### Introduction to the Calculus of Variations

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#### **Classical Methods**

Classical Problem Euler-Lagrange Equations Hamiltonian formulation Legendre Transform Hamilton's equations First integrals Symmetry and Noether's theorem Jacobi fields Examples

# Introduction to the Calculus of Variations: Lecture 3

Swarnendu Sil

Department of Mathematics Indian Institute of Science

Spring Semester 2021

# Outline

# **Classical Methods**

Classical Problem Euler-Lagrange Equations Hamiltonian formulation Legendre Transform Hamilton's equations First integrals Symmetry and Noether's theorem Second Variation Jacobi fields Examples

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$$u\mapsto I(u):=\int_{a}^{b}f\left(t,u\left(t
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We showed that  $C^2$  stationary points satisfy the EL equations.

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$$(u,v)\mapsto J(u,v):=\int_{a}^{b}\left[\left\langle \dot{u}\left(t
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where the function  $H : [a, b] \times \mathbb{R}^N \times \mathbb{R}^N \to \mathbb{R}$  is called the **Hamiltonian** 

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$$H(x, u, v) = \sup_{\xi \in \mathbb{R}^N} \left\{ \langle v, \xi \rangle - f(x, u, \xi) \right\}.$$

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We now define the notion of duality, also known as the Legendre transform, for convex functions.

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We now define the notion of duality, also known as the Legendre transform, for convex functions. See Lecture Notes for more. We allow functions to take the value  $+\infty$ .

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Examples

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Definition (Legendre transform)
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Let  $f : \mathbb{R}^N \to \mathbb{R}$  (or  $f : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ ).

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# Definition (Legendre transform)

Let  $f : \mathbb{R}^N \to \mathbb{R}$  (or  $f : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ ).

(i) The Legendre transform, or dual, of f is the function  $f^* : \mathbb{R}^N \to \mathbb{R} \cup \{\pm \infty\}$ 

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In general, f\* takes the value +∞, even if f takes only finite values.

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• If 
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# **Theorem (Properties of Legendre Transform)** Let $f : \mathbb{R}^N \to \mathbb{R}$ (or $f : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ ).

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# **Theorem (Properties of Legendre Transform)** Let $f : \mathbb{R}^N \to \mathbb{R}$ (or $f : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ ).

(i) The function  $f^*$  is convex (even if f is not) and  $f^{***} = f^*$ .

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**Theorem (Properties of Legendre Transform)** Let  $f : \mathbb{R}^N \to \mathbb{R}$  (or  $f : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ ). (i) The function  $f^*$  is convex (even if f is not) and  $f^{***} = f^*$ . (ii) The function  $f^{**}$  is convex and  $f^{**} \leq f$ . If f is bounded below and finite but not necessarily convex, then  $f^{**}$  is its convex envelope (the largest convex function that is smaller than f) Introduction to the Calculus of Variations

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 $\lim_{|x|\to\infty}\frac{f(x)}{|x|}=+\infty$ 

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$$\lim_{|x|\to\infty}\frac{f(x)}{|x|}=+\infty$$

then  $f^* \in C^1(\mathbb{R}^N)$ .

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$$\lim_{|x|\to\infty}\frac{f(x)}{|x|}=+\infty$$

then  $f^{*}\in C^{1}\left(\mathbb{R}^{N}
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$$f(x) + f^*(x^*) = \langle x^*, x \rangle$$

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then

$$x^{*} = \nabla f(x)$$
 and  $x = \nabla f^{*}(x^{*})$ .

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Let us try to calculate the Legendre transform of

$$f(x) = \frac{1}{p} |x|^p \qquad 1$$

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Examples

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$$f(x) = rac{1}{p} \left| x \right|^p \qquad 1$$

If y achieves the supremum (i.e. a maxima) for the following function

$$g(x) := \langle x^*, x \rangle - f(x),$$

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$$0 = \nabla g(y) = x^* - \nabla f(y) = x^* - |y|^{p-2} y.$$

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Now, by elementary manipulations

$$x^* = |y|^{p-2} y \Leftrightarrow y = |x^*|^{p'-2} x^*,$$

where p' is the Hölder conjugate of p, i.e

$$\frac{1}{p} + \frac{1}{p'} = 1.$$

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Now, by elementary manipulations

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where p' is the Hölder conjugate of p, i.e

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So plugging it in the definition, we deduce

$$f^{*}(x^{*}) = \frac{1}{p'} |x^{*}|^{p'}$$

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are called the **Hamilton's equations** and sometimes also called the **canonical form** of the Euler-Lagrange equation of the Lagrangian formulation.

