

Introduction to the Calculus of Variations: Lecture 20

Swarnendu Sil

Department of Mathematics
Indian Institute of Science

Spring Semester 2021

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasiconvex.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasiconvex.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasilinear.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasilinear.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$ and any $\phi \in W_0^{1, \infty}(D; \mathbb{R}^2)$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasilinear.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$ and any $\phi \in W_0^{1, \infty}(D; \mathbb{R}^2)$, we have,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasiconvex.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$ and any $\phi \in W_0^{1, \infty}(D; \mathbb{R}^2)$, we have,

$$\det(\xi + \nabla \phi)$$

$$= \det \begin{pmatrix} \xi_{11} + \frac{\partial \phi^1}{\partial x_1} & \xi_{12} + \frac{\partial \phi^1}{\partial x_2} \\ \xi_{21} + \frac{\partial \phi^2}{\partial x_1} & \xi_{22} + \frac{\partial \phi^2}{\partial x_2} \end{pmatrix}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations**the determinant**

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasiconvex.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$ and any $\phi \in W_0^{1, \infty}(D; \mathbb{R}^2)$, we have,

$$\det(\xi + \nabla \phi)$$

$$= \det \begin{pmatrix} \xi_{11} + \frac{\partial \phi^1}{\partial x_1} & \xi_{12} + \frac{\partial \phi^1}{\partial x_2} \\ \xi_{21} + \frac{\partial \phi^2}{\partial x_1} & \xi_{22} + \frac{\partial \phi^2}{\partial x_2} \end{pmatrix}$$

$$= (\xi_{11}\xi_{22} - \xi_{12}\xi_{21}) + \left(\xi_{11} \frac{\partial \phi^2}{\partial x_2} + \xi_{22} \frac{\partial \phi^1}{\partial x_1} - \xi_{12} \frac{\partial \phi^2}{\partial x_1} - \xi_{21} \frac{\partial \phi^1}{\partial x_2} \right)$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations**the determinant**

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proposition

Let $n = N = 2$. Let $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ be defined as

$$f(\xi) = \det \xi.$$

Then f is quasilinear.

Proof. For any $\xi \in \mathbb{R}^{2 \times 2}$, for any bounded open set $D \subset \mathbb{R}^2$ and any $\phi \in W_0^{1, \infty}(D; \mathbb{R}^2)$, we have,

$$\det(\xi + \nabla \phi)$$

$$= \det \begin{pmatrix} \xi_{11} + \frac{\partial \phi^1}{\partial x_1} & \xi_{12} + \frac{\partial \phi^1}{\partial x_2} \\ \xi_{21} + \frac{\partial \phi^2}{\partial x_1} & \xi_{22} + \frac{\partial \phi^2}{\partial x_2} \end{pmatrix}$$

$$= (\xi_{11}\xi_{22} - \xi_{12}\xi_{21}) + \left(\xi_{11} \frac{\partial \phi^2}{\partial x_2} + \xi_{22} \frac{\partial \phi^1}{\partial x_1} - \xi_{12} \frac{\partial \phi^2}{\partial x_1} - \xi_{21} \frac{\partial \phi^1}{\partial x_2} \right)$$

$$= \det \xi + \left(\xi_{11} \frac{\partial \phi^2}{\partial x_2} + \xi_{22} \frac{\partial \phi^1}{\partial x_1} - \xi_{12} \frac{\partial \phi^2}{\partial x_1} - \xi_{21} \frac{\partial \phi^1}{\partial x_2} \right).$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Note that since ϕ has zero trace on ∂D ,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2}(y) \, dy = 0.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations**the determinant**

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2} (y) \, dy = 0.$$

Similarly,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2} (y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1} (y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1} (y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2} (y) \, dy = 0.$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2}(y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1}(y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1}(y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2}(y) \, dy = 0.$$

So, we deduce from the earlier computation,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2} (y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1} (y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1} (y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2} (y) \, dy = 0.$$

So, we deduce from the earlier computation,

$$\int_D \det(\xi + \nabla \phi(y)) \, dy = \int_D \det \xi \, dy = |D| \det \xi.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations**the determinant**

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2} (y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1} (y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1} (y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2} (y) \, dy = 0.$$

So, we deduce from the earlier computation,

$$\int_D \det(\xi + \nabla \phi(y)) \, dy = \int_D \det \xi \, dy = |D| \det \xi.$$

