{t_{0}-\alpha}^{t_{0}+\alpha} \sin ^{4}\left[\frac{\pi\left(t-t_{0}\right)}{\alpha}\right]\left\langle\left[f_{u u}(t, \bar{u}, \dot{\bar{u}})-\frac{d}{d t} f_{u \xi}(t, \bar{u}, \dot{\bar{u}})\right] \zeta, \zeta\right\rangle \mathrm{d} t \geq 0
\end{aligned}
$$

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\begin{aligned}
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\end{aligned}
$$

But this implies

## Dominant term in the second variation II

Choose

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& \pi^{2} \int_{t_{0}-\alpha}^{t_{0}+\alpha} \sin ^{2}\left[\frac{2 \pi\left(t-t_{0}\right)}{\alpha}\right]\left\langle f_{\xi \xi}(t, \bar{u}(t), \dot{\bar{u}}(t)) \zeta, \zeta\right\rangle \mathrm{d} t \\
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\end{aligned}
$$

But this implies

$$
2 M \alpha^{3}-2 \beta \pi^{2} \alpha \geq 0
$$

## Dominant term in the second variation II

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$$

Clearly $\psi \in C_{c}^{1}\left([a, b] ; \mathbb{R}^{N}\right)$ and plugging it, we obtain

$$
\begin{aligned}
& \pi^{2} \int_{t_{0}-\alpha}^{t_{0}+\alpha} \sin ^{2}\left[\frac{2 \pi\left(t-t_{0}\right)}{\alpha}\right]\left\langle f_{\xi \xi}(t, \bar{u}(t), \dot{\bar{u}}(t)) \zeta, \zeta\right\rangle \mathrm{d} t \\
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\end{aligned}
$$

But this implies

$$
2 M \alpha^{3}-2 \beta \pi^{2} \alpha \geq 0
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where

$$
M=\max _{t \in\left[t_{0}-\alpha, t_{0}+\alpha\right]}\left|\left\langle\left[f_{u u}(t, \bar{u}, \dot{\bar{u}})-\frac{d}{d t} f_{u \xi}(t, \bar{u}, \dot{\bar{u}})\right] \zeta, \zeta\right\rangle\right| .
$$

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

> Second Variation

> Examples

The End

## Dominant term in the second variation III

But this means

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But this means

$$
\beta \leq \frac{M}{\pi^{2}} \alpha^{2}
$$

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

## Dominant term in the second variation III

But this means

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\beta \leq \frac{M}{\pi^{2}} \alpha^{2},
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which we can easily contradict by letting $\alpha \rightarrow 0$. So we deduce

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples

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Classical Methods
Classical Problem
Euler-Lagrange Equations Hamiltonian formulation First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

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for all $a \in \mathbb{R}^{n}, b \in \mathbb{R}^{N}$ and for all $x \in \Omega$. This is weaker than the Legendre condition in that case ( convexity only along rank one matrices ).

## Towards a sufficient condition

Introduction to the Calculus of Variations

## Possible candidate for sufficiency

## Classical Methods

Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

## Towards a sufficient condition

## Possible candidate for sufficiency

Can $f_{\xi \xi} \geq 0$ be a sufficient condition?

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

## Towards a sufficient condition

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

## Towards a sufficient condition

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Can $f_{\xi \xi} \geq 0$ be a sufficient condition? Clearly not! Think of $f(x)=x^{3}$.

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

## Towards a sufficient condition

## Possible candidate for sufficiency

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

> Second Variation

Examples

## Towards a sufficient condition

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation

Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples

## Towards a sufficient condition

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation

Symmetry and Noether's theorem

## Hamilton-Jacobi equations

## Second Variation

Examples
The End

## Towards a sufficient condition

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation

Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation

Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation

Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

## Towards a sufficient condition

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## Jacobi theory and Legendre method I

We now consider the second variation itself as an integral functional

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation

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J[\psi]:=\int_{a}^{b}[\langle P \psi, \dot{\psi}\rangle+\langle Q \psi, \psi\rangle] \mathrm{d} t, \quad \psi \in C^{1}, \psi(a)=\psi(b)=0
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Note that if

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\text { for all } \psi \in C^{1}, \psi \not \equiv 0 \text { with } \psi(a)=\psi(b)=0 \text {, }
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for some $c>0$, then $\bar{u}$ is a minimizer. (Check!)