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Hamilton's equation

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Examples

 $\in C^2$ 

The Euler-Lagrange equations for the functional

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are called the **Hamilton's equations** and sometimes also called the **canonical form** of the Euler-Lagrange equation of the Lagrangian formulation.

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$$\begin{cases} \dot{u}(t) = H_{v}(t, u(t), v(t)), \\ \dot{v}(t) = -H_{u}(t, u(t), v(t)). \end{cases}$$

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Examples

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These are 2N first order ODEs.

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Examples

 $\in C^2$
The Euler-Lagrange equations for the functional

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These are 2*N* first order ODEs.

Now we are going to show that in some cases these equations are equivalent to the EL equations for  $C^2$  stationary points.

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Lemma (Regularity of the Hamiltonian)

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(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite , for every  $(t, u, \xi) \in [a, b] \ltimes \mathbb{R}^{N}$ 

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$$[b] \stackrel{\text{Legendre}}{\to} \mathbb{R}^{n's} \stackrel{\text{ansform}}{\to} \mathbb{R}^{N},$$

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Examples

(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite, for every  $(t, u, \xi) \in [a, t]$ 

(coercivity)  $f(t, u, \xi) \geq \omega$ 

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] Ham  $\mathbb{R}^{N}$  is equal  $\mathbb{R}^{N}$ ,

(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite, for every  $(t, u, \xi) \in [a, b]$ 

(coercivity)  $f(t, u, \xi) \ge \omega(|\xi|) + g(t, u)$ , for every  $(t, u, \xi)$ where  $\omega$  is nonnegative.

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$$(b) \in [a, b] imes \mathbb{R}^N imes \mathbb{R}^N$$

(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite, for every  $(t, u, \xi) \in [a, t]$ 

(coercivity)  $f(t, u, \xi) \ge \omega(|\xi|) + g(t, u)$ , for every  $(t, u, \xi) \in [a, b] \times \mathbb{R}^{N} \times \mathbb{R}^{N}$ 

where  $\omega$  is nonnegative, continuous

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]  $\mathbb{R}_{n}^{\text{Legendre}}$   $\mathbb{R}_{n}^{\text{Legendre}}$ 

(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite , for every  $(t, u, \xi) \in [a, b] \ltimes \mathbb{R}^{N}$ 

(coercivity)  $f(t, u, \xi) \ge \omega(|\xi|) + g(t, u)$ , for every  $(t, u, \xi) \in [a, b] \xrightarrow{\text{Second Witter}}_{\text{Examples}} \mathbb{R}$ where  $\omega$  is nonnegative, continuous and increasing

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where  $\omega$  is nonnegative, continuous and increasing with  $\lim \omega(t)/t = \infty$ 

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(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite, for every  $(t, u, \xi) \in [a, t]$ 

I Second V Nation TO N (coercivity)  $f(t, u, \xi) \ge \omega(|\xi|) + g(t, u)$ , for every  $(t, u, \xi) \in [a]$ 

where  $\omega$  is nonnegative, continuous and increasing with lim  $\omega(t)/t = \infty$  and  $g: [a, b] \times \mathbb{R}^N \to \mathbb{R}$  is continuous.