This completes the proof. □

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2} (y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1} (y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1} (y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2} (y) \, dy = 0.$$

So, we deduce from the earlier computation,

$$\int_D \det(\xi + \nabla \phi(y)) \, dy = \int_D \det \xi \, dy = |D| \det \xi.$$

This completes the proof. □

Thus the determinant is both quasiaffine and rank one affine,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2}(y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1}(y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1}(y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2}(y) \, dy = 0.$$

So, we deduce from the earlier computation,

$$\int_D \det(\xi + \nabla \phi(y)) \, dy = \int_D \det \xi \, dy = |D| \det \xi.$$

This completes the proof. □

Thus the determinant is both quasiaffine and rank one affine, but neither affine nor convex.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Note that since ϕ has zero trace on ∂D , integrating by parts, we have

$$\int_D \xi_{11} \frac{\partial \phi^2}{\partial x_2}(y) \, dy = 0.$$

Similarly,

$$\int_D \xi_{22} \frac{\partial \phi^1}{\partial x_1}(y) \, dy, \int_D \xi_{12} \frac{\partial \phi^2}{\partial x_1}(y) \, dy, \int_D \xi_{21} \frac{\partial \phi^1}{\partial x_2}(y) \, dy = 0.$$

So, we deduce from the earlier computation,

$$\int_D \det(\xi + \nabla \phi(y)) \, dy = \int_D \det \xi \, dy = |D| \det \xi.$$

This completes the proof. □

Thus the determinant is both quasiaffine and rank one affine, but neither affine nor convex. We now introduce another notion of convexity in the vectorial calculus of variations.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Definition (Polyconvexity for $n = N = 2$)

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex**

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$f(\xi) = F(\xi, \det \xi) \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$f(\xi) = F(\xi, \det \xi) \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}.$$

Remark

This is not the general definition of polyconvexity.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$f(\xi) = F(\xi, \det \xi) \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}.$$

Remark

This is not the general definition of polyconvexity. This is what the general definition reduces to in the case $n = N = 2$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$f(\xi) = F(\xi, \det \xi) \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}.$$

Remark

This is not the general definition of polyconvexity. This is what the general definition reduces to in the case $n = N = 2$.

We have already proved the weak continuity of determinants.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Definition (Polyconvexity for $n = N = 2$)

A function $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}$ is called **polyconvex** if there exists a convex function $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$f(\xi) = F(\xi, \det \xi) \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}.$$

Remark

This is not the general definition of polyconvexity. This is what the general definition reduces to in the case $n = N = 2$.

We have already proved the weak continuity of determinants. Using that result and the Mazur lemma, we can prove the weak lower semicontinuity of functionals with polyconvex integrands.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex*

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex* and *continuous*.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let

$F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex* and *continuous*. Let

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (wlsc for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex* and *continuous*. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex* and *continuous*. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be *convex* and *continuous*. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Then, $\liminf_{s \rightarrow \infty} I[u_s] \geq I[u]$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let
 $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be **convex** and **continuous**. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Then, $\liminf_{s \rightarrow \infty} I[u_s] \geq I[u]$.

The integrand need **not be convex** as a function of the gradient variable.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be **convex** and **continuous**. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Then, $\liminf_{s \rightarrow \infty} I[u_s] \geq I[u]$.

The integrand need **not be convex** as a function of the gradient variable. Also, if $u_s \rightharpoonup u$ in $W^{1,p}$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be **convex** and **continuous**. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Then, $\liminf_{s \rightarrow \infty} I[u_s] \geq I[u]$.

The integrand need **not be convex** as a function of the gradient variable. Also, if $u_s \rightharpoonup u$ in $W^{1,p}$ for some $2 < p < \infty$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (wlscl for polyconvex integrands)

Let $\Omega \subset \mathbb{R}^2$ be open, bounded and smooth and let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$ be **convex** and **continuous**. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Let

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Then, $\liminf_{s \rightarrow \infty} I[u_s] \geq I[u]$.