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$J[\psi]>0$ is not enough!
$P>0$ for all $t \in(a, b)$ is not enough to obtain this.

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Note that if
$J[\psi]>c \int_{a}^{b}|\psi|^{2}$, for all $\psi \in C^{1}, \psi \not \equiv 0$ with $\psi(a)=\psi(b)=0$,
for some $c>0$, then $\bar{u}$ is a minimizer. (Check!)
$J[\psi]>0$ is not enough!
$P>0$ for all $t \in(a, b)$ is not enough to obtain this. So what other condition is needed to ensure this?

## Jacobi theory and Legendre method I

We now consider the second variation itself as an integral functional

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Legendre wanted to 'complete the square' by adding a null Lagrangian.

## Jacobi theory and Legendre method II

## Legendre method

Let $W$ be an arbitrary differentiable symmetric matrix.

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

## Jacobi theory and Legendre method II

## Legendre method

Let $W$ be an arbitrary differentiable symmetric matrix. Then

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0=\int_{a}^{b} \frac{d}{d t}[\langle W \psi, \psi\rangle] \mathrm{d} t \quad \text { for all } \psi \text { with } \psi(a)=\psi(b)=0
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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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When can we make this a perfect square?

## Jacobi theory and Legendre method III

## Riccati equation

## Proposition

Suppose $W$ is a solution of the following matrix Riccati equation,

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples
The End

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## Solving the Riccati equation

Introduction to the Calculus of Variations

Swarnendu Sil

To solve the Riccati equation
Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples

## Solving the Riccati equation

 Calculus of VariationsTo solve the Riccati equation

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## Classical Methods

Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples

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However, the equation above has another nice interpretation.

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations
Second Variation
Examples

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## Jacobi equation and Jacobi fields

We again consider the second variation itself as an integral functional

Hamiltonian formulation

Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Euler-Lagrange Equations functional

Hamitonian formulation
First integrals
Symmetry and Noether's theorem
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Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
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Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
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This is called the Jacobi equation and its solutions (for a given $u$ ) is called a Jacobi field along $u$. Before proceeding further, we need the notion of conjugate points.

## Conjugate points

## Definition

Let $\Psi$ be the matrix of $N$ solutions of the Jacobi equation,

Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations

## Second Variation

Examples
The End

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Classical Methods
Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

## Second Variation

Examples
The End
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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

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Examples
The End
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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

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Examples
The End
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Classical Methods
Classical Problem
Euler-Lagrange Equations
Hamiltonian formulation
First integrals
Symmetry and Noether's theorem
Hamilton-Jacobi equations

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Examples
The End
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A point $\bar{a} \in(a, b]$

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## Classical Methods

Euler-Lagrange Equations Hamiltonian formulation

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$$

Hopefully, by now all of you can see the point. If there are no interior conjugate points to $a$, then $\Psi$ would be invertible

## Conjugate points

## Definition

Let $\Psi$ be the matrix of $N$ solutions of the Jacobi equation, i.e.

$$
\Psi:=\left(\begin{array}{l}
\psi_{1} \\
\vdots \\
\psi_{N}
\end{array}\right) .
$$

where $\psi_{1}, \ldots, \psi_{N}$ solves the Jacobi equation and satisfies

$$
\Psi(a)=0 \quad \text { and } \quad \dot{\Psi}(a)=\mathbb{I}_{N} .
$$

A point $\bar{a} \in(a, b]$ is called a conjugate to the point $a$ or simply a conjugate point of $a$ if we have

$$
\operatorname{det} \Psi(\bar{a})=0 .
$$

Hopefully, by now all of you can see the point. If there are no interior conjugate points to $a$, then $\Psi$ would be invertible and would furnish a solution to the Riccati equation.

## Thank you Questions?

## Classical Methods

Classical Problem
Euler-Lagrange Equations Hamiltonian formulation
First integrals
Symmetry and Noether's theorem

Hamilton-Jacobi equations
Second Variation
Examples
The End