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] X d $\mathbb{K}$ fields X  $\mathbb{K}$ 

(convexity)  $f_{\xi\xi}(t, u, \xi)$  positive definite, for every  $(t, u, \xi) \in [a, \xi]$ 

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] Here  $N$  and  $N$  and  $N$  and  $N$  and  $N$  and  $b$  and  $N$  and  $N$ 

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> $H_t(t, u, v) = -f_t(t, u, H_v(t, u, v))$  $H_{\mu}(t, u, v) = -f_{\mu}(t, u, H_{\nu}(t, u, v)),$

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]  $\mathbb{R}^{Legendre}_{\mathsf{M}} \mathbb{R}^{\mathsf{N}}_{\mathsf{n}} \mathbb{R}^{\mathsf{n}}_{\mathsf{s}} \mathbb{R}^{\mathsf{N}}_{\mathsf{s}},$ 

$$\in [a, b] \stackrel{\scriptscriptstyle ext{Second VN}}{ imes \mathbb{R}^{ imes \mathbb{R}^{ imes \mathbb{N}}}} \mathbb{R}^{ imes}$$

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$$H(t, u, v) = \langle v, H_v(t, u, v) \rangle - f(t, u, H_v(t, u, v))$$

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$$b$$
]  $\mathbb{R}^{Legendre}_{M} \mathbb{R}^{n's}$  equation  $\mathbb{R}^{N}_{s}$ ,

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$$H(t, u, v) = \langle v, H_v(t, u, v) \rangle - f(t, u, H_v(t, u, v))$$

 $v = f_{\xi}(t, u, \xi)$  if and only if  $\xi = H_v(t, u, v)$ . and

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$$b$$
]  $\mathbb{R}^{Legendre}_{\mathsf{M}} \mathbb{R}^{\mathsf{N}}_{\mathsf{n}}$  is equal  $\mathbb{R}^{\mathsf{N}}_{\mathsf{s}}$ ,

$$[a, b] \stackrel{\text{Second V} N}{\times} \mathbb{R}^{N}$$

Note that the coercivity assumptions imply

$$\lim_{|\xi| \to \infty} \frac{f(t, u, \xi)}{|\xi|} = +\infty \qquad \text{for every } (t, u) \in [a, b] \times \mathbb{R}^N.$$

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Thus given any  $t \in [a, b]$  and  $u, v \in \mathbb{R}^N$ , the the supremum in the definition of H, i.e.

$$\sup_{\xi\in\mathbb{R}^{N}}\left\{\left\langle v,\xi\right\rangle -f\left(t,u,\xi\right)\right\}$$

is achieved at some  $\xi = \xi (t, u, v) \in \mathbb{R}^N$ .

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$$g(y) := \langle v, y \rangle - f(t, u, y)$$

achieves a maxima at  $y = \xi$ .

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### Hamilton's equations

### Proof of Regularity of the Hamiltonian Lemma

So far we have established that H(t, u, v) is finite everywhere and

$$v=f_{\xi}\left(t,u,\xi\right).$$

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So far we have established that H(t, u, v) is finite everywhere and

$$v=f_{\xi}(t,u,\xi)$$

One can actually establish the continuity of H as well already.

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So far we have established that H(t, u, v) is finite everywhere and

$$v=f_{\xi}(t,u,\xi)$$

One can actually establish the continuity of  ${\cal H}$  as well already. Let  $\xi$  be the maximizer

$$H(t, u, v) = \langle v, \xi \rangle - f(t, u, \xi)$$

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$$H(t, u, v) = \langle v, \xi \rangle - f(t, u, \xi)$$

By definition of *H*, for some other point  $(\bar{t}, \bar{u}, \bar{v})$ , we have

 $H(\overline{t},\overline{u},\overline{v}) \geq \langle \overline{v},\xi \rangle - f(\overline{t},\overline{u},\xi).$ 

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 $H(\overline{t},\overline{u},\overline{v}) \geq \langle \overline{v},\xi \rangle - f(\overline{t},\overline{u},\xi).$ 

Thus, we obtain

$$H(t, u, v) - H(\bar{t}, \bar{u}, \bar{v}) \leq \langle v - \bar{v}, \xi \rangle + \left[f(\bar{t}, \bar{u}, \xi) - f(t, u, \xi)\right].$$

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One can actually establish the continuity of H as well already. Let  $\xi$  be the maximizer

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Thus, we obtain

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Now continuity of *H* follows from the continuity of  $(t, u) \mapsto f(t, u, \xi)$  for every  $\xi$ .

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Now we want to invert the equation

$$v=f_{\xi}\left(t,u,\xi\right)$$

and express  $\xi$  as a function of t, u, v.