The integrand need **not be convex** as a function of the gradient variable. Also, if $u_s \rightharpoonup u$ in $W^{1,p}$ for some $2 < p < \infty$, both the convergences in the hypothesis above are satisfied and consequently the theorem holds.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous, convex*

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*, *convex* and satisfies,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*, *convex* and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*, *convex* and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*, *convex* and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$, some exponent $q > 1$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be *continuous*, *convex* and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$, some exponent $q > 1$. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be **continuous**, **convex** and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$, some exponent $q > 1$. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

If $I[u_0] < \infty$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be **continuous**, **convex** and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$, some exponent $q > 1$. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

If $I[u_0] < \infty$, then the following problem

$$\inf \left\{ I[u] : u \in u_0 + W_0^{1,p}(\Omega; \mathbb{R}^2) \right\} = m$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Theorem (existence for polyconvex integrands)

Let $2 \leq p < \infty$ and let $\Omega \subset \mathbb{R}^2$ be open bounded and smooth. Let $u_0 \in W^{1,p}(\Omega; \mathbb{R}^2)$ be given. Let $F : \mathbb{R}^{2 \times 2} \times \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$, $F = F(\xi, \theta)$ be **continuous**, **convex** and satisfies,

$$f(\xi, \theta) \geq \begin{cases} c_1 |\xi|^2 + c_2 |\theta|^q & \text{if } p = 2, \\ c_1 |\xi|^p & \text{if } p > 2, \end{cases} \quad \text{for all } \xi \in \mathbb{R}^{2 \times 2}, \theta \in \mathbb{R},$$

for some $c_1, c_2 > 0$, some exponent $q > 1$. Let

$$I[u] := \int_{\Omega} F(\nabla u(x), \det \nabla u(x)) \, dx.$$

If $I[u_0] < \infty$, then the following problem

$$\inf \left\{ I[u] : u \in u_0 + W_0^{1,p}(\Omega; \mathbb{R}^2) \right\} = m$$

admits a minimizer.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 dx \leq \frac{1}{c_1} (m + 1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q dx \leq \frac{1}{c_2} (m + 1)$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 dx \leq \frac{1}{c_1} (m+1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q dx \leq \frac{1}{c_2} (m+1)$$

for all $s \geq 1$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 dx \leq \frac{1}{c_1} (m + 1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q dx \leq \frac{1}{c_2} (m + 1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 dx \leq \frac{1}{c_1} (m+1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q dx \leq \frac{1}{c_2} (m+1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that $\{u_s\}_{s \geq 1}$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 \, dx \leq \frac{1}{c_1} (m + 1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q \, dx \leq \frac{1}{c_2} (m + 1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that $\{u_s\}_{s \geq 1}$ is uniformly bounded in $W^{1,2}(\Omega; \mathbb{R}^2)$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 dx \leq \frac{1}{c_1} (m+1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q dx \leq \frac{1}{c_2} (m+1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that $\{u_s\}_{s \geq 1}$ is uniformly bounded in $W^{1,2}(\Omega; \mathbb{R}^2)$. Hence, up to the extraction of a subsequence, we have

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 \, dx \leq \frac{1}{c_1} (m + 1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q \, dx \leq \frac{1}{c_2} (m + 1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that $\{u_s\}_{s \geq 1}$ is uniformly bounded in $W^{1,2}(\Omega; \mathbb{R}^2)$. Hence, up to the extraction of a subsequence, we have

$$u_s \rightharpoonup u \quad \text{in } W^{1,2}(\Omega; \mathbb{R}^2),$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof. We only show the case $p = 2$. The other case is much easier. For any minimizing sequence $\{u_s\}_{s \geq 1}$, the coercivity inequality implies

$$\int_{\Omega} |\nabla u_s(x)|^2 \, dx \leq \frac{1}{c_1} (m + 1)$$

and

$$\int_{\Omega} |\det \nabla u_s(x)|^q \, dx \leq \frac{1}{c_2} (m + 1)$$

for all $s \geq 1$. By Poincaré inequality, the first estimate implies that $\{u_s\}_{s \geq 1}$ is uniformly bounded in $W^{1,2}(\Omega; \mathbb{R}^2)$. Hence, up to the extraction of a subsequence, we have

$$u_s \rightharpoonup u \quad \text{in } W^{1,2}(\Omega; \mathbb{R}^2),$$

for some $u \in u_0 + W_0^{1,2}(\Omega; \mathbb{R}^2)$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result, by uniqueness of limits,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result, by uniqueness of limits, we must have

$$v = \det \nabla u.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result, by uniqueness of limits, we must have

$$v = \det \nabla u.$$

Thus, we have

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result, by uniqueness of limits, we must have

