

The Lovász Local Lemma & its Consequences

Part: 2

Usage & Applications

A presentation by -

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1. k -CNF:

Its similarity to the hypergraph coloring problem.
Theoretical Setup for the Algorithm

2. The Moser-Tardos Algorithm:

The Algorithm
Analysis and Proof of Correctness
Parallelism

3. Further Applications:

Packet Routing

Conjunctive Normal Form:

$$\phi = \mathbf{c}_1 \wedge \mathbf{c}_2 \wedge \cdots \wedge \mathbf{c}_m$$

Each \mathbf{c}_i is a disjunction of k many boolean literals.

To determine: **If ϕ is satisfiable**

Theorem:

If each X_i occurs in at most $\frac{2^k}{ek}$ many clauses, then ϕ is satisfiable.

Theoretical Setup

Let $\mathbf{X}_i : \Omega \rightarrow \mathbb{R}$, $i \in [n]$ independent

Let $\chi = \{X_1, X_2, \dots, X_n\}$

Denote the bad events as $\mathbf{E}_1, \mathbf{E}_2, \dots, \mathbf{E}_m$. Each \mathbf{E}_i can be completely determined by $\text{vbl}(\mathbf{E}_i) = \{\mathbf{X}_{i_1}, \mathbf{X}_{i_2}, \dots, \mathbf{X}_{i_j}\}$

Dependency Graph ?

Theoretical Setup

The Moser-Tardos Algorithm

The Moser-Tardos Algorithm

Algorithm: LLL_CONSTRUCT(χ , E_i 's)

for every $X \in \chi$ **do**

 Sample X

end for

while *there are violated events* **do**

 Pick a violated event E

for every $X \in \text{vb1}(E)$ **do**

 Sample X

end for

end while

return the final assignment of X_i 's

$$\mathbb{E}(\# \text{ of resamplings }) \leq \sum_{i=1}^n \frac{x(E_i)}{1 - x(E_i)}$$

Analysis of the Algorithm

1. Log of Execution **C**
2. Witness Tree $w_{\text{tree}}(t)$
3. Properties
4. Probability of *occurrence* of w_{tree}
5. Branching Process

Witness Tree Creation

Properties of $\text{wtree}(t)$

Given $\log C$ at time t , the witness tree $\text{wtree}(t)$ has the following properties:

(i) If $r < s$, A_r is added to $\text{wtree}(t)$ at time r and A_s added to $\text{wtree}(t)$ at time s , and A_r and A_s overlap, then

$$\text{depth of } A_r > \text{depth of } A_s$$

(ii) All the vertices at the same level in $\text{wtree}(t)$ are **independent**

(iii) All trees up to time t are **different**; $\text{wtree}(1) \neq \text{wtree}(2) \neq \dots \neq \text{wtree}(t)$.

Properties

Probability of occurrence of w_{tree}

Probability of occurrence of w_{tree}

$$\mathbb{P}(w_{\text{tree}} \text{ occurs in } C) = \prod_{E_i \in V(w_{\text{tree}})} \mathbb{P}(E_i)$$

$$R_{E_i} = \sum_{w_{\text{tree}} \in \mathcal{T}_{E_i}} 1_{\{w_{\text{tree}} \text{ occurs in } C\}}.$$

Thus,

$$\begin{aligned} \mathbb{E}(R_{E_i}) &= \sum_{w_{\text{tree}} \in \mathcal{T}_{E_i}} \mathbb{P}(w_{\text{tree}} \text{ occurs in } C) \\ &= \sum_{w_{\text{tree}} \in \mathcal{T}_{E_i}} \prod_{E_j \in V(w_{\text{tree}})} \mathbb{P}(E_j) \\ &\leq \sum_{w_{\text{tree}} \in \mathcal{T}_{E_i}} \prod_{E_j \in V(w_{\text{tree}})} x(E_j) \prod_{E_k \in N(E_j)} (1 - x(E_k)) \end{aligned}$$

Branching Process

Branching Process

Result:

$$\mathbb{P}(\text{wtree}_{GW} = \text{wtree}) = \frac{1 - x(E_i)}{x(E_i)} \prod_{E_j \in V(\text{wtree})} x(E_j) \prod_{E_k \in N(E_j)} (1 - x(E_k))$$

Branching Process

Instead of picking **one** violated event at a time, the algorithm greedily picks a **maximal independent set** of violated events in the dependency graph G , at every resampling step.

Benefit:

If the bound of LLL is weakened only a little, then

$$\mathbb{E}(\# \text{ of resamplings }) = O \left(\frac{1}{\epsilon} \log \left(\sum_{i=1}^n \frac{x(E_i)}{1 - x(E_i)} \right) \right)$$

P_1, P_2, \dots, P_r : directed paths in a network

Design a packet scheduling policy to **minimise** time

Notations:

1. c : (Congestion) is the maximum number of paths that share a directed edge
2. d : (Dilation) is the maximum path length that occurs in the path system.

Observation:

$$T \geq \max\{c, d\}$$

Result: (Leighton, Maggs & Richa)

In the above model, there is always a packet schedule that achieves $O(c + d)$ delivery time for each packet.