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Now we want to invert the equation

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Now we want to invert the equation

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and express  $\xi$  as a function of t, u, v. But since  $f \in C^2$  and  $f_{\xi\xi}$  is positive definite and hence invertible,

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$$H(t, u, v) = \langle v, \xi(t, u, v) \rangle - f(t, u, \xi(t, u, v))$$

immediately implies H is  $C^1$ .

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immediately implies H is  $C^1$ . Furthermore, we deduce

$$\begin{split} H_t &= \langle \mathbf{v} - f_{\xi}, \xi_t \rangle - f_t = -f_t, \\ H_u &= \langle \mathbf{v} - f_{\xi}, \xi_u \rangle - f_u = -f_u, \\ H_v &= \xi + \langle \mathbf{v} - f_{\xi}, \xi_v \rangle = \xi. \end{split}$$

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The last equation also proves  $\xi = H_v$  if and only if  $v = f_{\xi}$ .

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## **Proof of Regularity of the Hamiltonian Lemma** But since *f* is $C^2$ and $\xi$ is $C^1$ ,

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## **Proof of Regularity of the Hamiltonian Lemma** But since *f* is $C^2$ and $\xi$ is $C^1$ , we deduce that the maps

 $(t, u, v) \mapsto f_t(t, u, \xi(t, u, v))$  and  $(t, u, v) \mapsto f_u(t, u, \xi(t, u, v))$ 

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$(t, u, v) \mapsto f_t(t, u, \xi(t, u, v))$  and  $(t, u, v) \mapsto f_u(t, u, \xi(t, u, v))$ 

are both  $C^1$  as well.

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 $(t, u, v) \mapsto f_t(t, u, \xi(t, u, v))$  and  $(t, u, v) \mapsto f_u(t, u, \xi(t, u, v))$ 

are both  $C^1$  as well. Thus the equations ( which we deduced on last slide )

$$\nabla H = \begin{pmatrix} H_t \\ H_u \\ H_v \end{pmatrix} = \begin{pmatrix} -f_t \\ -f_u \\ \xi \end{pmatrix}$$

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 $(t, u, v) \mapsto f_t(t, u, \xi(t, u, v))$  and  $(t, u, v) \mapsto f_u(t, u, \xi(t, u, v))$ 

are both  ${\cal C}^1$  as well. Thus the equations ( which we deduced on last slide )

$$\nabla H = \begin{pmatrix} H_t \\ H_u \\ H_v \end{pmatrix} = \begin{pmatrix} -f_t \\ -f_u \\ \xi \end{pmatrix}$$

implies that H is  $C^2$ .

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 $(t, u, v) \mapsto f_t(t, u, \xi(t, u, v))$  and  $(t, u, v) \mapsto f_u(t, u, \xi(t, u, v))$ 

are both  $C^1$  as well. Thus the equations ( which we deduced on last slide )

$$\nabla H = \begin{pmatrix} H_t \\ H_u \\ H_v \end{pmatrix} = \begin{pmatrix} -f_t \\ -f_u \\ \xi \end{pmatrix}$$

implies that H is  $C^2$ .

Now we are ready to state and prove our main theorem regarding the Hamiltonian formulation.

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## **Theorem (Hamiltonian and Lagrangian formulation)** Let f satisfy the hypotheses of the last lemma

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Let f satisfy the hypotheses of the last lemma and let H be its Hamiltonian.

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Let f satisfy the hypotheses of the last lemma and let H be its Hamiltonian. Let  $u, v \in C^2([a, b]; \mathbb{R}^N)$  satisfy,

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Let f satisfy the hypotheses of the last lemma and let H be its Hamiltonian. Let  $u, v \in C^2([a, b]; \mathbb{R}^N)$  satisfy,

$$(\mathbf{H}) \qquad \begin{cases} \dot{u}\left(t\right) = H_{v}\left(t, u\left(t\right), v\left(t\right)\right), \\ \dot{v}\left(t\right) = -H_{u}\left(t, u\left(t\right), v\left(t\right)\right), \end{cases} \quad \text{for every } t \in [a, b]. \end{cases}$$

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Then u verifies

$$(\mathsf{EL}) \quad \frac{d}{dt} \left[ f_{\xi} \left( t, u\left( t \right), \dot{u}\left( t \right) \right) \right] = f_{u} \left( t, u\left( t \right), \dot{u}\left( t \right) \right), \quad \text{ for every } t \in \left( a, b \right).$$