$$v = \det \nabla u.$$

Thus, we have

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

The second inequality implies that $\{\det \nabla u_s\}_{s \geq 1}$ is uniformly bounded in $L^q(\Omega)$ and since $q > 1$, up to the extraction of a subsequence, we have

$$\det \nabla u_s \rightharpoonup v \quad \text{in } L^q(\Omega),$$

for some $v \in L^q(\Omega)$. But using the same argument as in the proof of weak continuity of the determinant result, by uniqueness of limits, we must have

$$v = \det \nabla u.$$

Thus, we have

$$\begin{cases} u_s \rightharpoonup u & \text{in } W^{1,2}(\Omega; \mathbb{R}^2), \\ \det \nabla u_s \rightharpoonup \det \nabla u & \text{in } L^1(\Omega). \end{cases}$$

Now we can use the wisc theorem to conclude. □

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Now we begin studying the question of regularity of minimizers.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Now we begin studying the question of regularity of minimizers.
We have established the existence of a minimizer in some Sobolev class,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Regularity questions in the Calculus of variations

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it.**

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Regularity questions in the Calculus of variations

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands:

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity:

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

The techniques used for both types are related,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

The techniques used for both types are related, but the latter is usually considerably more technically challenging.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

The techniques used for both types are related, but the latter is usually considerably more technically challenging. In this course, we would only discuss regularity results for the Euler-Lagrange equations.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

The techniques used for both types are related, but the latter is usually considerably more technically challenging. In this course, we would only discuss regularity results for the Euler-Lagrange equations. Since the Euler-Lagrange equations are often 'elliptic',

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Now we begin studying the question of regularity of minimizers. We have established the existence of a minimizer in some Sobolev class, typically $W^{1,p}$. Now we want to show that **they are in fact more regular when the problem allows it**. This is in general a quite difficult subject which is both important, interesting and intricate. The results can be broadly divided into two types, depending on the regularity of the integrand.

- ▶ Regular enough integrands: We establish regularity for the Euler-Lagrange equations.
- ▶ Integrands without the required regularity: Here we can no longer work with the Euler-Lagrange equation and instead prove regularity directly using minimality.

The techniques used for both types are related, but the latter is usually considerably more technically challenging. In this course, we would only discuss regularity results for the Euler-Lagrange equations. Since the Euler-Lagrange equations are often 'elliptic', these types of results are called **elliptic regularity** results.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u ,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$ reduces to $\ddot{u} \in L^2$.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$ reduces to $\ddot{u} \in L^2$. This, together with the fact that $u \in W^{1,2}$ immediately implies $u \in W^{2,2}$,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$ reduces to $\ddot{u} \in L^2$. This, together with the fact that $u \in W^{1,2}$ immediately implies $u \in W^{2,2}$, at least locally inside Ω .

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$ reduces to $\ddot{u} \in L^2$. This, together with the fact that $u \in W^{1,2}$ immediately implies $u \in W^{2,2}$, at least locally inside Ω . Can we say the same for any $n \geq 1$?

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

To appreciate the rather remarkable nature of the results we are going to prove, let us start with a simple question.

Let $\Omega \subset \mathbb{R}^n$ be open, bounded and smooth. Suppose we know $\Delta u \in L^2(\Omega)$ for some $u \in W^{1,2}(\Omega)$. Since the Laplacian is a polynomial of the second derivatives of u , can we say something about the second derivatives of u ?

First consider the case $n = 1$. Here the statement $\Delta u \in L^2$ reduces to $\ddot{u} \in L^2$. This, together with the fact that $u \in W^{1,2}$ immediately implies $u \in W^{2,2}$, at least locally inside Ω . Can we say the same for any $n \geq 1$?

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, all second derivatives of u does not even appear in the equation,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

We know only their sum to be L^2 to begin with.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

We know only their sum to be L^2 to begin with.

It is perfectly possible for the sum of two functions,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

We know only their sum to be L^2 to begin with.

It is perfectly possible for the sum of two functions, none of which are L^2 ,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

We know only their sum to be L^2 to begin with.

It is perfectly possible for the sum of two functions, none of which are L^2 , to be square integrable.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Things are far from clear when $n \geq 2$. For example, if $n = 2$,

$$\Delta u(x, y) = \frac{\partial^2 u}{\partial x^2}(x, y) + \frac{\partial^2 u}{\partial y^2}(x, y).$$

So first of all, **all second derivatives of u does not even appear in the equation**, only the pure ones do.

Secondly, it is not even clear if we can conclude that the pure second derivatives are in L^2 .

We know only their sum to be L^2 to begin with.

It is perfectly possible for the sum of two functions, none of which are L^2 , to be square integrable.

However, this somewhat miraculous conclusion is actually true in all dimensions.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

▶ **Linear/Perturbative theory**

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.
 - ▶ L^2 theory:

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory:

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D) u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D) u \in L^p \Rightarrow u \in W^{2,p}$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D) u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D) u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory:

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D)u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory: This implies results of the type

$$P(x, D)u \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D)u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory: This implies results of the type

$$P(x, D)u \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}$$

Here $P(x, D)$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D)u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory: This implies results of the type

$$P(x, D)u \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}$$

Here $P(x, D)$ is a second order variable coefficient linear operator

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D)u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory: This implies results of the type

$$P(x, D)u \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}$$

Here $P(x, D)$ is a second order variable coefficient linear operator with appropriately regular coefficients.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

Types of regularity results

Elliptic regularity results can be broadly classified into a few types depending on the techniques and the spaces involved.

- ▶ **Linear/Perturbative theory** Here we first establish regularity for a model constant coefficient operator and then tackle the variable coefficient operator case by perturbation techniques. Depending on the spaces involved they can be classified into three types.

- ▶ L^2 theory: This implies results of the type

$$P(x, D)u \in L^2 \Rightarrow u \in W^{2,2}$$

- ▶ L^p theory: This implies results of the type

$$P(x, D)u \in L^p \Rightarrow u \in W^{2,p}$$

- ▶ Schauder theory: This implies results of the type

$$P(x, D)u \in C^{0,\alpha} \Rightarrow u \in C^{2,\alpha}$$

Here $P(x, D)$ is a second order variable coefficient linear operator with appropriately regular coefficients. All of these has their local and up to the boundary versions.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

► Non Linear theory

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients**

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

**Regularity questions in the
Calculus of variations**

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:**

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$)

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$),

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:**

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems. Instead, we try to prove what is known as **partial regularity** results.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems. Instead, we try to prove what is known as **partial regularity** results. The prototype result is

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems. Instead, we try to prove what is known as **partial regularity** results. The prototype result is

$$P(x, D)u = 0 \text{ in } \Omega \Rightarrow u \in C_{loc}^{1,\alpha}(\Omega \setminus \Sigma)$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems. Instead, we try to prove what is known as **partial regularity** results. The prototype result is

$$P(x, D)u = 0 \text{ in } \Omega \Rightarrow u \in C_{loc}^{1,\alpha}(\Omega \setminus \Sigma)$$

where Σ is a 'lower dimensional set',

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

- ▶ **Non Linear theory** Here we first establish regularity for a model linear operator, but with **rough coefficients** so that Perturbative theory can not be applied. This can then be used to conclude regularity for nonlinear problems as well. These can be divided into two classes.
 - ▶ **Equations:** Typically, these results are called **De Giorgi-Nash-Moser** theory. The prototype result is

$$P(x, D)u = 0 \Rightarrow u \in C_{loc}^{1,\alpha}$$

These results are typically valid for equations ($N = 1$) and does not in general extend to systems ($N \geq 2$), except for systems with special structures.

- ▶ **General systems:** Everywhere regularity, is in general **not true** for nonlinear elliptic systems. Instead, we try to prove what is known as **partial regularity** results. The prototype result is

$$P(x, D)u = 0 \text{ in } \Omega \Rightarrow u \in C_{loc}^{1,\alpha}(\Omega \setminus \Sigma)$$

where Σ is a 'lower dimensional set', called the singular set.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition. Then $u \in W_{loc}^{2,2}(\Omega; \mathbb{R}^N)$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition. Then $u \in W_{loc}^{2,2}(\Omega; \mathbb{R}^N)$ and for any $\tilde{\Omega} \subset\subset \Omega$,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition. Then $u \in W_{loc}^{2,2}(\Omega; \mathbb{R}^N)$ and for any $\tilde{\Omega} \subset\subset \Omega$, we have the estimate

$$\|\nabla^2 u\|_{L^2(\tilde{\Omega})} \leq c \left(\|u\|_{L^2(\Omega)} + \|f\|_{L^2(\Omega)} + \|\nabla F\|_{L^2(\Omega)} \right)$$