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Conversely, if  $u \in C^2([a, b]; \mathbb{R}^N)$  satisfies (EL)

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$$(\mathsf{EL}) \quad \frac{d}{dt} \left[ f_{\xi} \left( t, u(t), \dot{u}(t) \right) \right] = f_{u} \left( t, u(t), \dot{u}(t) \right), \quad \text{for every } t \in (a, b).$$

Conversely, if  $u \in C^2([a, b]; \mathbb{R}^N)$  satisfies (EL) then (u, v) are  $C^2$  solutions of (H)

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Conversely, if  $u \in C^2([a, b]; \mathbb{R}^N)$  satisfies (**EL**) then (u, v) are  $C^2$  solutions of (**H**) where

 $v\left(t
ight)=\mathit{f}_{\xi}\left(t,u\left(t
ight),\dot{u}\left(t
ight)
ight), \hspace{1em} \textit{for every }t\in\left[a,b
ight].$ 

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# Proof of the Hamiltonian and Lagrangian formulation theorem.

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# **Proof of the Hamiltonian and Lagrangian formulation** theorem.

Now that we have done all the hard work in proving the lemma, the proof is easy.

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# **Proof of the Hamiltonian and Lagrangian formulation** theorem.

Now that we have done all the hard work in proving the lemma, the proof is easy.

$$\dot{u} = H_v$$
 implies  $v(t) = f_{\xi}(t, u(t), \dot{u}(t))$ .

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$$\dot{u} = H_v$$
 implies  $v(t) = f_{\xi}(t, u(t), \dot{u}(t))$ .

But then,

$$\frac{d}{dt}f_{\xi}=\dot{v}=-H_{u}=-\left\langle v-f_{\xi},\xi_{u}\right\rangle +f_{u}=f_{u},$$

which is the (EL) equations.

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which is the (**EL**) equations. Conversely, if  $u \in C^2([a, b]; \mathbb{R}^N)$  satisfies (**EL**) then

 $v(t) = f_{\xi}(t, u(t), \dot{u}(t))$  implies  $\dot{u} = H_v$ .

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$$v(t) = f_{\xi}(t, u(t), \dot{u}(t)) \quad \text{ implies } \dot{u} = H_{v}.$$

Also,

$$\dot{\mathbf{v}} = rac{d}{dt} f_{\xi} = f_u = \langle \mathbf{v} - f_{\xi}, \xi_u \rangle - H_u = -H_u,$$

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But then,

$$\frac{d}{dt}f_{\xi}=\dot{v}=-H_{u}=-\langle v-f_{\xi},\xi_{u}\rangle+f_{u}=f_{u},$$

which is the (**EL**) equations. Conversely, if  $u \in C^2([a, b]; \mathbb{R}^N)$  satisfies (**EL**) then

$$v\left(t
ight)=\mathit{f}_{\xi}\left(t,u\left(t
ight),\dot{u}\left(t
ight)
ight) \hspace{0.5cm} ext{implies}\hspace{0.5cm}\dot{u}=\mathit{H}_{v}.$$

Also,

$$\dot{\mathbf{v}} = rac{d}{dt} f_{\xi} = f_u = \langle \mathbf{v} - f_{\xi}, \xi_u 
angle - H_u = -H_u,$$

verifying  $(\mathbf{H})$ .

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We begin with a few definitions.

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### **First integrals**

We begin with a few definitions.

**Definition (Integral Curves)** An *integral curve* of the vector field Introduction to the Calculus of Variations

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### **First integrals**

We begin with a few definitions.

## **Definition (Integral Curves)**

An *integral curve* of the vector field is a curve which is tangent to the vector field at each point.