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition. Then $u \in W_{loc}^{2,2}(\Omega; \mathbb{R}^N)$ and for any $\tilde{\Omega} \subset\subset \Omega$, we have the estimate

$$\|\nabla^2 u\|_{L^2(\tilde{\Omega})} \leq c \left(\|u\|_{L^2(\Omega)} + \|f\|_{L^2(\Omega)} + \|\nabla F\|_{L^2(\Omega)} \right)$$

where $c > 0$ is a constant depending only on

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

We can barely scratch the surface of elliptic regularity in this course. That would require a course for itself. We would only prove the so-called interior $W^{2,2}$ estimate.

Theorem (Interior L^2 estimate)

Let $u \in W^{1,2}(\Omega; \mathbb{R}^N)$ be a weak solution of the following

$$-\operatorname{div}(A(x) \nabla u) = f - \operatorname{div} F \quad \text{in } \Omega,$$

where $f \in L^2(\Omega; \mathbb{R}^N)$, $F \in W^{1,2}(\Omega; \mathbb{R}^{N \times n})$ and $A \in W^{1,\infty}(\Omega; \mathbb{R}^{N \times n} \times \mathbb{R}^{N \times n})$ satisfies the strong Legendre condition. Then $u \in W_{loc}^{2,2}(\Omega; \mathbb{R}^N)$ and for any $\tilde{\Omega} \subset\subset \Omega$, we have the estimate

$$\|\nabla^2 u\|_{L^2(\tilde{\Omega})} \leq c \left(\|u\|_{L^2(\Omega)} + \|f\|_{L^2(\Omega)} + \|\nabla F\|_{L^2(\Omega)} \right)$$

where $c > 0$ is a constant depending only on $\tilde{\Omega}$, Ω and the ellipticity and the bounds on A .

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Theorem (Caccioppoli inequality)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Theorem (Caccioppoli inequality)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega). \quad (1)$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Theorem (Caccioppoli inequality)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega). \quad (1)$$

Then for every $x_0 \in \Omega$, $0 < \rho < R < \text{dist}(x_0, \partial\Omega)$,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Theorem (Caccioppoli inequality)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega). \quad (1)$$

Then for every $x_0 \in \Omega$, $0 < \rho < R < \text{dist}(x_0, \partial\Omega)$, we have

$$\int_{B_{\rho}(x_0)} |\nabla u|^2 \, dx \leq \frac{c}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_{\rho}(x_0)} |u - \lambda|^2 \, dx, \quad \text{for all } \lambda \in \mathbb{R}, \quad (2)$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
Functions

The End

The main tool is an inequality called the **Caccioppoli inequality** or the **reverse Poincaré inequality**. We begin with the simplest case, the case of harmonic functions.

Theorem (Caccioppoli inequality)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega). \quad (1)$$

Then for every $x_0 \in \Omega$, $0 < \rho < R < \text{dist}(x_0, \partial\Omega)$, we have

$$\int_{B_{\rho}(x_0)} |\nabla u|^2 \, dx \leq \frac{c}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_{\rho}(x_0)} |u - \lambda|^2 \, dx, \quad \text{for all } \lambda \in \mathbb{R}, \quad (2)$$

for some universal constant $c > 0$.

The regularity is a consequence of the competition between reverse Poincaré and the usual Poincaré-Sobolev inequalities.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic Functions

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1),

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Thus, using Hölder inequality, we deduce

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Thus, using Hölder inequality, we deduce

$$\int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \leq \int_{B_R(x_0)} |\nabla u| |u - \lambda| 2\eta |\nabla \eta| \, dx$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Thus, using Hölder inequality, we deduce

$$\begin{aligned} \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u| |u - \lambda| 2\eta |\nabla \eta| \, dx \\ &\leq \left(\int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \right)^{\frac{1}{2}} \left(\int_{B_R(x_0)} 4 |u - \lambda|^2 |\nabla \eta|^2 \, dx \right)^{\frac{1}{2}} \end{aligned}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity $\frac{1}{2}$ Regularity for Harmonic
functions

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Thus, using Hölder inequality, we deduce

$$\begin{aligned} \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u| |u - \lambda| 2\eta |\nabla \eta| \, dx \\ &\leq \left(\int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \right)^{\frac{1}{2}} \left(\int_{B_R(x_0)} 4 |u - \lambda|^2 |\nabla \eta|^2 \, dx \right)^{\frac{1}{2}} \end{aligned}$$