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## **Definition (Integral Curves)**

An *integral curve* of the vector field is a curve which is tangent to the vector field at each point. Mathematically, given a vector field X on  $\mathbb{R}^N$ ,

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# **Definition (Integral Curves)**

An *integral curve* of the vector field is a curve which is tangent to the vector field at each point. Mathematically, given a vector field X on  $\mathbb{R}^N$ , the map  $\phi : [a, b] \to \mathbb{R}^N$  is an integral curve of the vector field X

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# **Definition (Integral Curves)**

An *integral curve* of the vector field is a curve which is tangent to the vector field at each point. Mathematically, given a vector field X on  $\mathbb{R}^N$ , the map  $\phi : [a, b] \to \mathbb{R}^N$  is an integral curve of the vector field X if it satisfies

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$$\dot{\phi}\left(t
ight)=X\left(\phi\left(t
ight)
ight)$$
 for each  $t\in\left[a,b
ight].$  (1)

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## **Definition (Integral Curves)**

An *integral curve* of the vector field is a curve which is tangent to the vector field at each point. Mathematically, given a vector field X on  $\mathbb{R}^N$ , the map  $\phi : [a, b] \to \mathbb{R}^N$  is an integral curve of the vector field X if it satisfies

$$\dot{\phi}(t) = X(\phi(t))$$
 for each  $t \in [a, b]$ . (1)

Clearly, (1) is a system of ODEs.

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Clearly, (1) is a system of ODEs.  $\phi$  is also called an **integral curve** for the system of ODEs in this case as well.

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## **Definition (First Integral)**

A first integral of a system of differential equations

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Clearly, (1) is a system of ODEs.  $\phi$  is also called an **integral curve** for the system of ODEs in this case as well.

## **Definition (First Integral)**

A *first integral* of a system of differential equations is a function which has a **constant value along each integral curve** of the system.

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A function  $\Phi \in C^2(\mathbb{R}^N \times \mathbb{R}^N)$ ,  $\Phi = \Phi(u, v)$ , is a first integral of the Hamilton's equations with Hamiltonian  $H = H(t, u, v) \in C^2([a, b] \times \mathbb{R}^N \times \mathbb{R}^N)$ 

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$$\{\Phi, H\} := \langle \Phi_u, H_v \rangle - \langle \Phi_v, H_u \rangle := \sum_{i=1}^N \frac{\partial \Phi}{\partial u^i} \frac{\partial H}{\partial v^i} - \frac{\partial \Phi}{\partial v^i} \frac{\partial H}{\partial u^i}$$

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A function  $\Phi \in C^2(\mathbb{R}^N \times \mathbb{R}^N)$ ,  $\Phi = \Phi(u, v)$ , is a first integral of the Hamilton's equations with Hamiltonian  $H = H(t, u, v) \in C^2([a, b] \times \mathbb{R}^N \times \mathbb{R}^N)$  if and only if the **Poisson Bracket** 

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vanishes identically.

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A function  $\Phi \in C^2(\mathbb{R}^N \times \mathbb{R}^N)$ ,  $\Phi = \Phi(u, v)$ , is a first integral of the Hamilton's equations with Hamiltonian  $H = H(t, u, v) \in C^2([a, b] \times \mathbb{R}^N \times \mathbb{R}^N)$  if and only if the **Poisson Bracket** 

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vanishes identically.

Proof.

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vanishes identically.

# Proof.

Along each integral curve (u(t), v(t)) of the Hamilton's equations,

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A function  $\Phi \in C^2(\mathbb{R}^N \times \mathbb{R}^N)$ ,  $\Phi = \Phi(u, v)$ , is a first integral of the Hamilton's equations with Hamiltonian  $H = H(t, u, v) \in C^2([a, b] \times \mathbb{R}^N \times \mathbb{R}^N)$  if and only if the **Poisson Bracket** 

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vanishes identically.

# Proof.

Along each integral curve (u(t), v(t)) of the Hamilton's equations, we have

$$\dot{\Phi}(t) = rac{d}{dt} \Phi = \langle \Phi_u, \dot{u} 
angle + \langle \Phi_v, \dot{v} 
angle = \{ \Phi, H \} \, .$$

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The Poisson bracket is an example of a commutator bracket.

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The Poisson bracket is an example of a **commutator bracket**. It is intimately related to another extremely useful bracket operation in mathematics,

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In physics, this is usually stated as the fact that the Hamiltonian ( i.e. **the total energy** ) of a mechanical system is a **conserved quantity**.

**This however, is not a coincidence!** This is just a special instance of a profound general fact known as Noether's theorem.

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# **Thank you** *Questions?*