This implies

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity $\frac{1}{2}$ Regularity for Harmonic
functions

The End

Proof. Let $\eta \in C_c^\infty(B_R(x_0))$ be such that

$$\eta \equiv 1 \quad \text{in } B_\rho(x_0), \quad 0 \leq \eta \leq 1 \quad \text{and} \quad |\nabla \eta| \leq \frac{c}{R - \rho}.$$

For any $\lambda \in \mathbb{R}$, set $\phi = (u - \lambda)\eta^2$. Plugging into (1), we get

$$\int_{\Omega} |\nabla u|^2 \eta^2 \, dx + \int_{\Omega} \langle \nabla u, (u - \lambda) 2\eta \nabla \eta \rangle \, dx = 0.$$

Thus, using Hölder inequality, we deduce

$$\begin{aligned} \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u| |u - \lambda| 2\eta |\nabla \eta| \, dx \\ &\leq \left(\int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \right)^{\frac{1}{2}} \left(\int_{B_R(x_0)} 4 |u - \lambda|^2 |\nabla \eta|^2 \, dx \right)^{\frac{1}{2}} \end{aligned}$$

This implies

$$\int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity $\frac{1}{2}$ Regularity for Harmonic
functions

The End

Hence, we obtain

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Hence, we obtain

$$\int_{B_\rho(x_0)} |\nabla u|^2 \, dx \leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \end{aligned}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Hence, we obtain

$$\begin{aligned}
 \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\
 &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\
 &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx.
 \end{aligned}$$

This completes the proof. □

However remarkable it may sound,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to proof that harmonic functions are smooth!

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**. This is a baffling notion at first sight.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**. This is a baffling notion at first sight. To prove the smoothness of u ,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**. This is a baffling notion at first sight. To prove the smoothness of u , first we are going to prove some estimates

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**. This is a baffling notion at first sight. To prove the smoothness of u , first we are going to prove some estimates assuming u is smooth!!

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Hence, we obtain

$$\begin{aligned} \int_{B_\rho(x_0)} |\nabla u|^2 \, dx &\leq \int_{B_R(x_0)} |\nabla u|^2 \eta^2 \, dx \\ &\leq 4 \int_{B_R(x_0)} |u - \lambda|^2 |\nabla \eta|^2 \, dx \\ &\leq \frac{4c^2}{(R - \rho)^2} \int_{B_R(x_0) \setminus B_\rho(x_0)} |u - \lambda|^2 \, dx. \end{aligned}$$

This completes the proof. □

However remarkable it may sound, this is enough to prove that harmonic functions are smooth! To do this, we would use what are called **a priori estimates**. This is a baffling notion at first sight. To prove the smoothness of u , first we are going to prove some estimates assuming u is smooth!! In case you are wondering, we do know how to spell circularity.

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality, for any $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$, we have,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality, for any $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$, we have, for any $1 \leq i \leq n$,

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality, for any $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$, we have, for any $1 \leq i \leq n$,

$$\int_{B_{R/2}(x_0)} \left| \nabla \left(\frac{\partial u}{\partial x_i} \right) \right|^2 \, dx \leq \frac{c}{R^2} \int_{B_{2R/3}(x_0)} \left| \frac{\partial u}{\partial x_i} \right|^2 \, dx$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality, for any $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$, we have, for any $1 \leq i \leq n$,

$$\int_{B_{R/2}(x_0)} \left| \nabla \left(\frac{\partial u}{\partial x_i} \right) \right|^2 \, dx \leq \frac{c}{R^2} \int_{B_{2R/3}(x_0)} \left| \frac{\partial u}{\partial x_i} \right|^2 \, dx \leq \frac{c}{R^4} \int_{B_R(x_0)} |u|^2 \, dx.$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proposition (Apriori estimates for higher derivatives)

Let $u \in C^\infty(\Omega)$ be a **smooth** solution of $\Delta u = 0$. Then for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Since u is harmonic and smooth, so is $\frac{\partial u}{\partial x_i}$ for any $1 \leq i \leq n$. So applying the Caccioppoli inequality, for any $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$, we have, for any $1 \leq i \leq n$,

$$\int_{B_{R/2}(x_0)} \left| \nabla \left(\frac{\partial u}{\partial x_i} \right) \right|^2 \, dx \leq \frac{c}{R^2} \int_{B_{2R/3}(x_0)} \left| \frac{\partial u}{\partial x_i} \right|^2 \, dx \leq \frac{c}{R^4} \int_{B_R(x_0)} |u|^2 \, dx.$$

We can iterate for higher derivatives. □

Direct methods

Dirichlet Integral

Integrands depending only on the gradient

Integrands with x dependence

Integrands with x and u dependence

Euler-Lagrange Equations

Glimpses of the Vectorial Calculus of Variations

Necessity of convexity and the vectorial calculus of variations

the determinant

Polyconvexity

Regularity

Regularity questions in the Calculus of variations

L^2 regularity

Regularity for Harmonic functions

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega).$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega).$$

Then $u \in C_{loc}^{\infty}(\Omega)$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega).$$

Then $u \in C_{loc}^{\infty}(\Omega)$ and for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega).$$

Then $u \in C_{loc}^{\infty}(\Omega)$ and for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Theorem (Smoothness of harmonic functions)

Let $u \in W^{1,2}(\Omega)$ be a weak solution of $\Delta u = 0$, i.e.

$$\int_{\Omega} \langle \nabla u, \nabla \phi \rangle = 0 \quad \text{for every } \phi \in W_0^{1,2}(\Omega).$$

Then $u \in C_{loc}^{\infty}(\Omega)$ and for every $x_0 \in \Omega$, $0 < R < \text{dist}(x_0, \partial\Omega)$ and any $k \in \mathbb{N}$, we have

$$\int_{B_{R/2}(x_0)} |D^k u|^2 \, dx \leq c \int_{B_R(x_0)} |u|^2 \, dx$$

for some constant $c = c(k, R) > 0$.

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ .

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the apriori estimates

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the apriori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

$$u_\varepsilon \rightarrow u \quad \text{in } C^m(\overline{B_{R/2}(x_0)})$$

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularity**Regularity for Harmonic
functions**

The End

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

$$u_\varepsilon \rightarrow u \quad \text{in } C^m(\overline{B_{R/2}(x_0)})$$

for any $m \in \mathbb{N}$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

$$u_\varepsilon \rightarrow u \quad \text{in } C^m(\overline{B_{R/2}(x_0)})$$

for any $m \in \mathbb{N}$. Since x_0 and R are otherwise arbitrary,

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

$$u_\varepsilon \rightarrow u \quad \text{in } C^m(\overline{B_{R/2}(x_0)})$$

for any $m \in \mathbb{N}$. Since x_0 and R are otherwise arbitrary, this proves $u \in C_{loc}^\infty(\Omega)$.

Direct methods

Dirichlet Integral

Integrands depending only
on the gradientIntegrands with x
dependenceIntegrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of VariationsNecessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations L^2 regularityRegularity for Harmonic
functions

The End

Proof.

Fix $x_0 \in \Omega$ and $0 < R < \text{dist}(x_0, \partial\Omega)$. Let $u_\varepsilon := u * \rho_\varepsilon$, for some standard symmetric mollifying kernel ρ . Then using Fubini, we can show that u_ε is harmonic in a neighbourhood of $B_R(x_0) \subset \Omega$. Thus, any derivative of u_ε of any order satisfies the a priori estimates and thus $\{u_\varepsilon\}_{\varepsilon>0}$ is uniformly bounded in $W^{k,2}(B_{R/2}(x_0))$ for any $k \in \mathbb{N}$. By Rellich-Kondrachov compact embeddings, this implies that up to the extraction of a subsequence,

$$u_\varepsilon \rightarrow u \quad \text{in } C^m(\overline{B_{R/2}(x_0)})$$

for any $m \in \mathbb{N}$. Since x_0 and R are otherwise arbitrary, this proves $u \in C_{loc}^\infty(\Omega)$. The estimates now follows from the estimates for u_ε by passing to the limit. \square

Thank you
Questions?

Direct methods

Dirichlet Integral

Integrands depending only
on the gradient

Integrands with x
dependence

Integrands with x and u
dependence

Euler-Lagrange Equations

Glimpses of the Vectorial
Calculus of Variations

Necessity of convexity and
the vectorial calculus of
variations

the determinant

Polyconvexity

Regularity

Regularity questions in the
Calculus of variations

L^2 regularity

Regularity for Harmonic
functions

The End